

a practical introduction to

# Gaussian Processes

for astronomy

***Dan Foreman-Mackey***

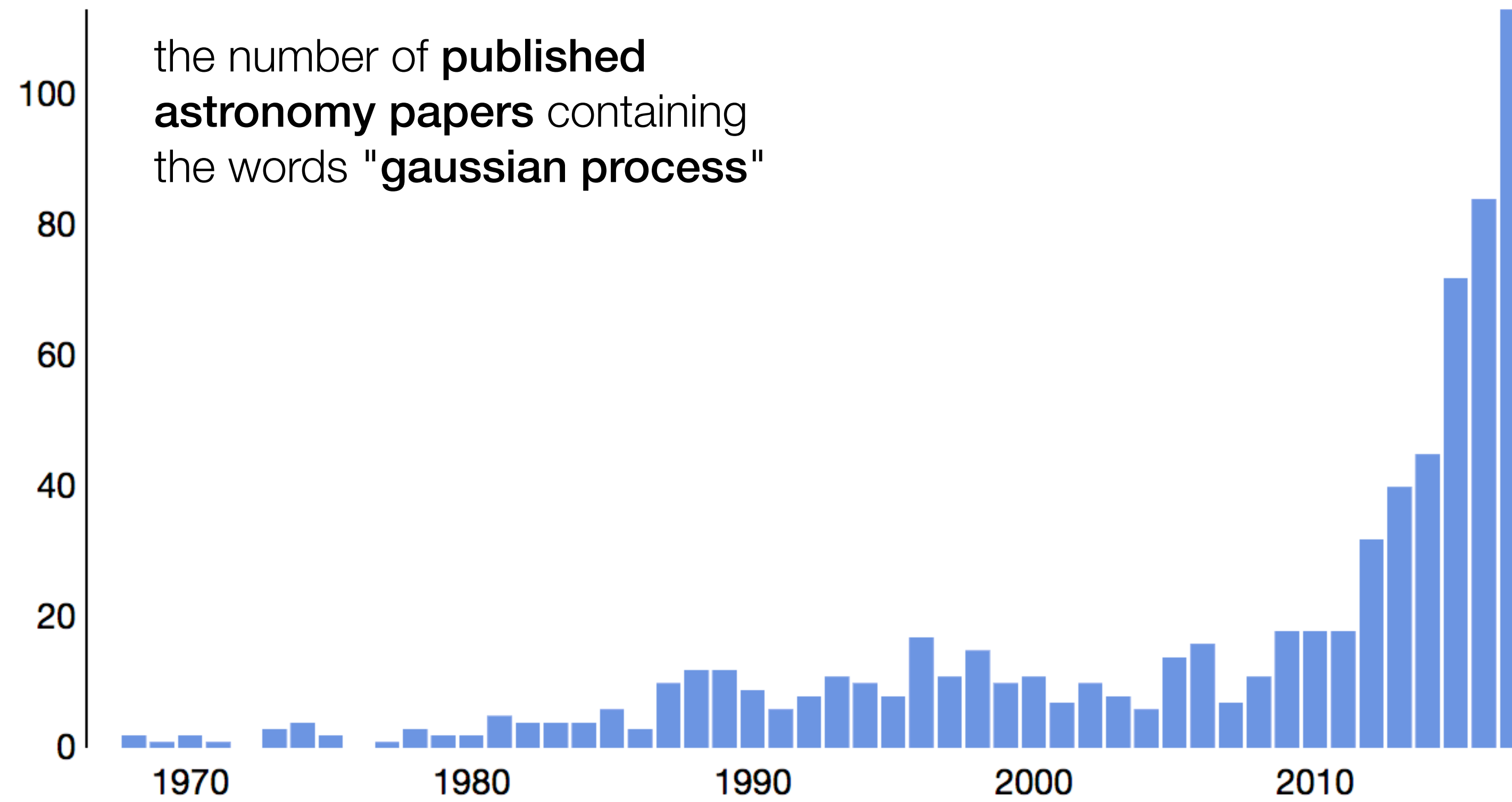
Flatiron Institute // [dfm.io](http://dfm.io) // [github.com/dfm](https://github.com/dfm) // [@exoplaneteer](https://twitter.com/exoplaneteer)

# Resources


- a** [gaussianprocess.org/gpml](https://gaussianprocess.org/gpml)
- b** [george.readthedocs.io](https://george.readthedocs.io)
- c** [dfm.io/gp.js](https://dfm.io/gp.js)
- d** [github.com/dfm/gp](https://github.com/dfm/gp)
- e** [foreman.mackey@gmail.com](mailto:foreman.mackey@gmail.com)

1

# Gaussian **P**rocesses



Don't you think **you**  
should be using  
**Gaussian Processes?**

A man with dark, wavy hair and a serious expression is pointing his right index finger directly at the camera. He is wearing a dark blue or black shirt. The background is a plain, light-colored wall. The lighting is soft, highlighting his face and hand.

Don't you think **you**  
should be using  
**Gaussian Processes?**

After today, you will be.

gaussian process - Google Search

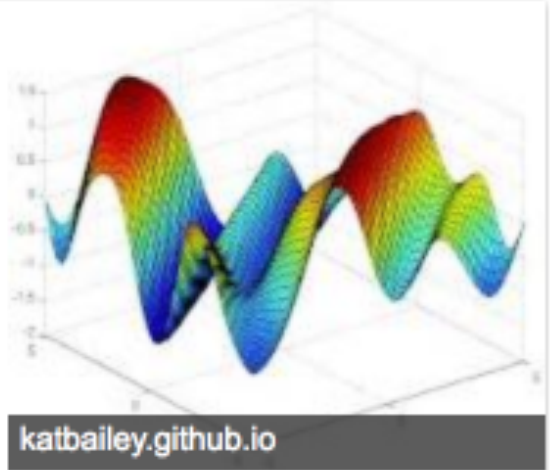
Secure | <https://www.google.com.au/search?q=gaussian+process&oq=gaussian+process&aqs=chrome..69i57j69i61l2j0l3.2794j0j4&sourc...>

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About 3,840,000 results (0.44 seconds)

In probability theory and statistics, a **Gaussian process** is a particular kind of statistical model where observations occur in a continuous domain, e.g. time or space. In a **Gaussian process**, every point in some continuous input space is associated with a normally distributed random variable.



[Gaussian process - Wikipedia](https://en.wikipedia.org/wiki/Gaussian_process)  
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[Ornstein–Uhlenbeck process](#) · [Kriging](#) · [Lazy learning](#)

[Gaussian Processes for Dummies · - Katherine Bailey](https://katbailey.github.io/post/gaussian-processes-for-dummies/)  
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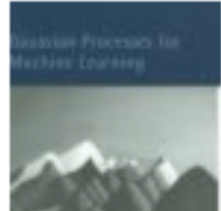
Aug 9, 2016 - **Gaussian Processes** (GPs) are the natural next step in that journey as they provide an alternative approach to regression problems. This post ...

[1.7. Gaussian Processes — scikit-learn 0.19.1 documentation](https://scikit-learn.org/stable/modules/gaussian_process.html)  
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**Gaussian Processes** (GP) are a generic supervised learning method designed to solve regression and probabilistic classification problems. The advantages of **Gaussian processes** are: The prediction interpolates the observations (at least for regular kernels).

See results about

[Gaussian processes for m...](#)  
Originally published: 23 N...  
Authors: Carl Edward Ras...



gaussian process - Google Search

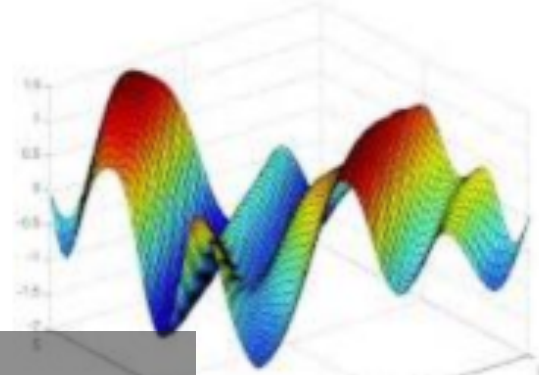
Secure | <https://www.google.com.au/search?q=gaussian+process&oq=gaussian+process&aqs=chrome..69i57j69i61i2j0i3.2794j0j4&sourc...>

gaussian process

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[https://en.wikipedia.org/wiki/Gaussian\\_process](https://en.wikipedia.org/wiki/Gaussian_process)

Cool.

katbailey.github.io

About this result Feedback

**See results about**

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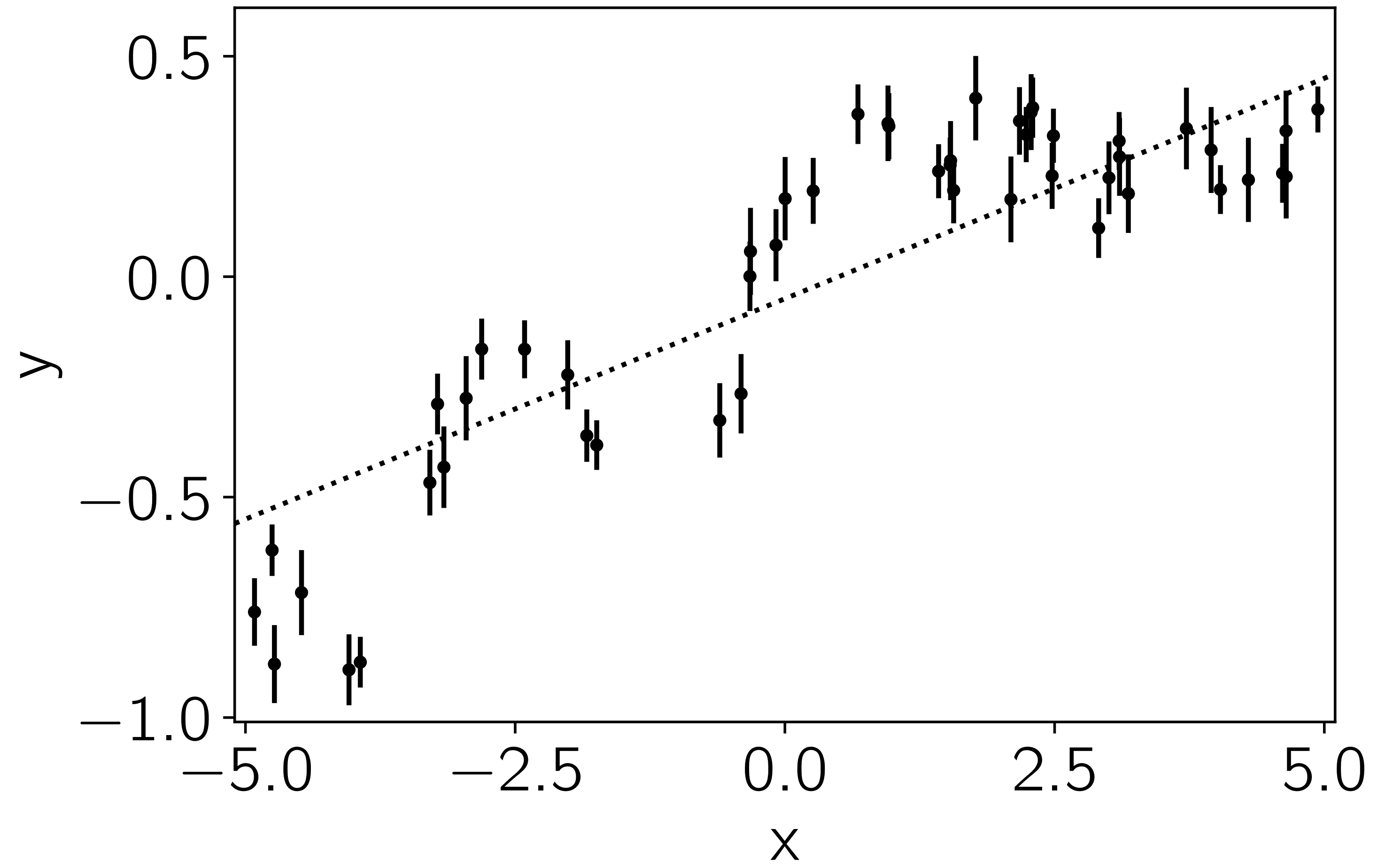
# Today

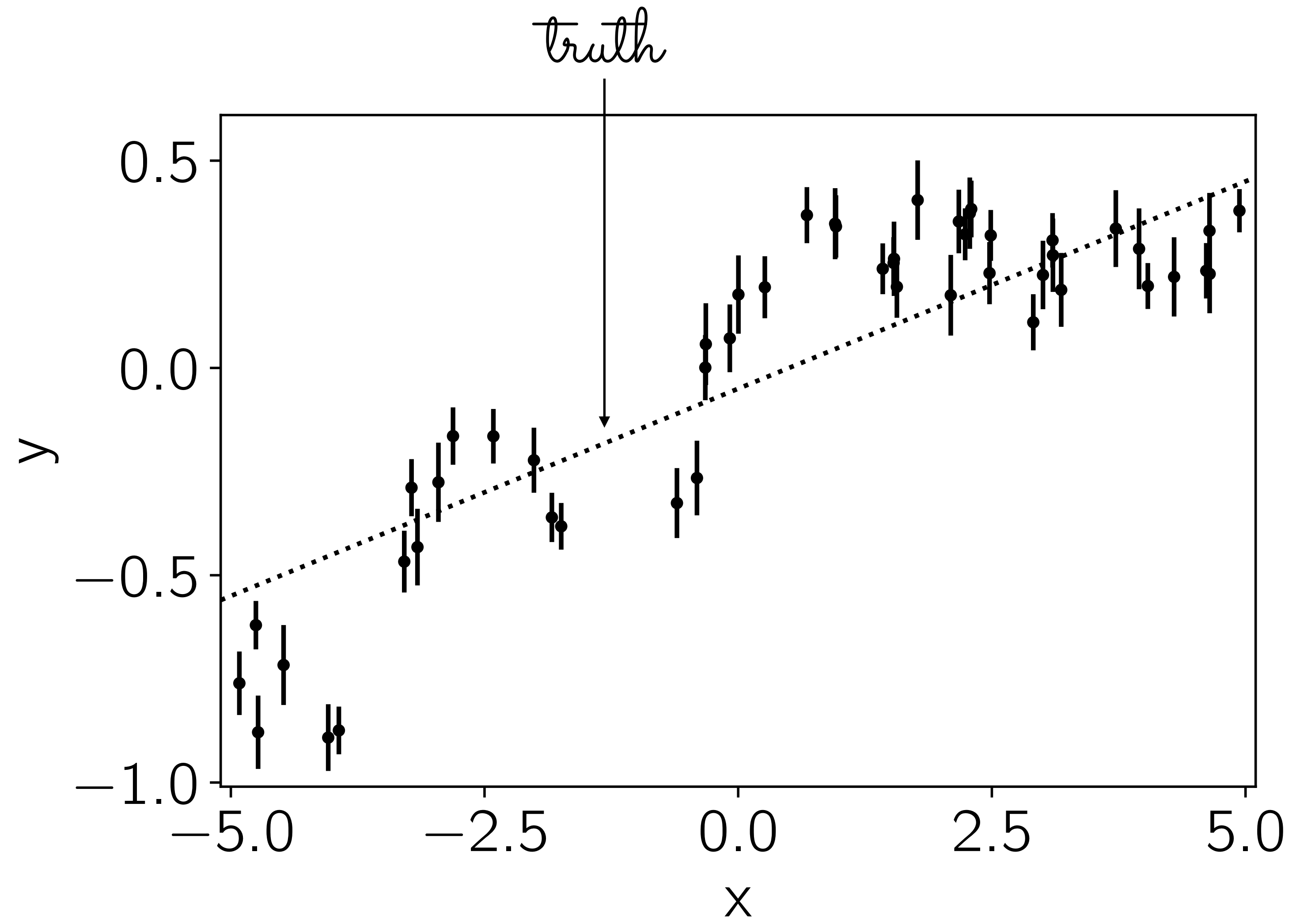
- 1 Why?
- 2 What?
- 3 How?

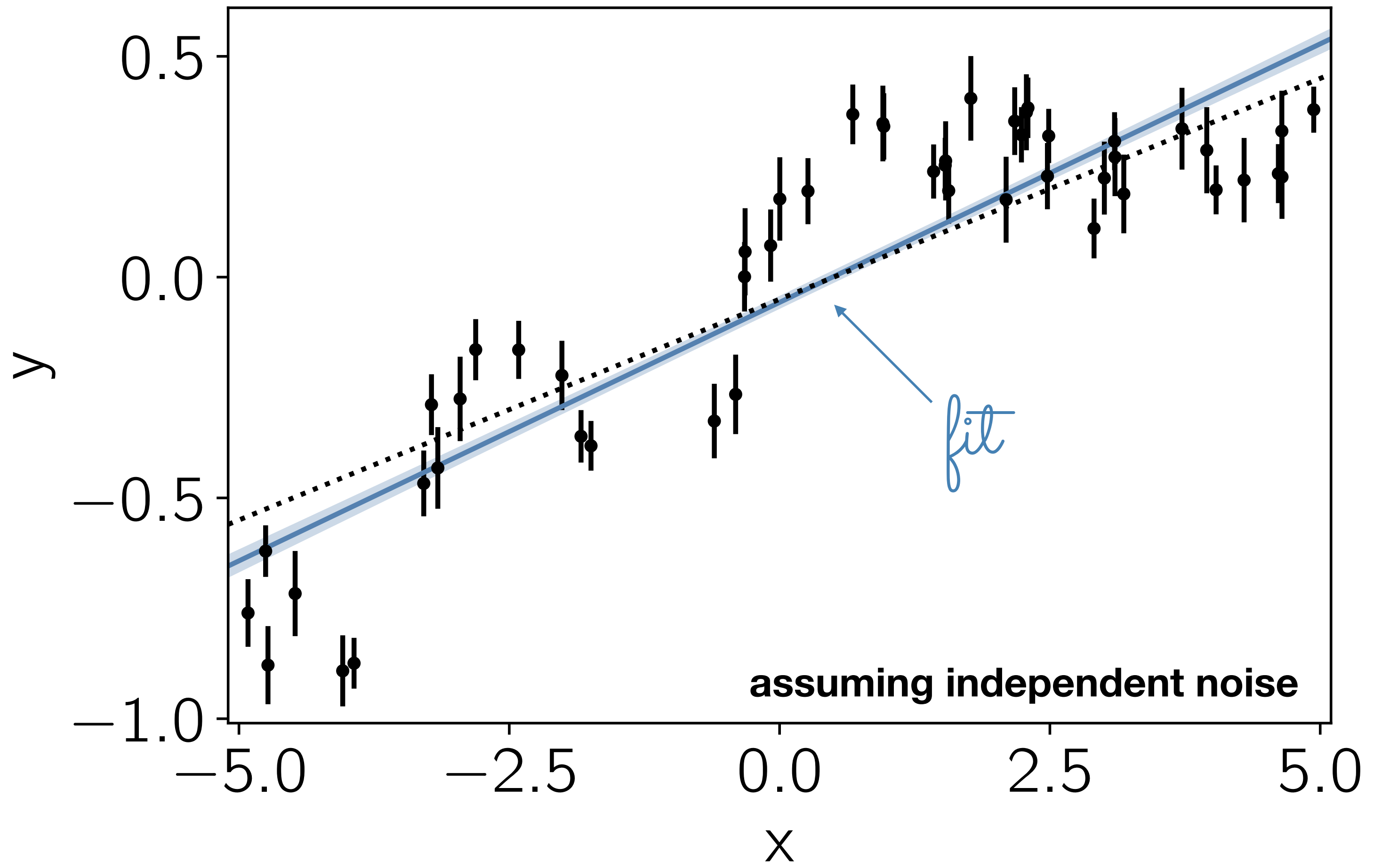
2

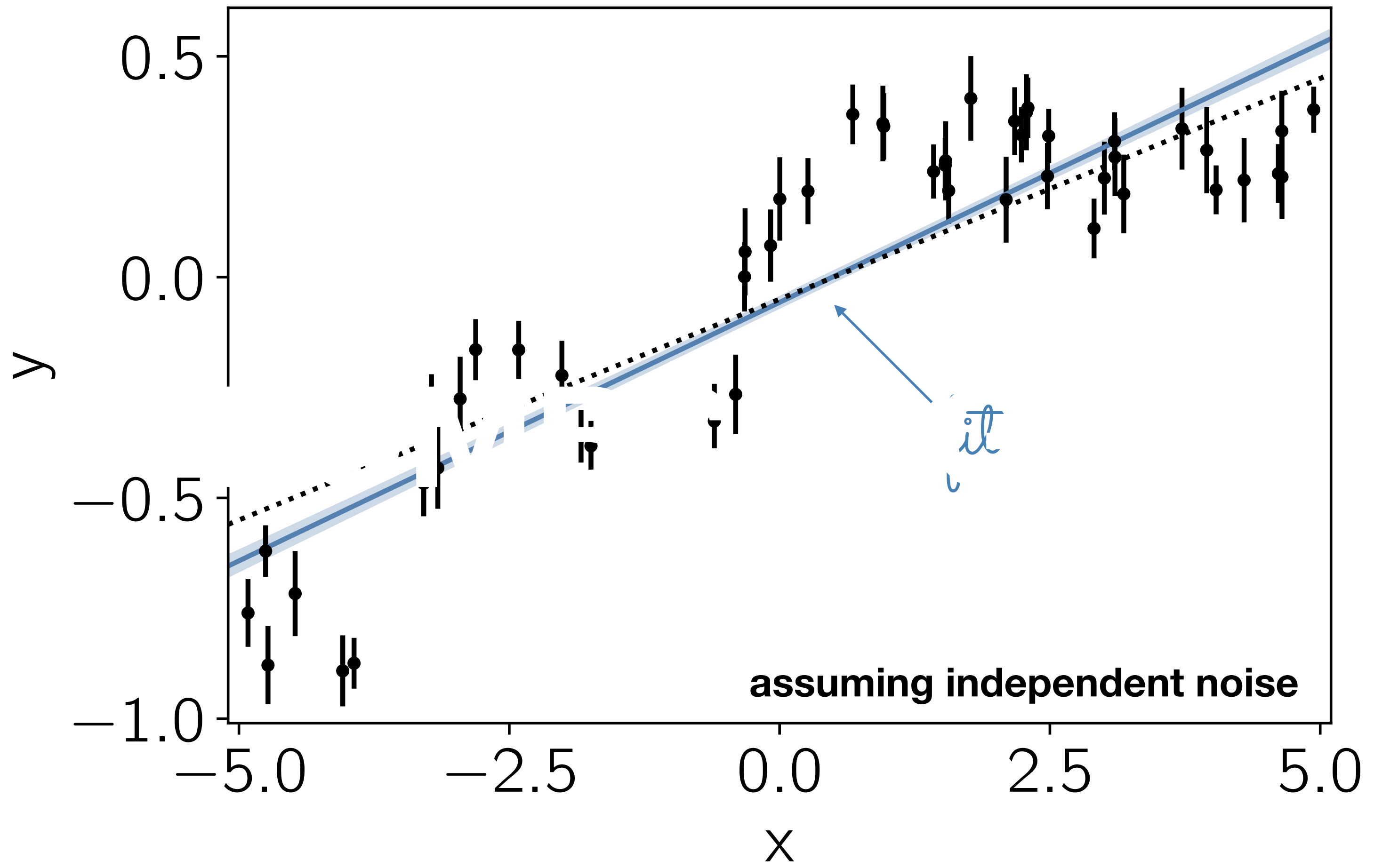
# The **importance** of **correlated noise**

*a motivating example*

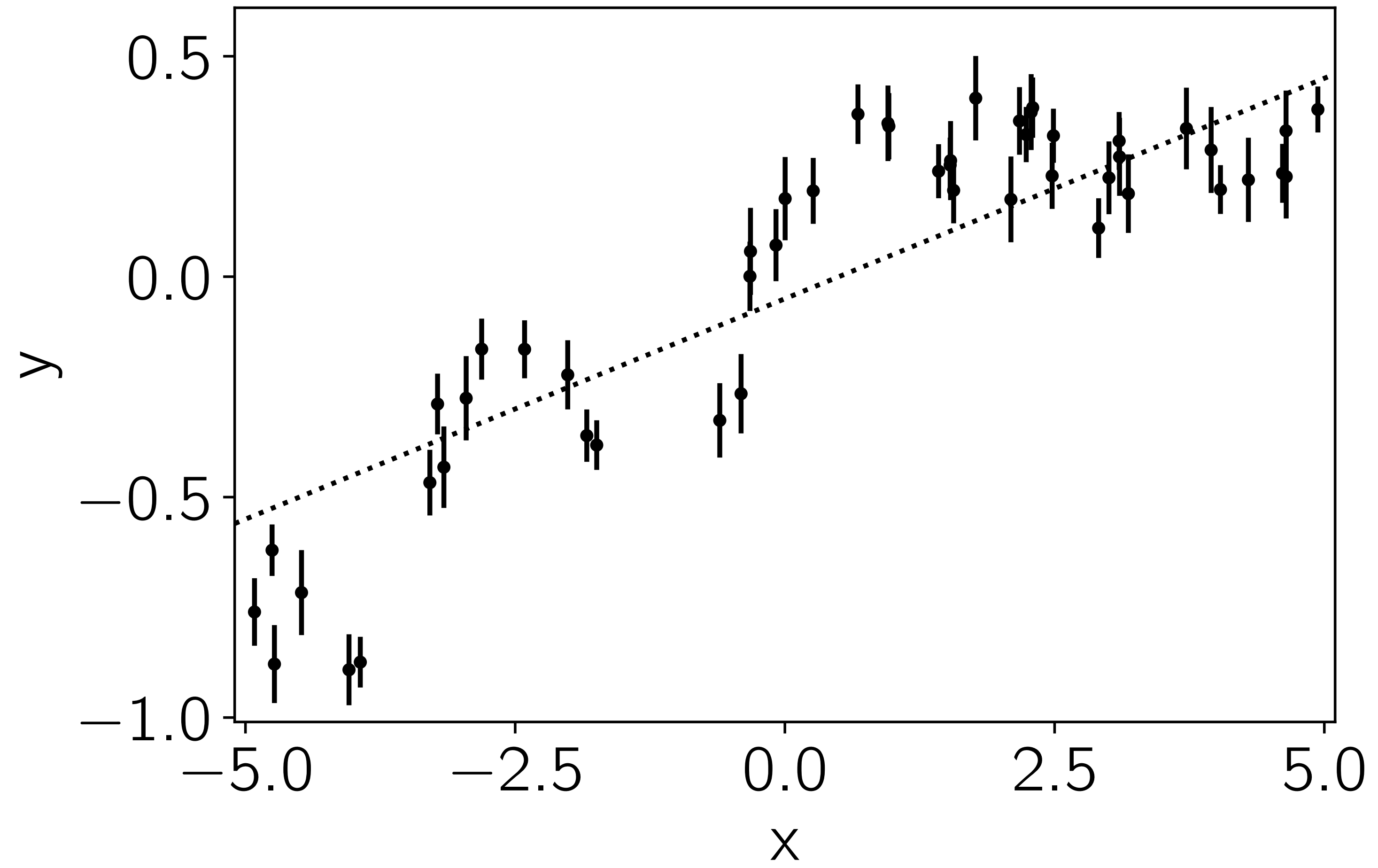




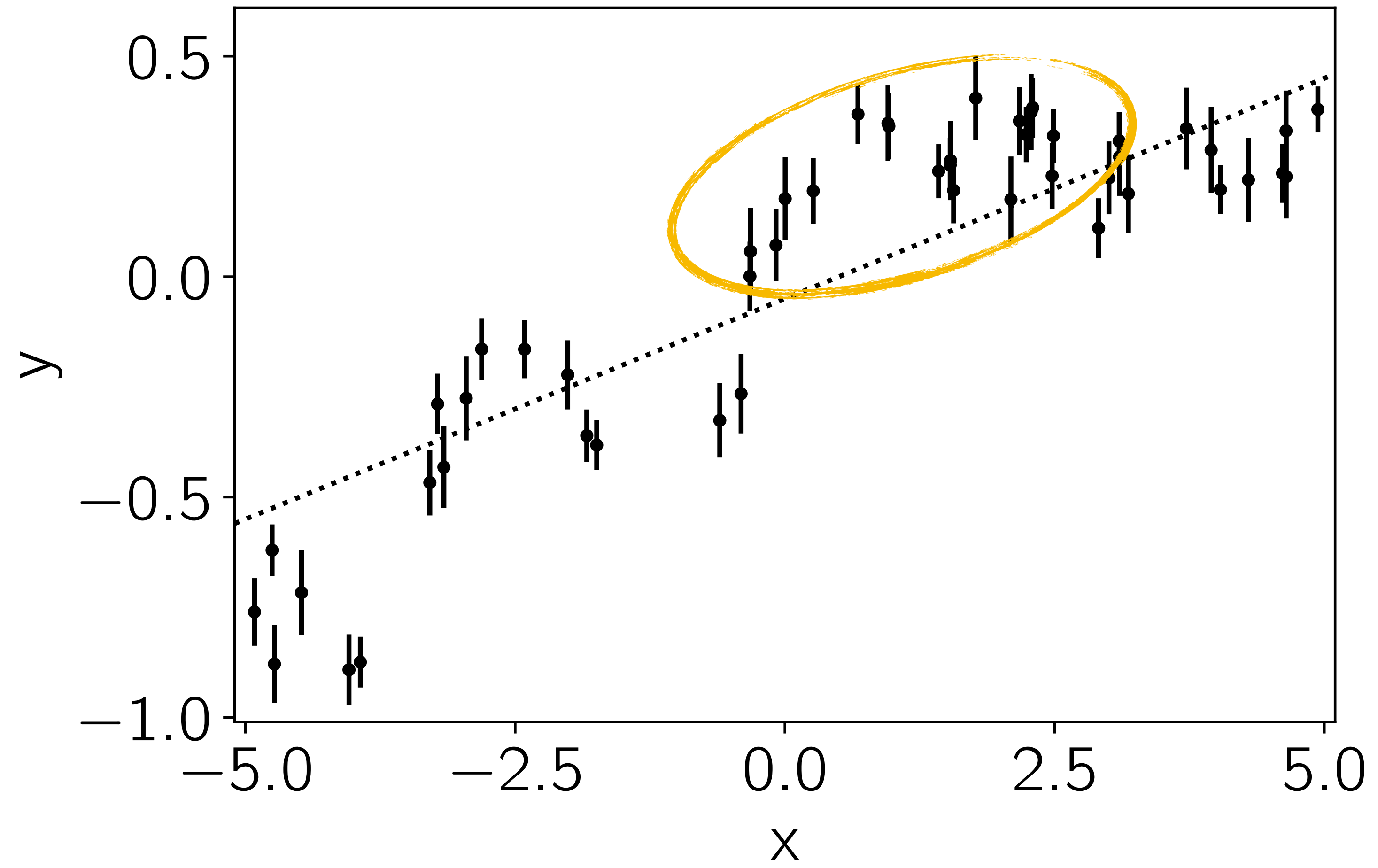




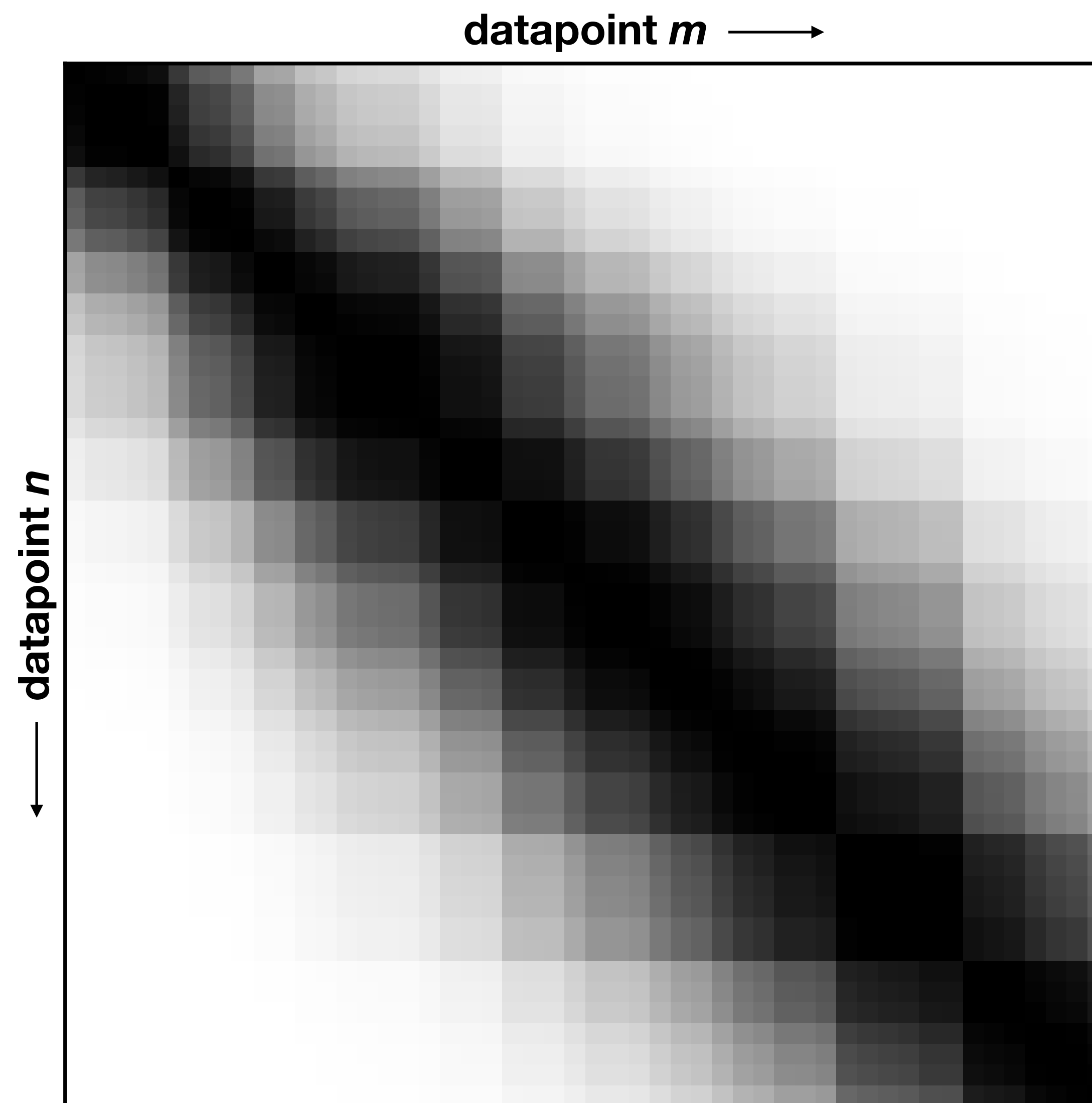
What **happened**?







# The true **covariance** matrix



$$\log p(\{y_n\} | \theta) = -\frac{1}{2} \sum_{n=1}^N \left[ \frac{[y_n - m_n]^2}{\sigma_n^2} + \log(2\pi\sigma_n^2) \right]$$



$$\log p(\{y_n\} | \theta) = -\frac{1}{2} \mathbf{r}^T \mathbf{C}^{-1} \mathbf{r} - \frac{1}{2} \log \det \mathbf{C} - \frac{N}{2} \log(2\pi)$$

if...

$$\mathbf{r} = \begin{pmatrix} y_1 - m_1 \\ \vdots \\ y_N - m_N \end{pmatrix} \quad \text{and} \quad \mathbf{C} = \begin{pmatrix} \sigma_1^2 & & 0 \\ & \ddots & \\ 0 & & \sigma_N^2 \end{pmatrix}$$

$$\log p(\{y_n\} | \theta) = -\frac{1}{2} \sum_{n=1}^N \left[ \frac{[y_n - m_n]^2}{\sigma_n^2} + \log(2\pi\sigma_n^2) \right]$$



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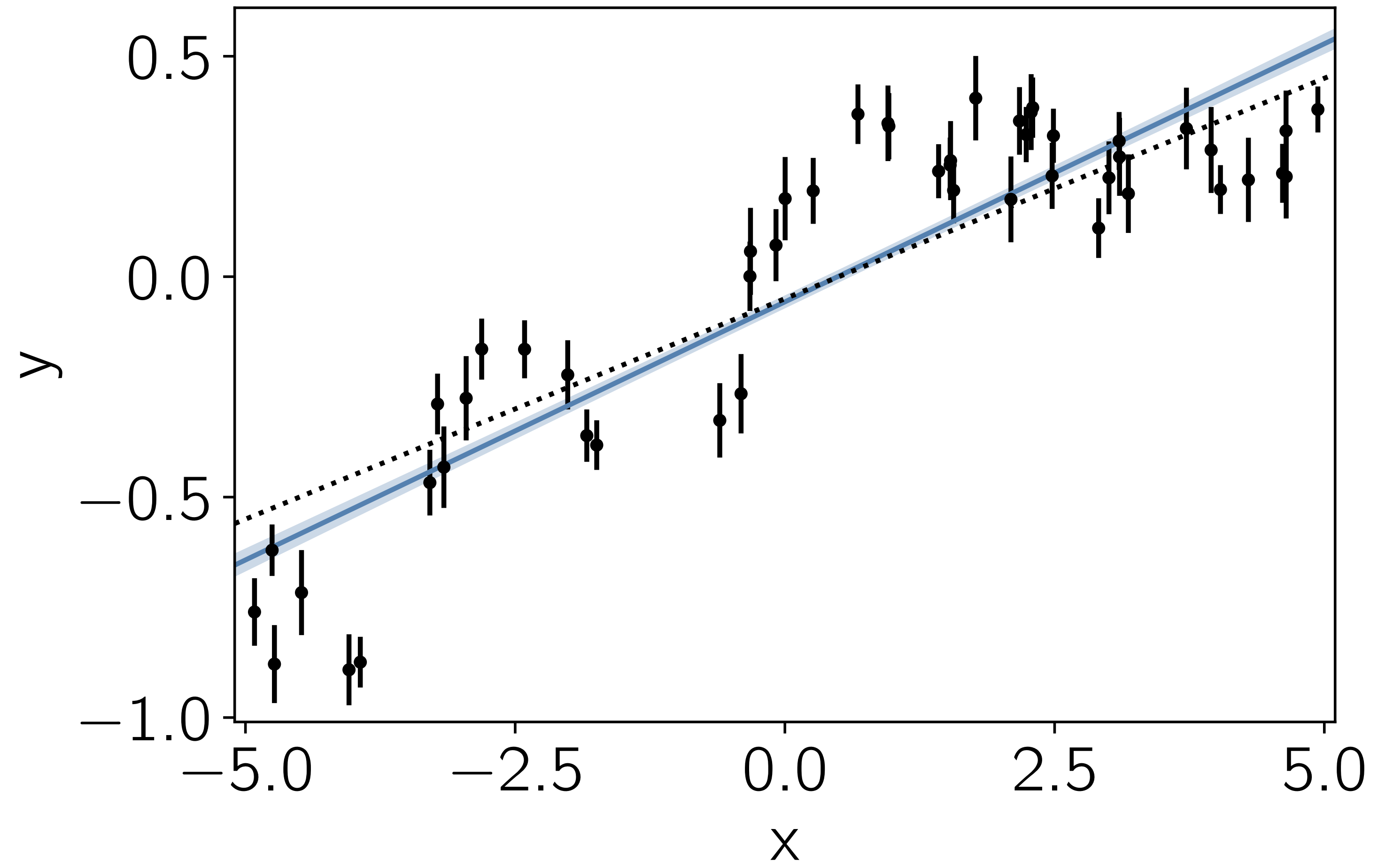
↓

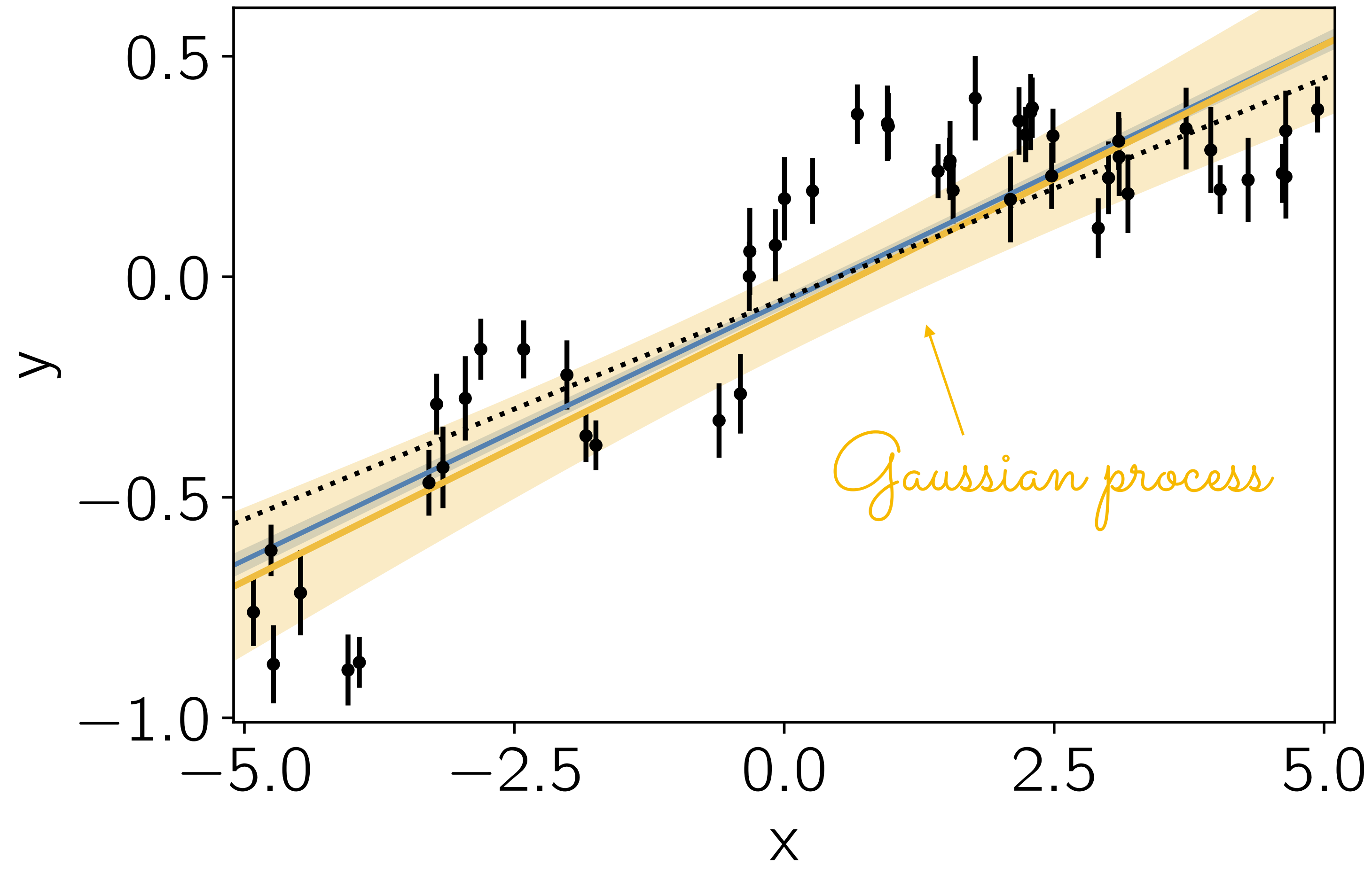
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if...

$$\mathbf{r} = \begin{pmatrix} y_1 - m_1 \\ \vdots \\ y_N - m_N \end{pmatrix} \quad \text{and} \quad \mathbf{C} = \begin{pmatrix} \text{[Covariance Matrix]}^* \end{pmatrix}$$

\* Note: this part has **everything** to do with Gaussian processes



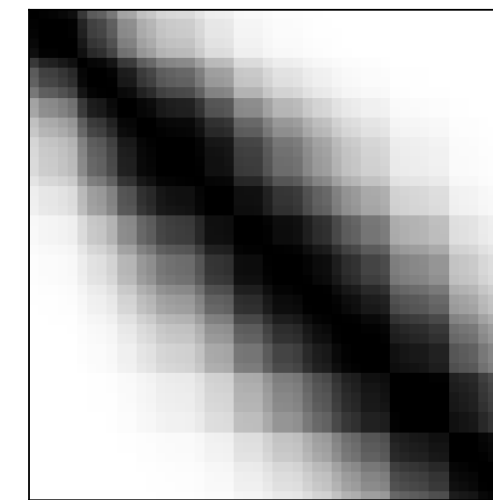




Excellent.



But: we don't know

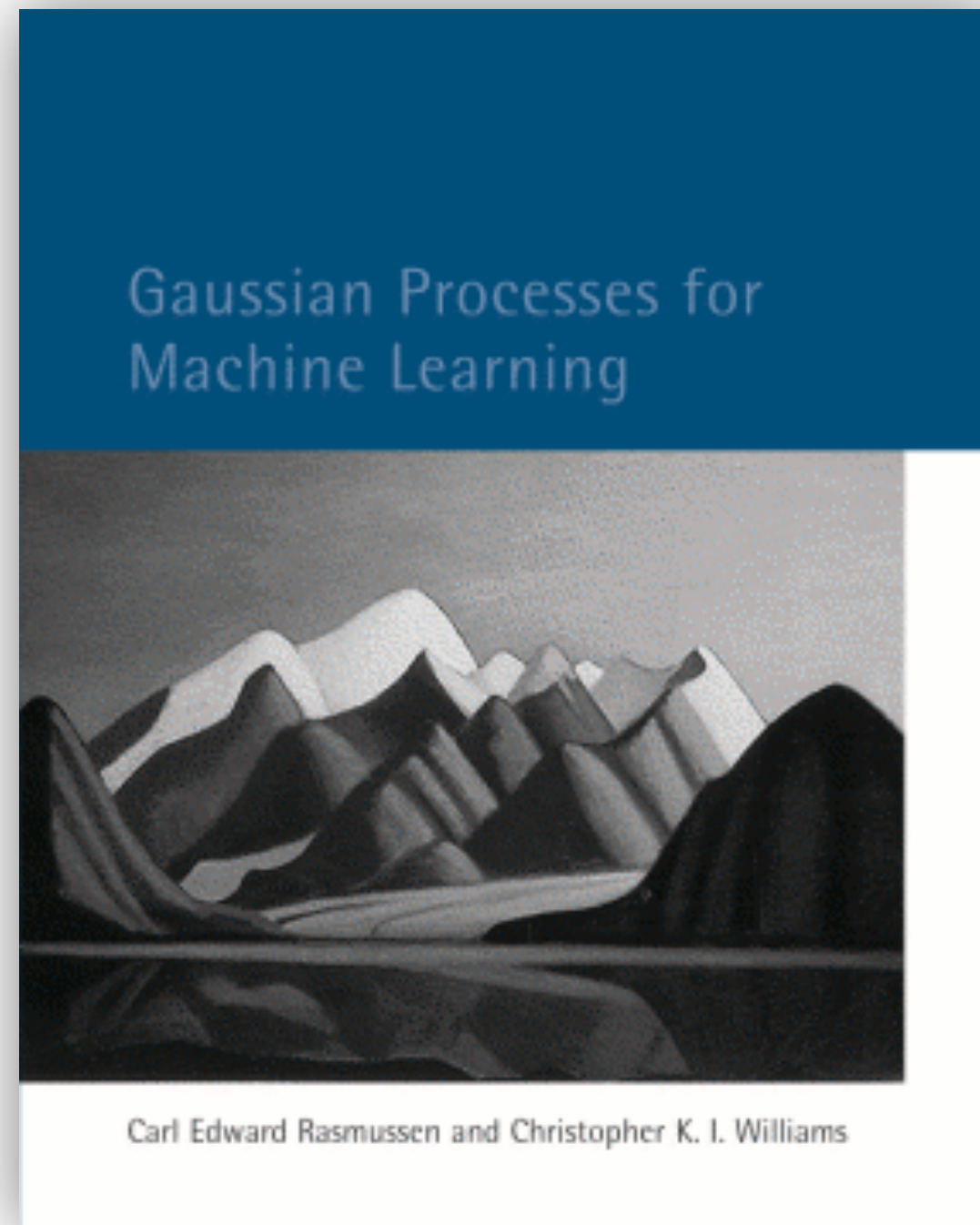


\*

\* we need to fit for it.

3

# The **math** of **Gaussian processes**



Rasmussen & Williams  
[gaussianprocess.org/gpml](http://gaussianprocess.org/gpml)

parameters of mean model

covariance matrix

$$\log p(\{y_n\} | \theta, \alpha) = -\frac{1}{2} \mathbf{r}_\theta^T K_\alpha^{-1} \mathbf{r}_\theta - \frac{1}{2} \log \det K_\alpha - \frac{N}{2} \log(2\pi)$$

parameters of covariance model

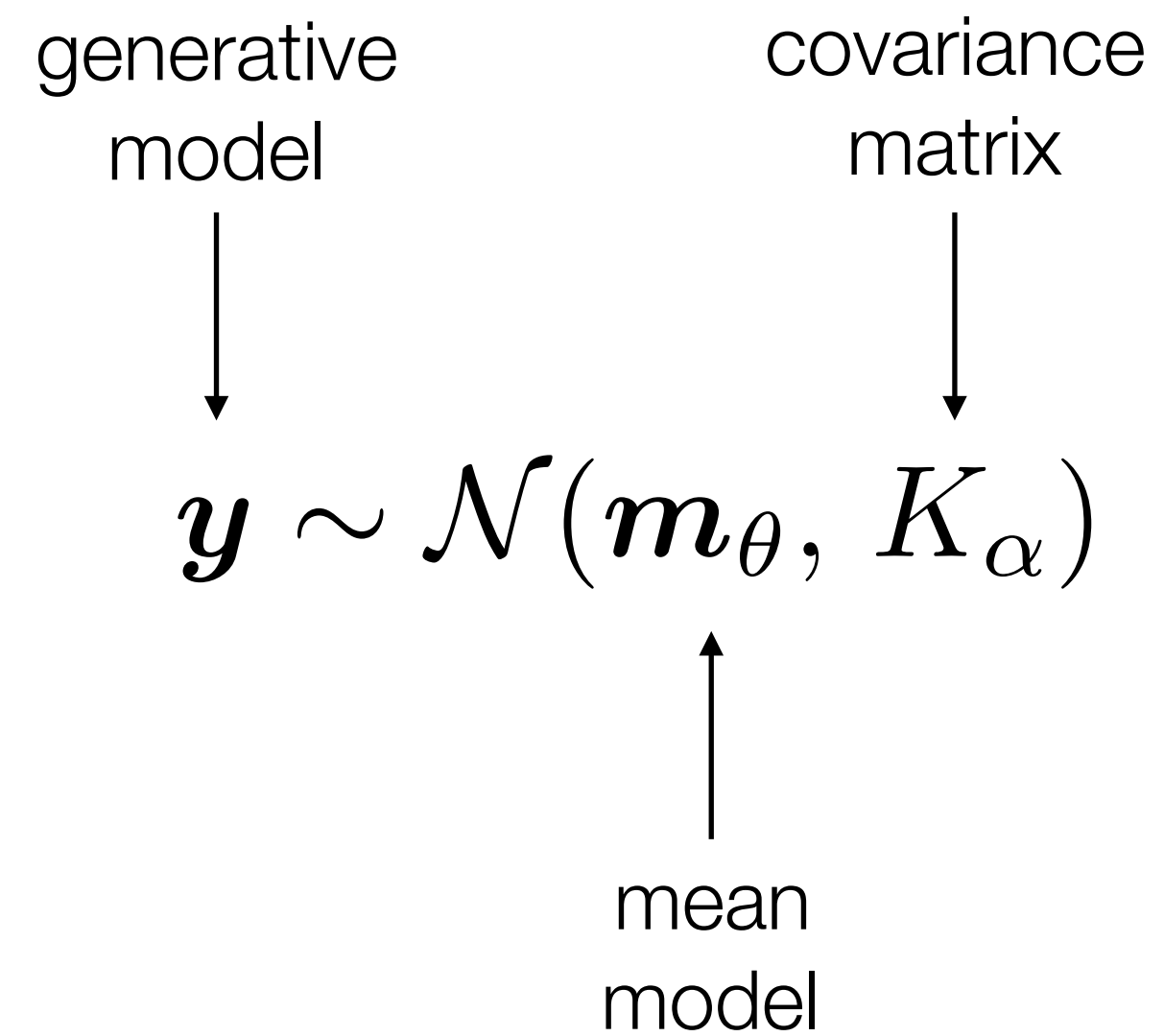
residual vector

The diagram illustrates the components of the log-likelihood function. It shows the equation:  $\log p(\{y_n\} | \theta, \alpha) = -\frac{1}{2} \mathbf{r}_\theta^T K_\alpha^{-1} \mathbf{r}_\theta - \frac{1}{2} \log \det K_\alpha - \frac{N}{2} \log(2\pi)$ . Four labels with arrows point to specific parts of the equation: 'parameters of mean model' points to  $\theta$ , 'covariance matrix' points to  $K_\alpha$ , 'parameters of covariance model' points to  $\alpha$ , and 'residual vector' points to  $\mathbf{r}_\theta$ .

$$\begin{array}{c}
 \text{parameters of} \\
 \text{mean model} \\
 \downarrow \\
 \log p(\{y_n\} \mid \theta, \alpha) = -\frac{1}{2} \mathbf{r}_\theta^T K_\alpha^{-1} \mathbf{r}_\theta - \frac{1}{2} \log \det K_\alpha - \frac{N}{2} \log(2\pi) \\
 \uparrow \qquad \qquad \qquad \uparrow \\
 \text{parameters of} \qquad \text{residual} \\
 \text{covariance model} \qquad \text{vector} \\
 \text{covariance} \\
 \text{matrix} \\
 \downarrow
 \end{array}$$

This is the equation for **an  $N$ -dimensional Gaussian**\*

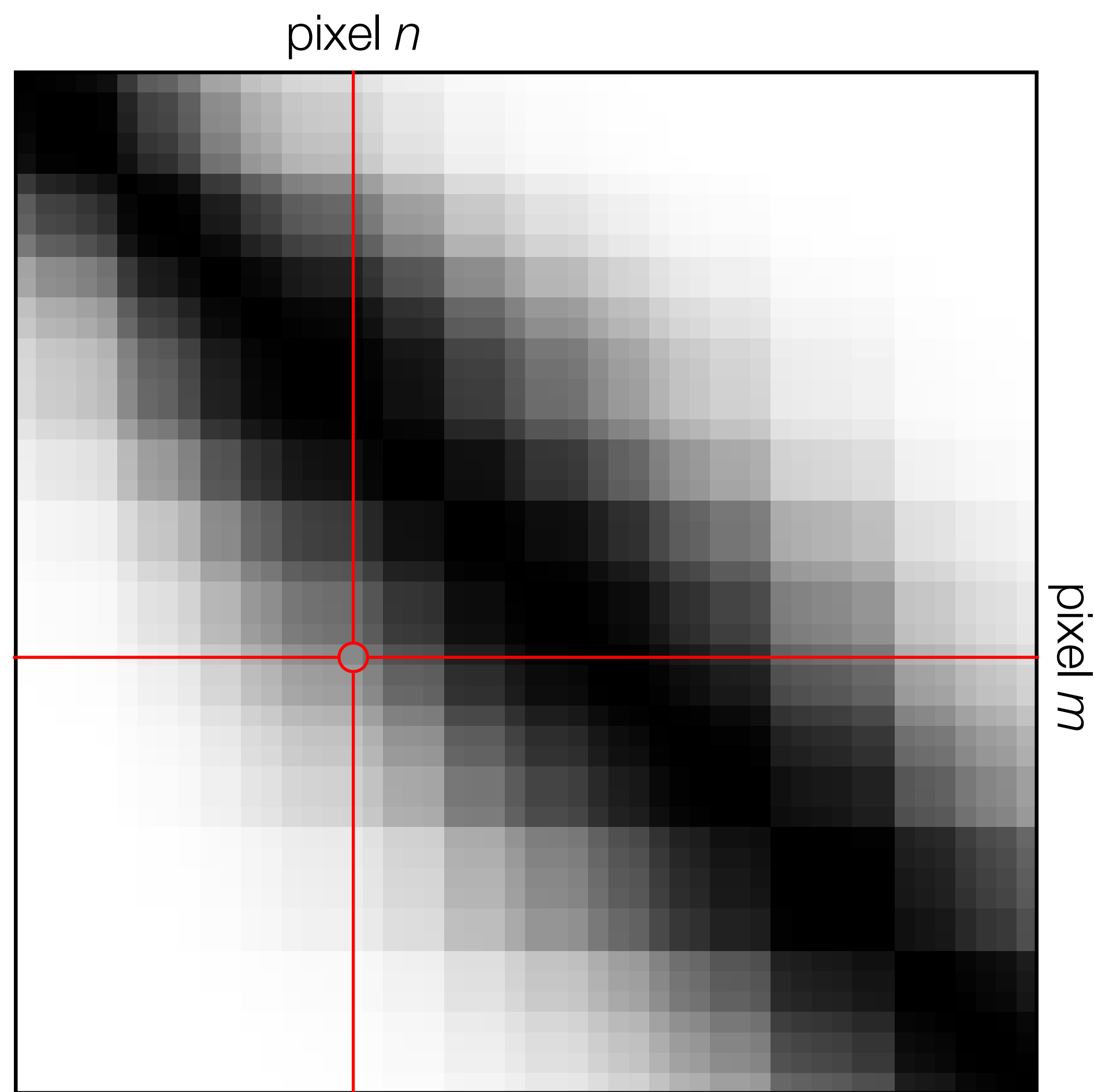
\* *hint: this is where the name comes from...*



This is the equation for **an  $N$ -dimensional Gaussian**\*

\* *hint: this is where the name comes from...*

$$[K_\alpha]_{nm} =$$



$$[K_\alpha]_{nm} =$$



$$[K_\alpha]_{nm} = \sigma_n^2 \delta_{nm}$$

$$[K_\alpha]_{nm} = \sigma_n^2 \delta_{nm} + k_\alpha(\mathbf{x}_n, \mathbf{x}_m)$$

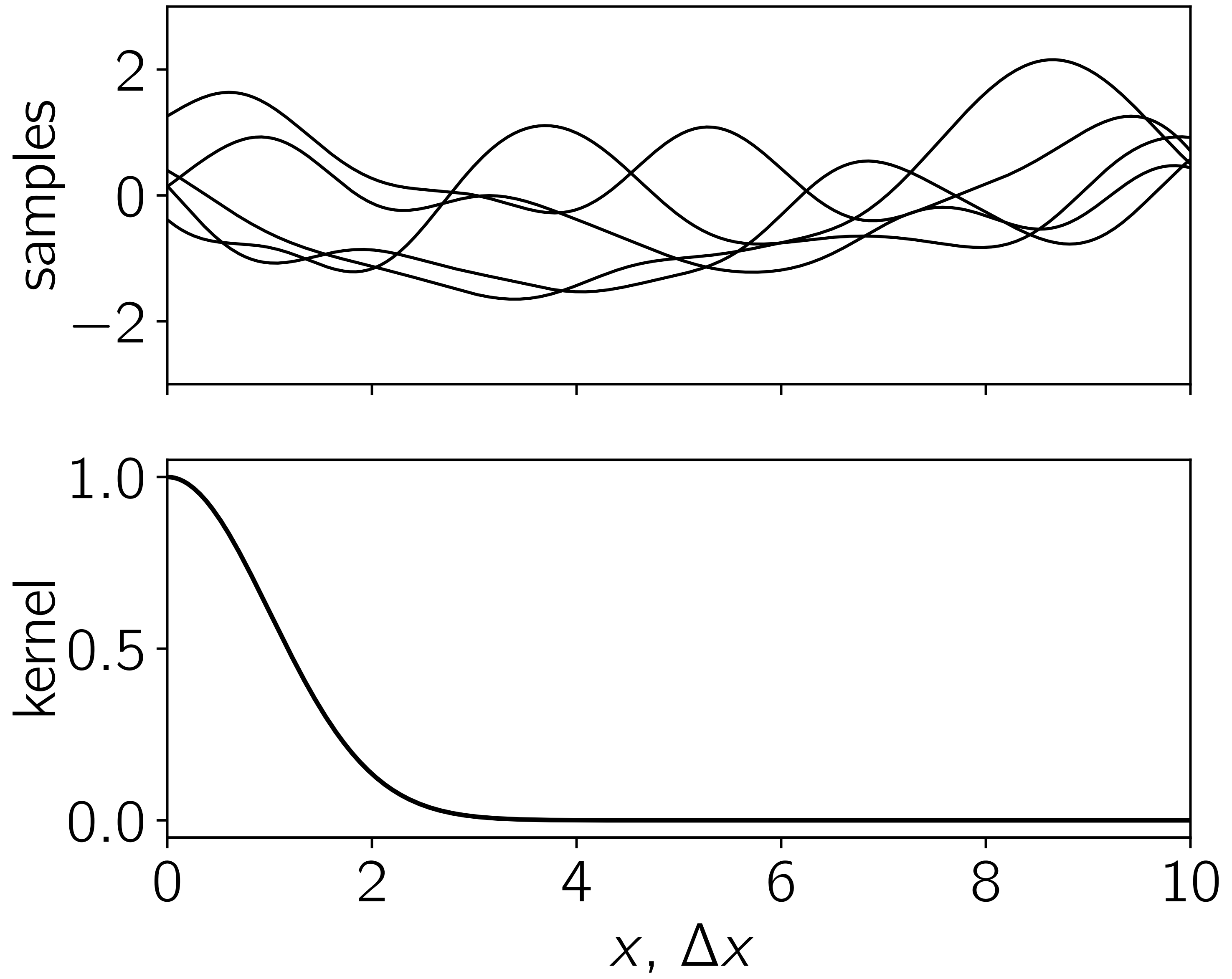
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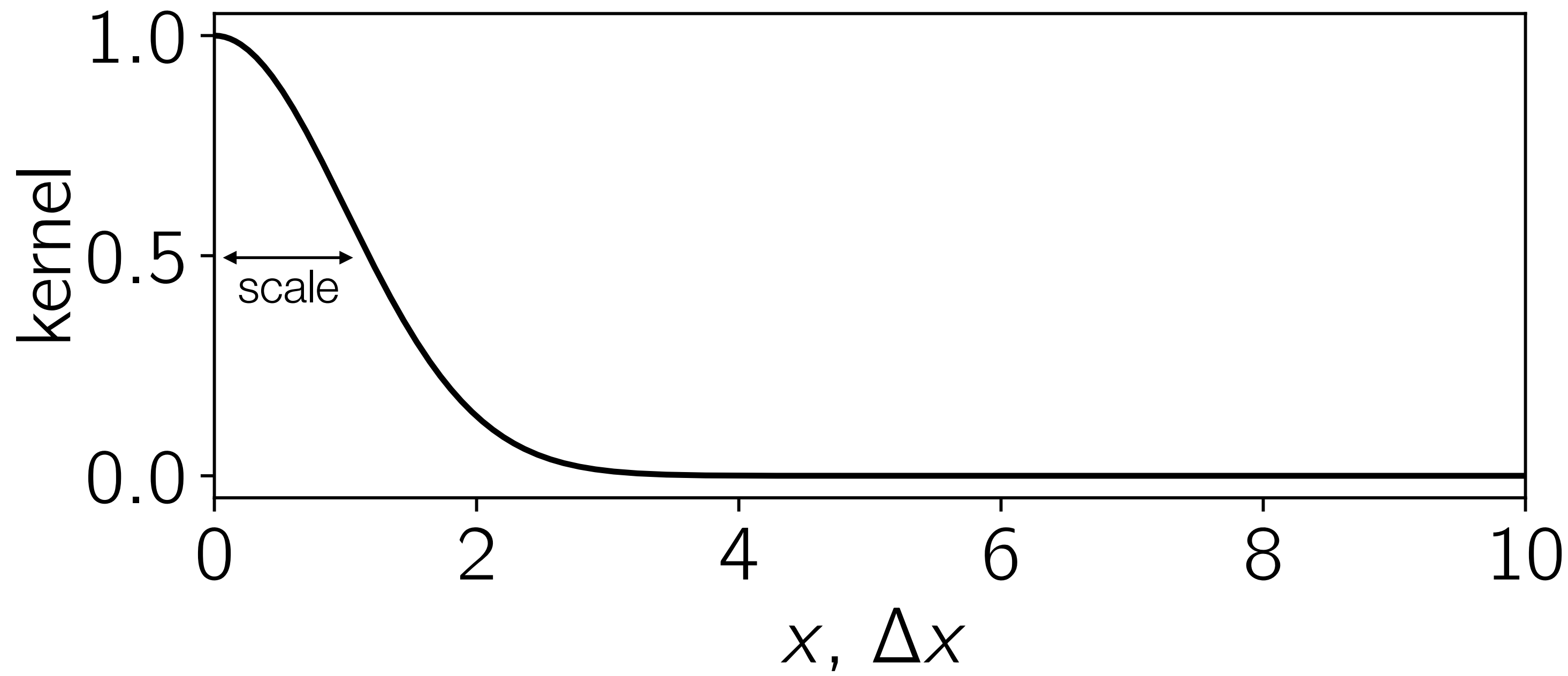
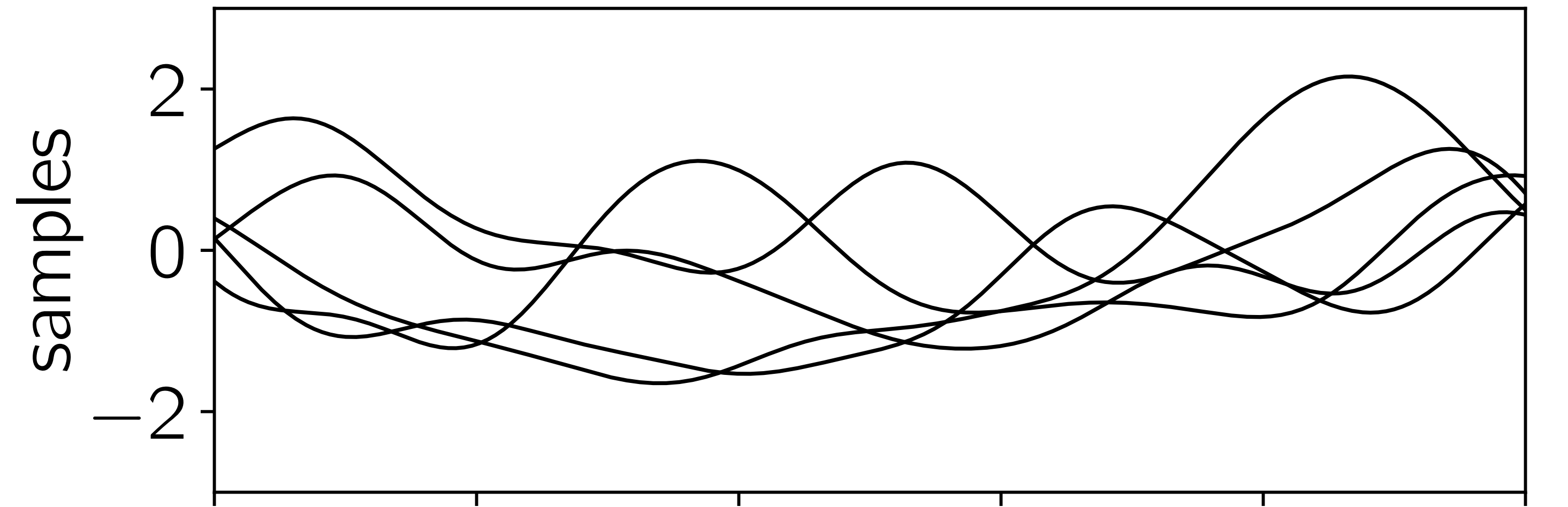
the "kernel" function

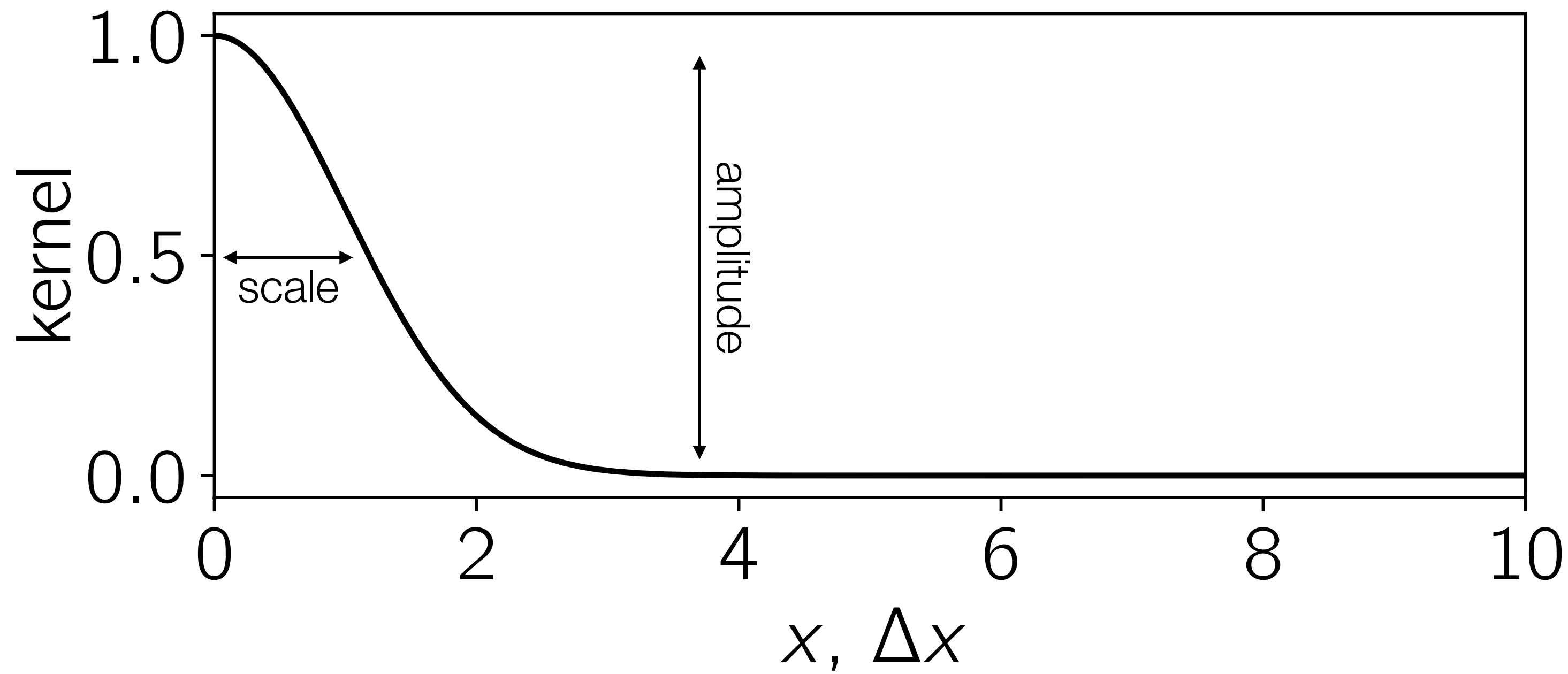
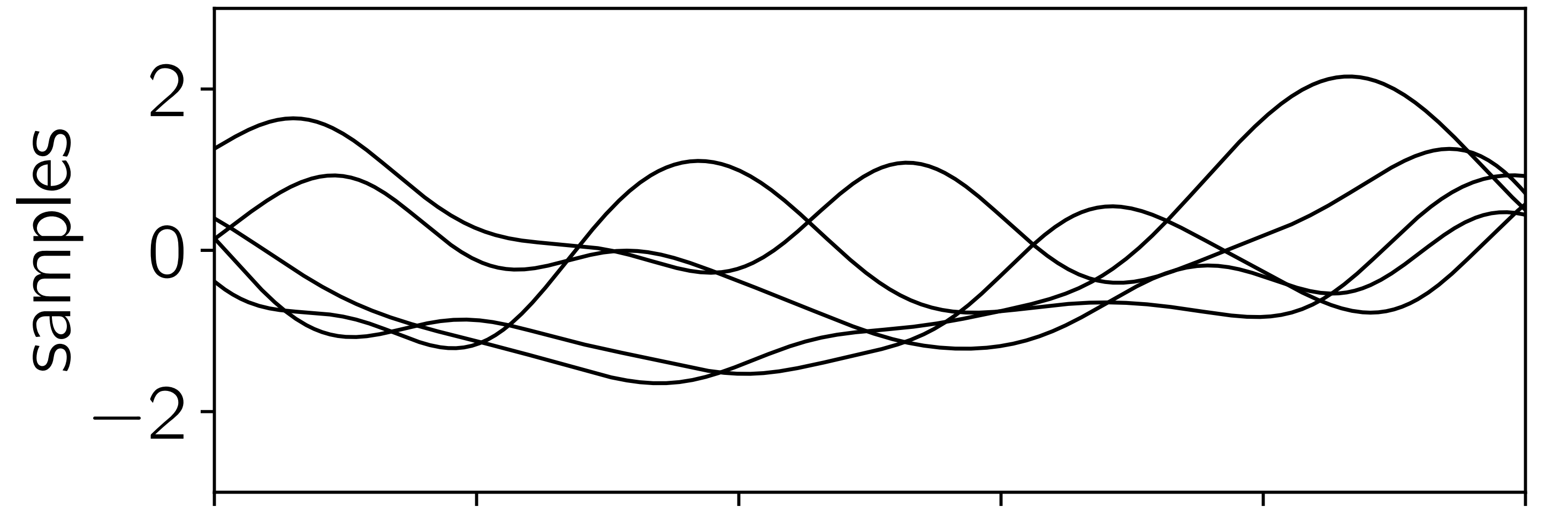
for example\*:

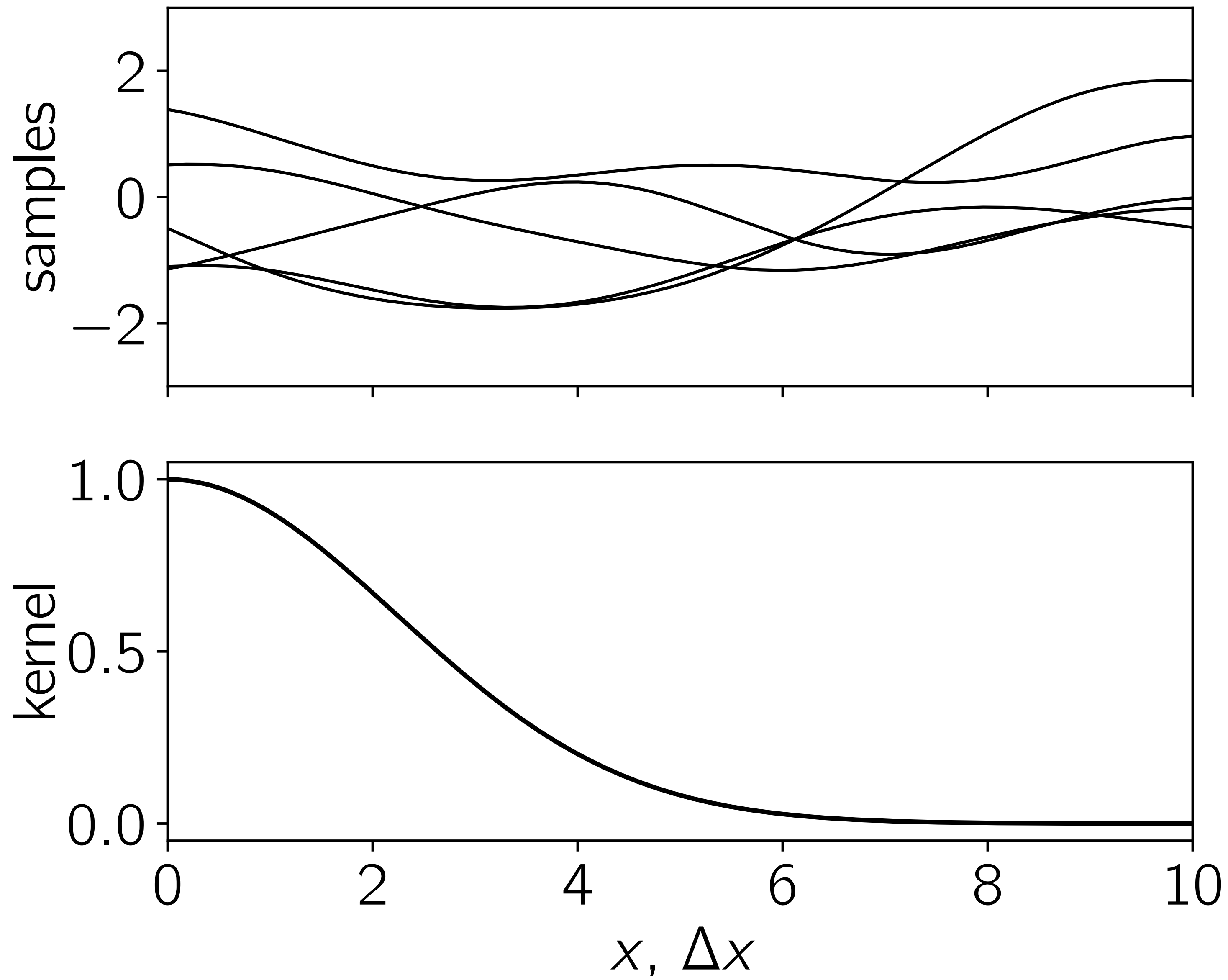
$$k_\alpha(\mathbf{x}_n, \mathbf{x}_m) = a^2 \exp\left(-\frac{(\mathbf{x}_n - \mathbf{x}_m)^2}{2\tau^2}\right)$$

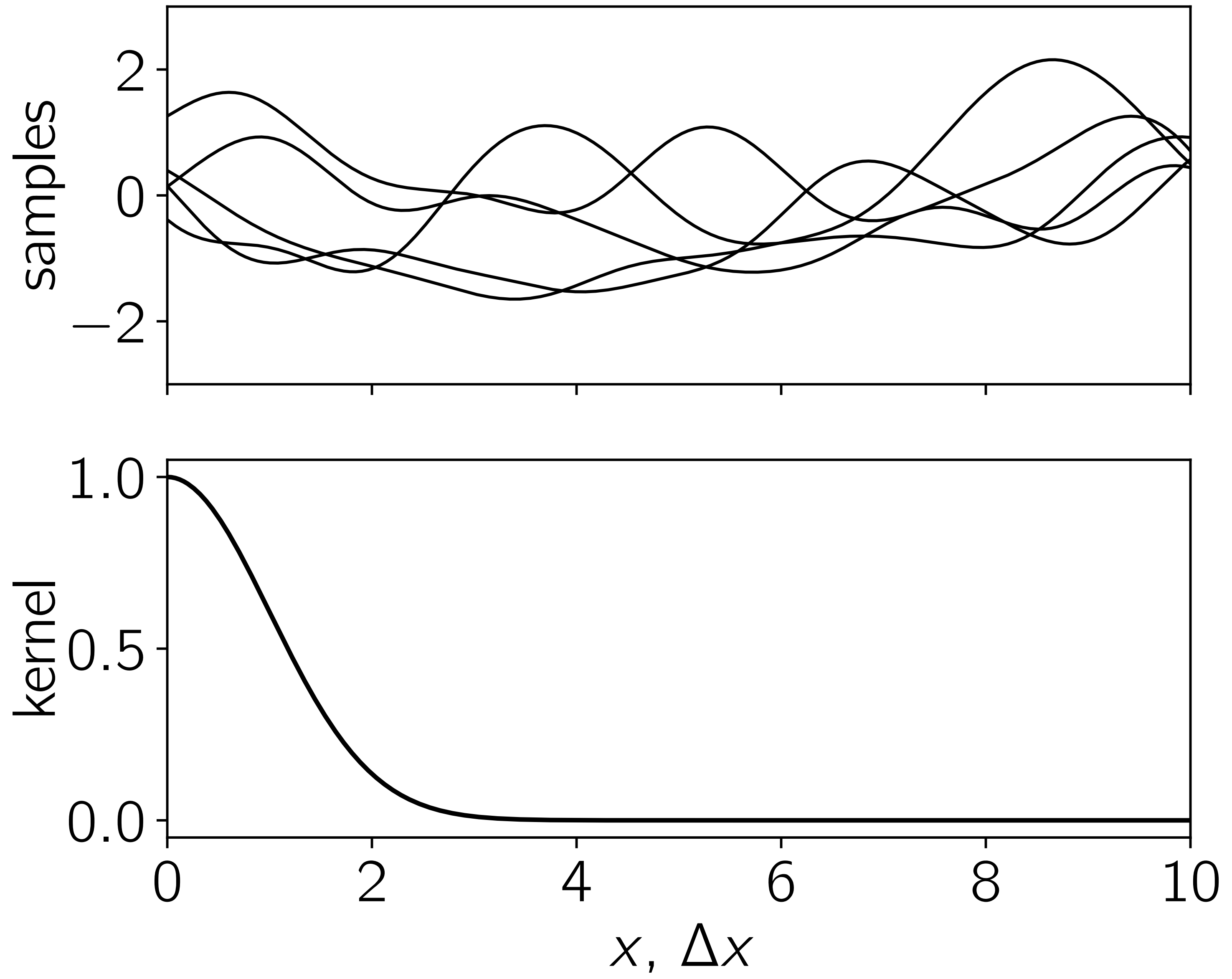
\* Note: this part has nothing to do with the name Gaussian process



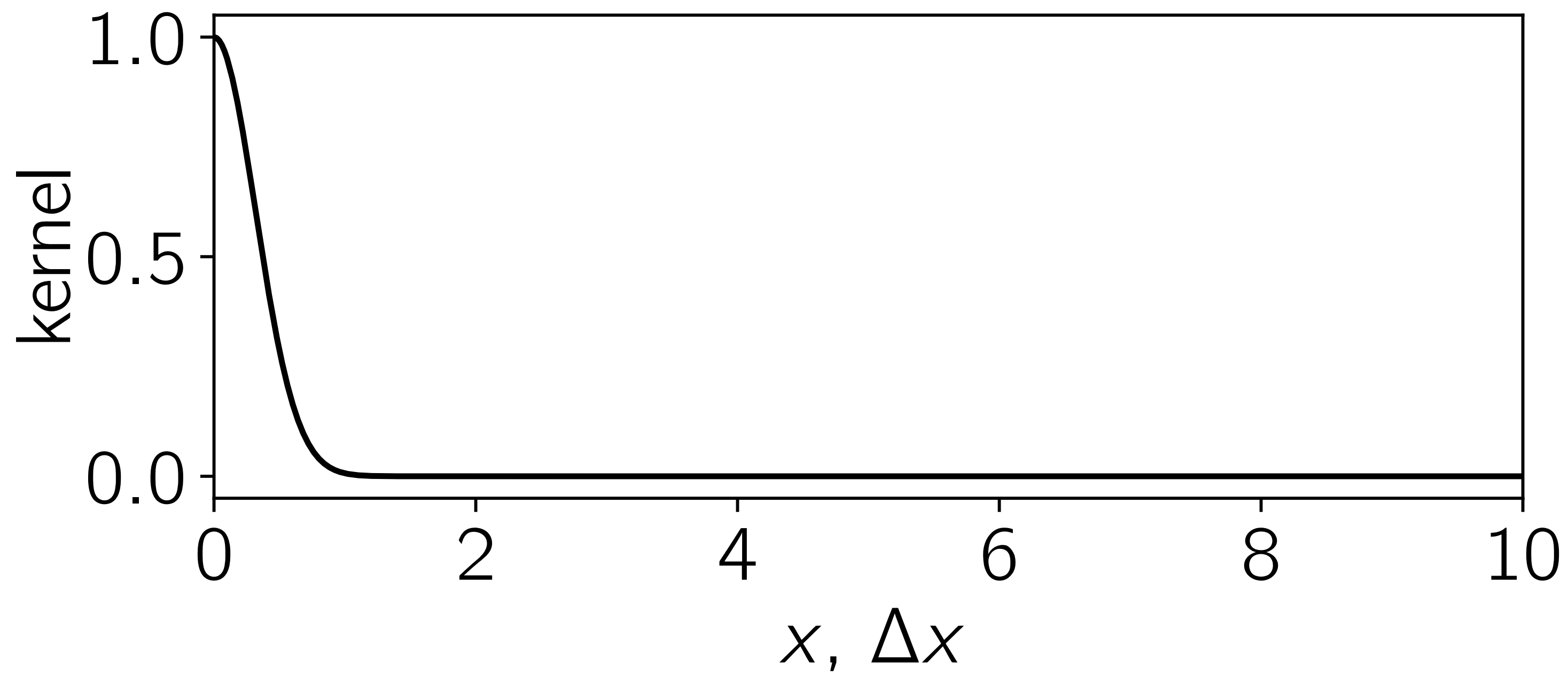
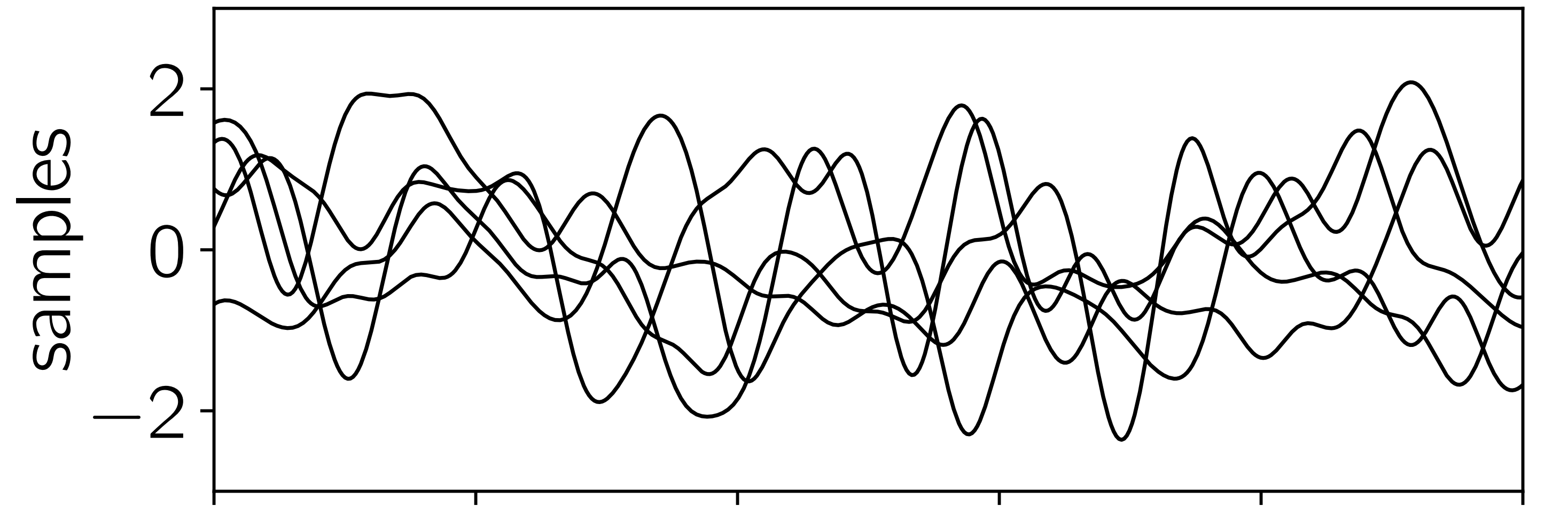


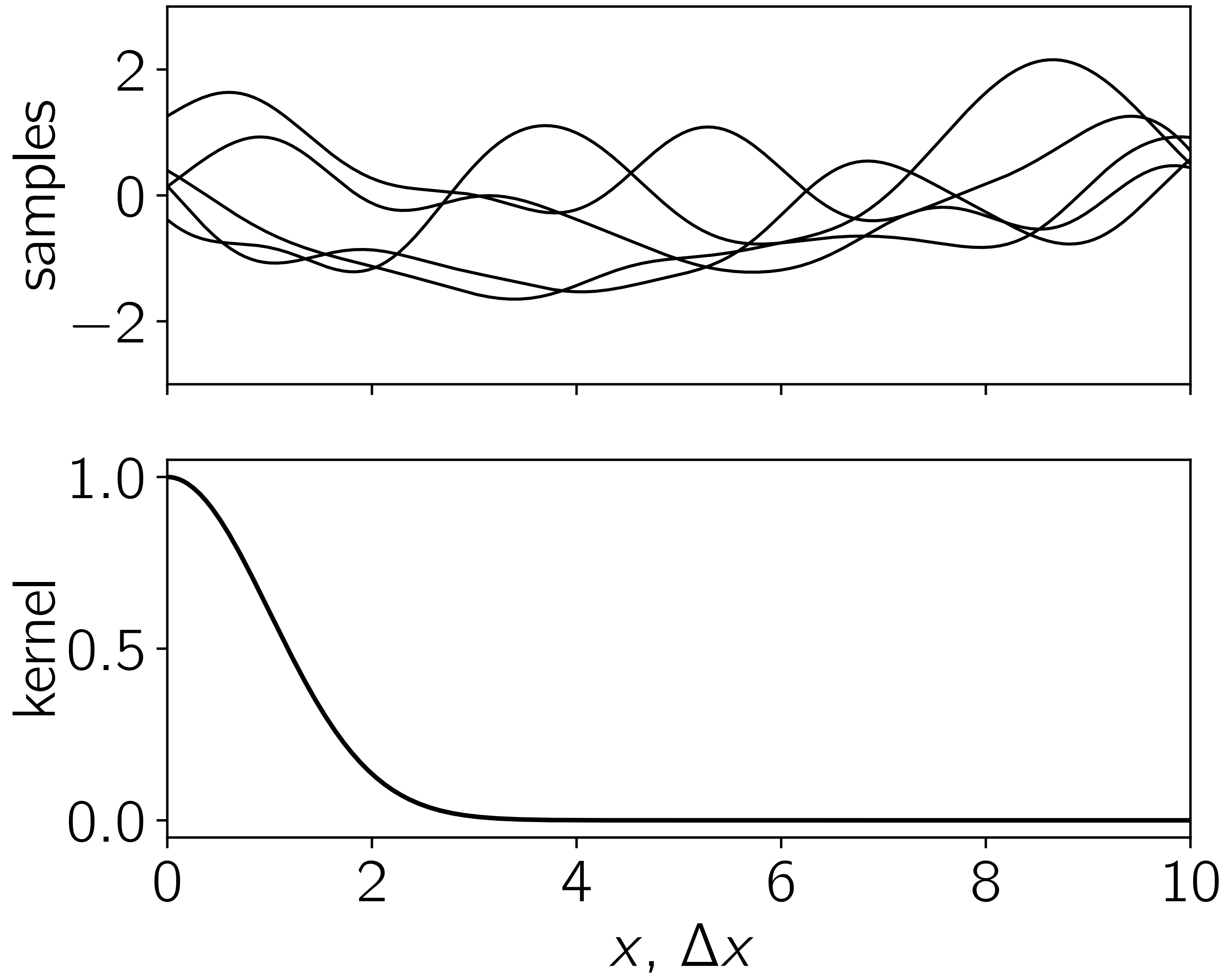


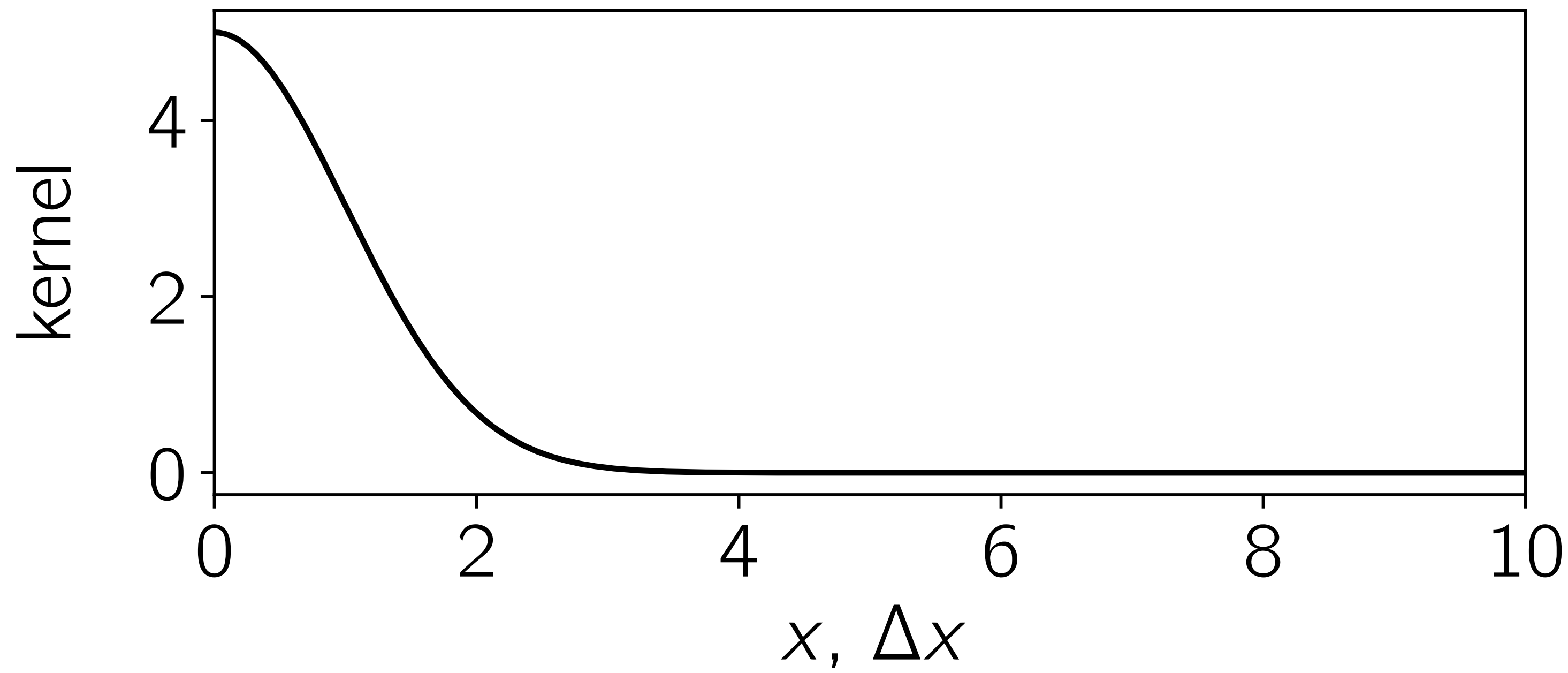
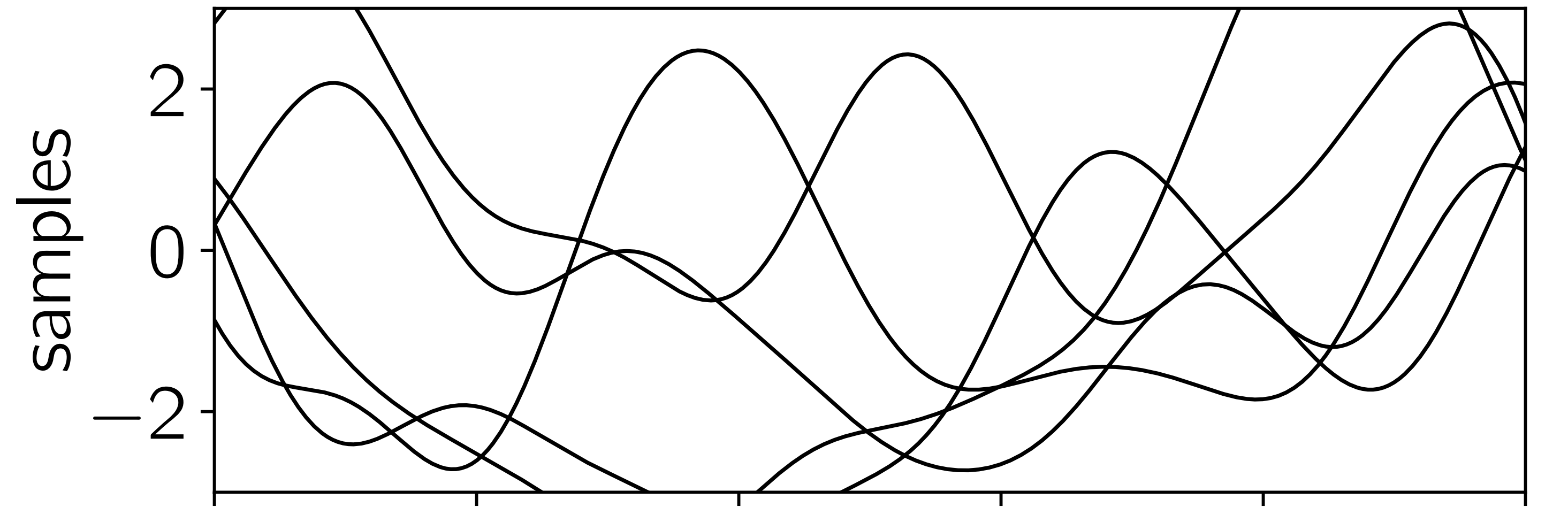












$$\log p(\{y_n\} | \theta, \alpha) = -\frac{1}{2} \mathbf{r}_\theta^T K_\alpha^{-1} \mathbf{r}_\theta - \frac{1}{2} \log \det K_\alpha - \frac{N}{2} \log(2\pi)$$

a **drop-in replacement** for  $\chi^2$

# A fully functional GP implementation in Python

```
import numpy as np

def gp_log_like(params, x, y, yerr):
    K = params[0]**2 * np.exp(-0.5*(x[:, None]-x[None, :])**2/params[1]**2)
    K[np.diag_indices_from(K)] += yerr**2
    ll = np.dot(y, np.linalg.solve(K, y))
    ll += np.linalg.slogdet(K)[1]
    return -0.5*ll
```

+ **scipy.optimize** or **emcee**

# Using GPs in Python

- 1 **george**
- 2 **scikit-learn**
- 3 **GPy**
- 4 **PyMC3**
- 5 **etc.**

# Using GPs in Python

1

george

2

scikit-learn

3

GPy

4

PyMC3

5

etc.

4

**Why?** The **problems** with Gaussian processes



$$\log p(\{y_n\} | \theta, \alpha) = -\frac{1}{2} \mathbf{r}_\theta^T K_\alpha^{-1} \mathbf{r}_\theta - \frac{1}{2} \log \det K_\alpha - \frac{N}{2} \log(2\pi)$$

a

## Choosing the kernel

$$\log p(\{y_n\} | \theta, \alpha) = -\frac{1}{2} \mathbf{r}_\theta^T K_\alpha^{-1} \mathbf{r}_\theta - \frac{1}{2} \log \det K_\alpha - \frac{N}{2} \log(2\pi)$$

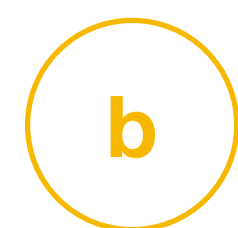
**a**

## Choosing the kernel

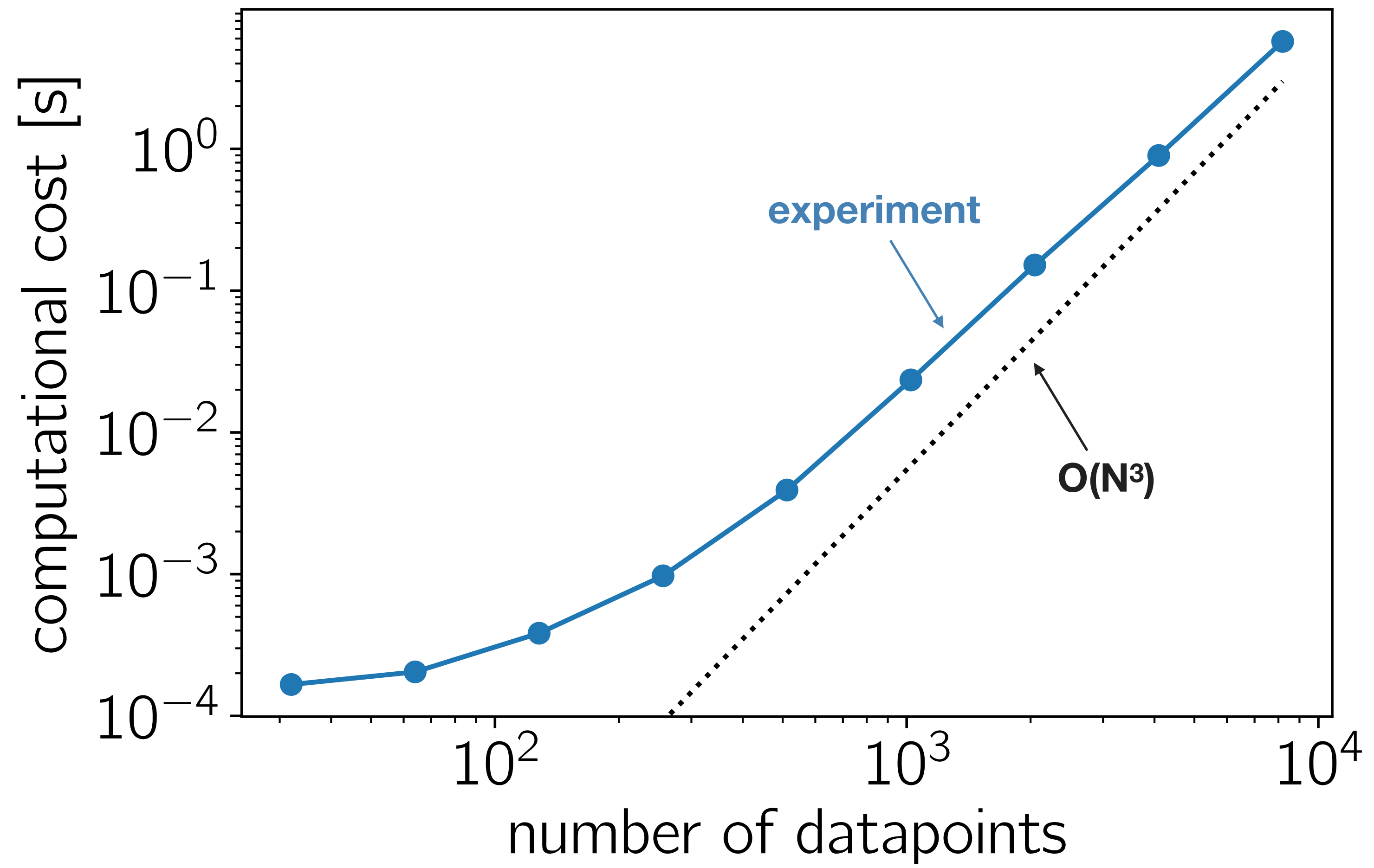
$$\log p(\{y_n\} | \theta, \alpha) = -\frac{1}{2} \mathbf{r}_\theta^T K_\alpha^{-1} \mathbf{r}_\theta - \frac{1}{2} \log \det K_\alpha - \frac{N}{2} \log(2\pi)$$

**b**

## Scaling to large datasets



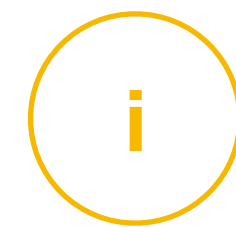
## **Scaling to large datasets**



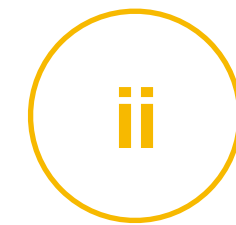
**a** **Approximation**

**b** **Structure**

# Approximation methods



**Subsample**



**Sparsity**



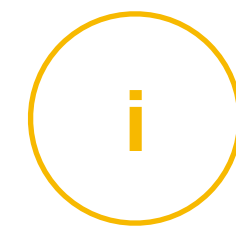
**Low-rank approximations**

(see HODLR solver in george)

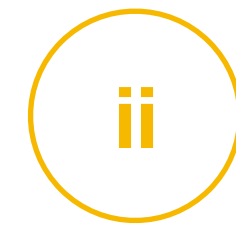


**etc.**

# Structured models



**Kronecker products**



**Evenly sampled data**

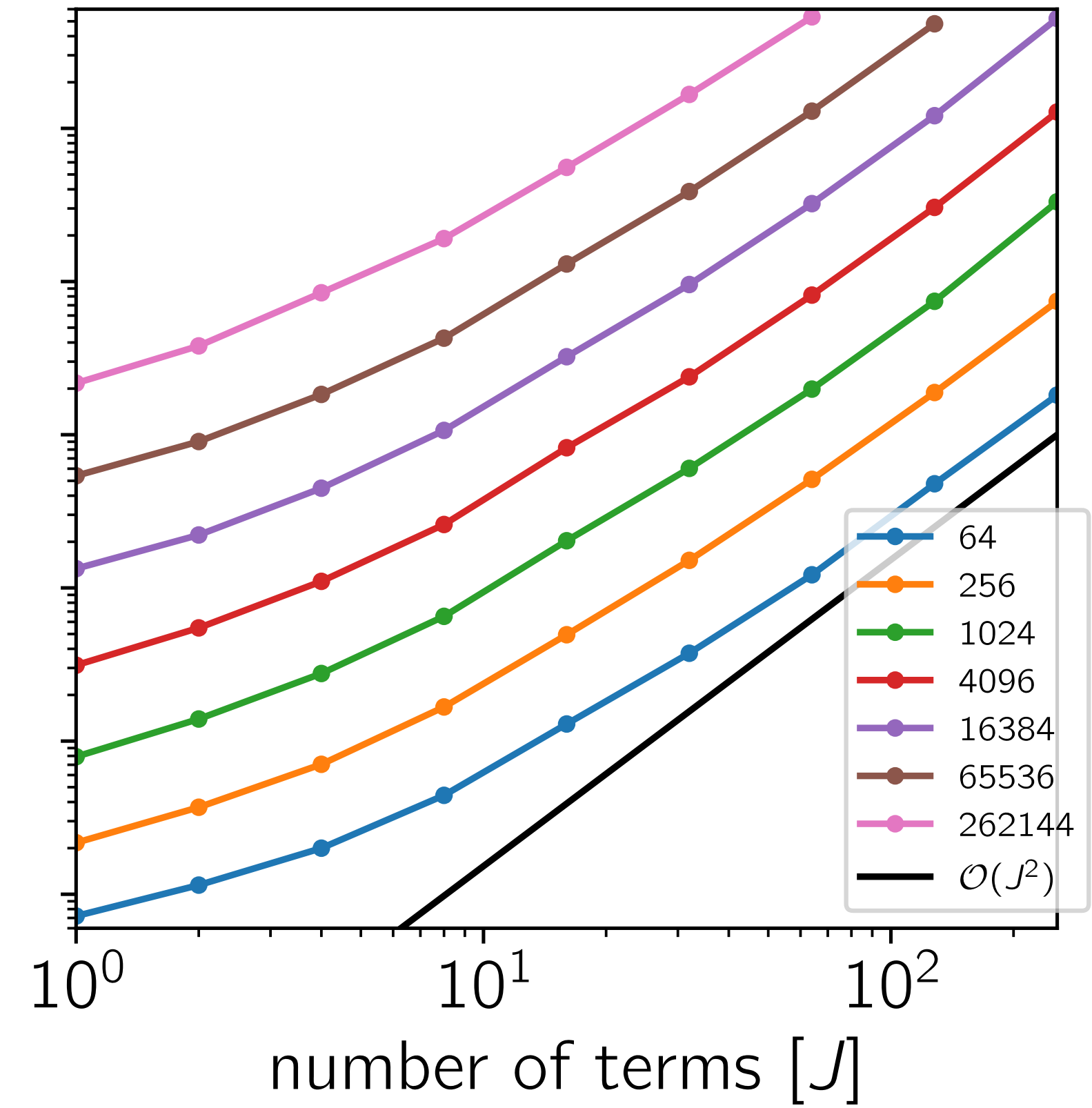
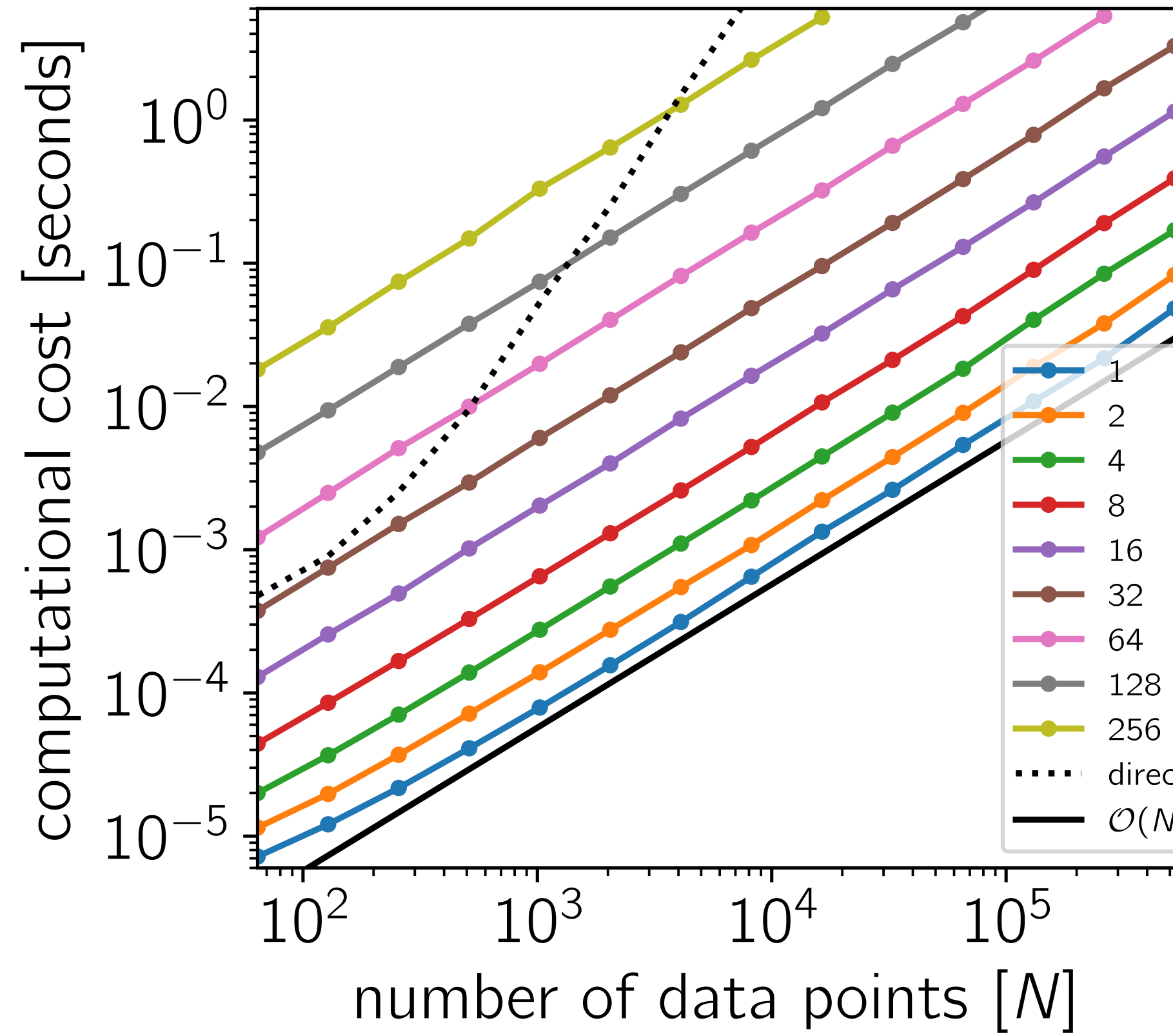


**Semi-separable kernels**  
(see celerite)



**etc.**





5

**Recap**

if there is **correlated noise** (instrumental or astrophysical)  
in your data\*, try a **Gaussian process**:

$$\log p(\{y_n\} | \theta, \alpha) = -\frac{1}{2} \mathbf{r}_\theta^T K_\alpha^{-1} \mathbf{r}_\theta - \frac{1}{2} \log \det K_\alpha - \frac{N}{2} \log(2\pi)$$

to do this in **Python**, try:

```
import george
```

```
george.readthedocs.io
```

\* *Hint: there is!*

# Resources

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a practical introduction to

*Gaussian Processes*

for astronomy

***Dan Foreman-Mackey***

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