

# A DEMPSTER-SHAFER BAYESIAN SOLUTION TO THE BANFF A1 CHALLENGE

Paul Edlefsen

August 1, 2007

## THE THREE POISSON MODEL

$$n \sim \text{Pois}(\epsilon s + b)$$

$$y \sim \text{Pois}(t b)$$

$$z \sim \text{Pois}(u \epsilon)$$

# OVERVIEW

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- ▶ The Three Poisson Model

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- ▶ The Plausibility Transform

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- ▶ The Plausibility Transform
- ▶ An Analytical Form of the Solution

# THE THREE POISSON MODEL

$$n \sim \text{Pois}(\epsilon s + b)$$

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The parameter of interest is  $S$ .

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$b$  and  $\epsilon$  are nuisance parameters.

## THE THREE POISSON MODEL

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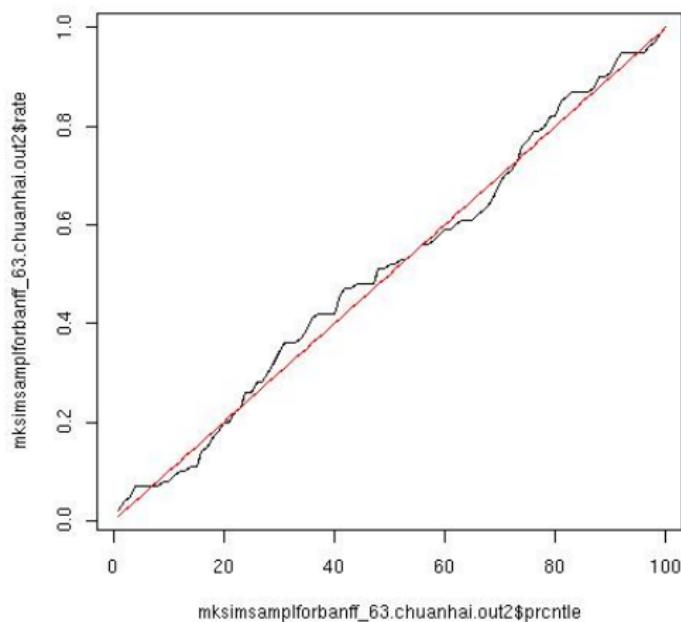
$$y_i \sim \text{Pois}(t_i b_i)$$

$$z_i \sim \text{Pois}(u_i \epsilon_i)$$

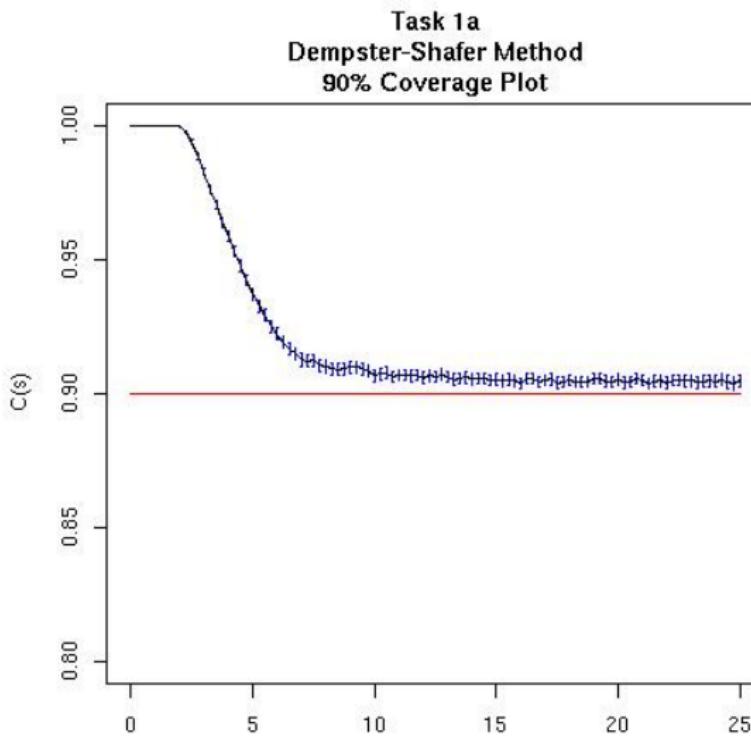
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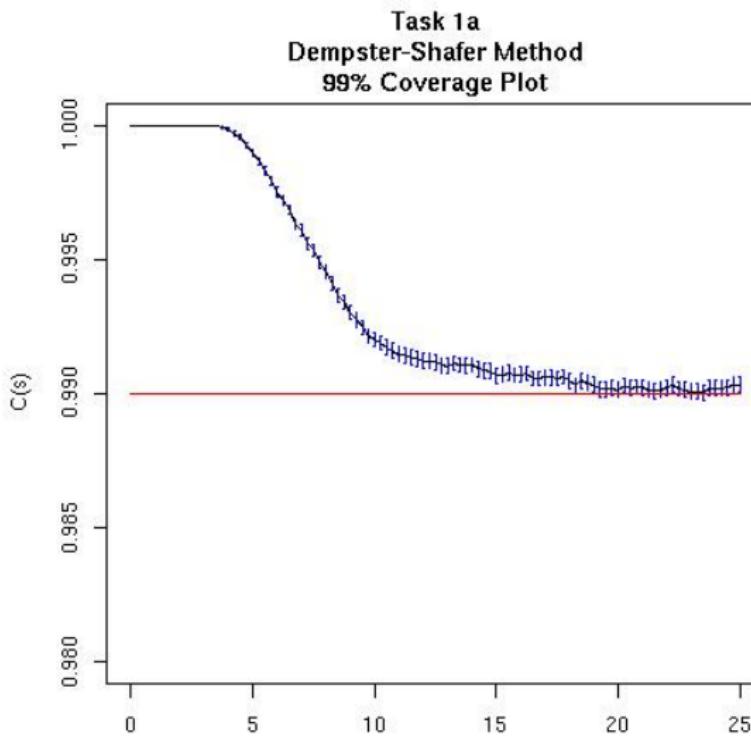
# SOME RESULTS



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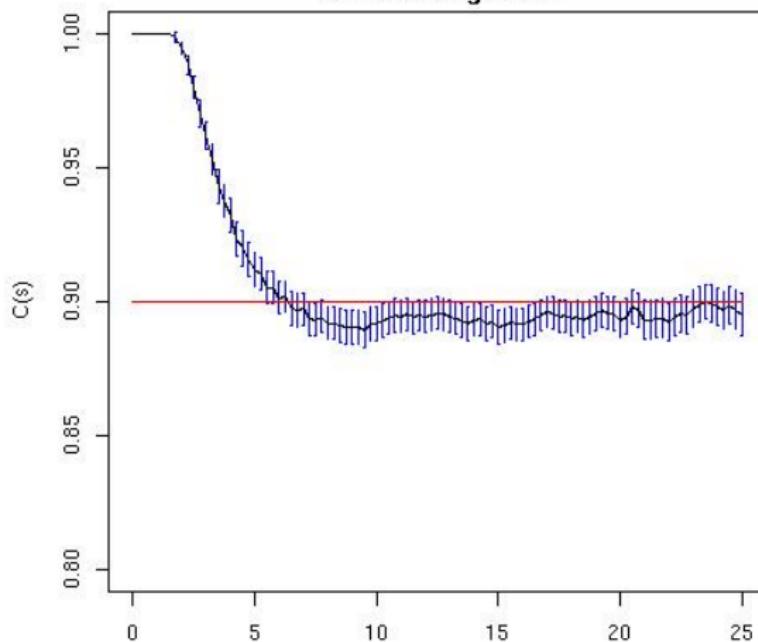


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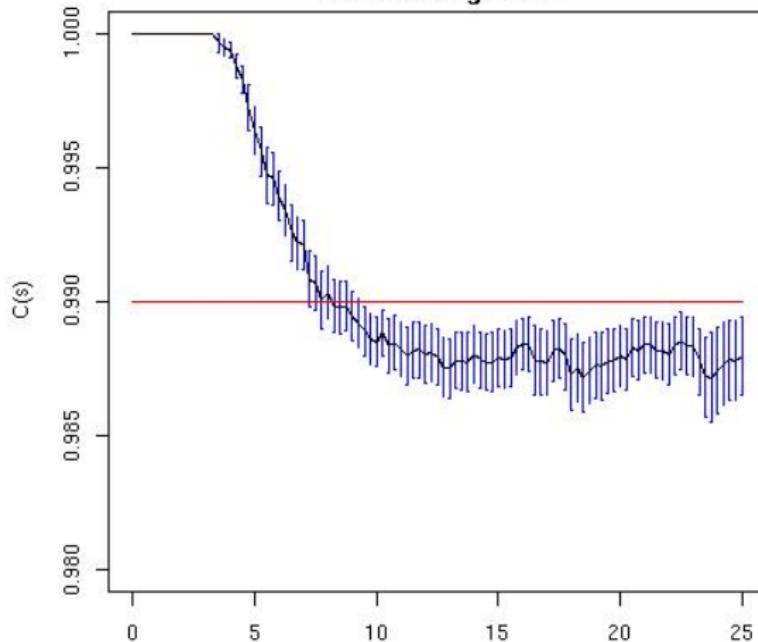
# SOME RESULTS

Task 2  
Dempster-Shafer Method  
90% Coverage Plot



# SOME RESULTS

Task 2  
Dempster-Shafer Method  
99% Coverage Plot



# THE POISSON DSM

$$K \sim \text{Pois}(\lambda)$$

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$$\Lambda_l \leq \lambda \leq \Lambda_u$$

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$$\begin{aligned} K &\sim \text{Pois}(\lambda) \\ \Lambda_l \leq \lambda \leq \Lambda_u \\ \Lambda_l &\sim \text{Gamma}(k) \end{aligned}$$

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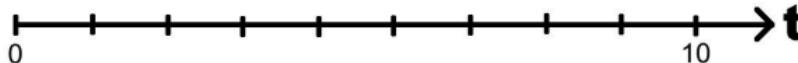
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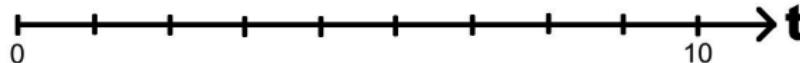
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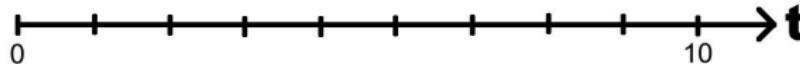
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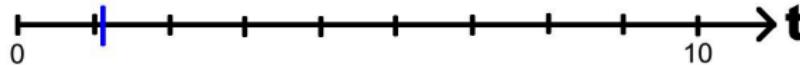
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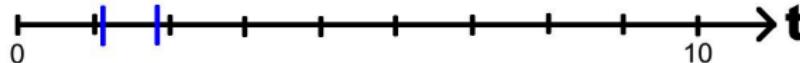
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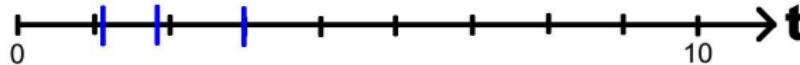
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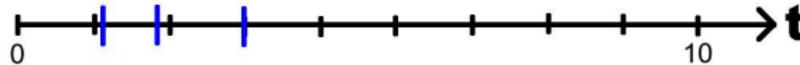
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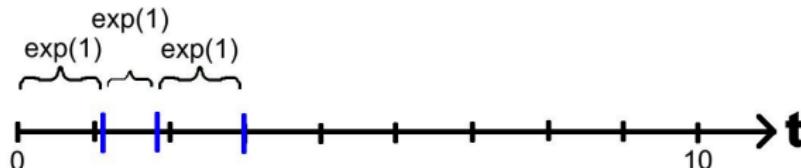
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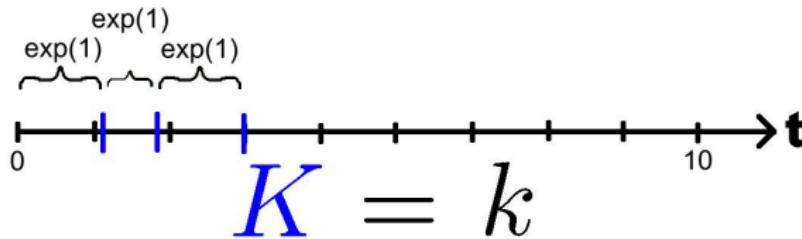
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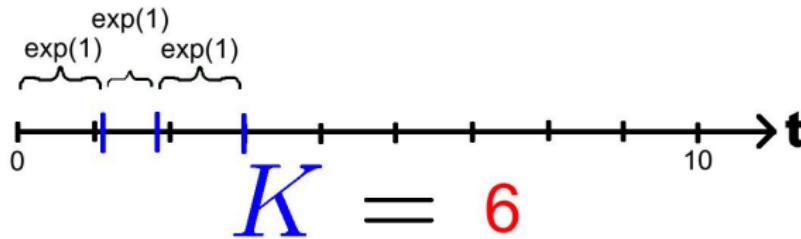
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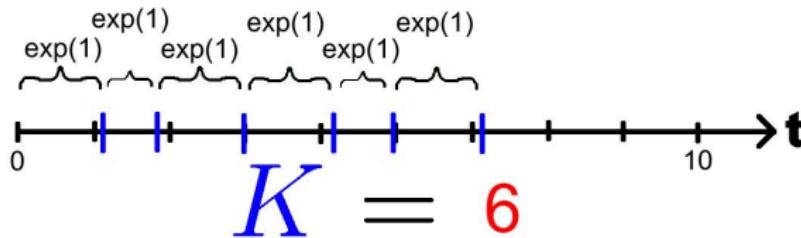
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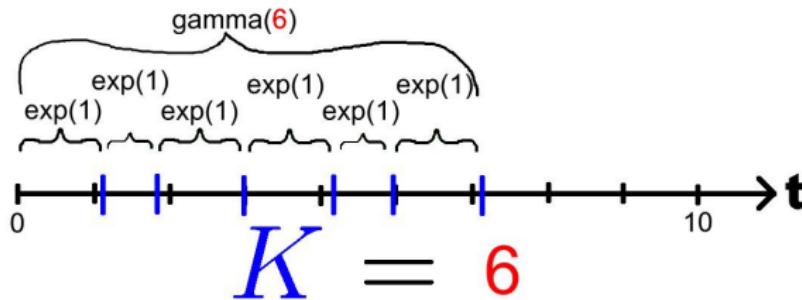
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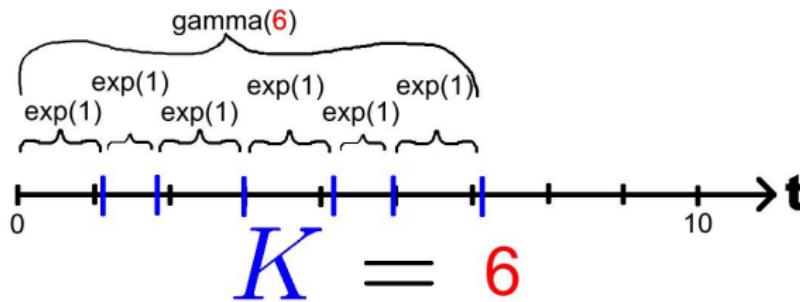
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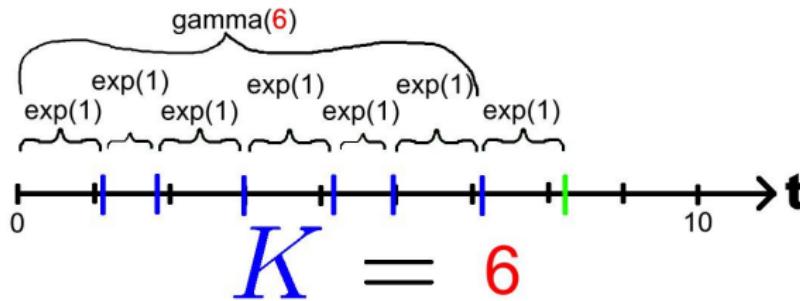
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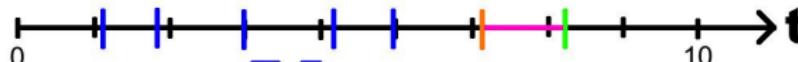
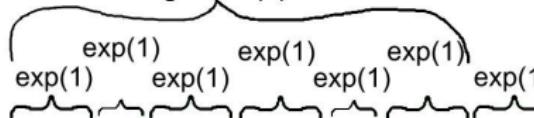
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$$K = 6$$

## THE THREE POISSON MODEL

The parameter of interest is  $\textcolor{red}{s}$ .

$$n_i \sim \text{Pois}(\textcolor{green}{\epsilon}_i \textcolor{red}{s} + \textcolor{blue}{b}_i)$$

$$y_i \sim \text{Pois}(t_i \textcolor{blue}{b}_i)$$

$$z_i \sim \text{Pois}(u_i \textcolor{green}{\epsilon}_i)$$

$\textcolor{blue}{b}$  and  $\textcolor{green}{\epsilon}$  are nuisance parameters.

$i$  is the channel, in 1..n.

## THE THREE POISSON MODEL DSM

The parameter of interest is  $s$ .

$$n_i \sim \text{Pois}(\epsilon_i s + b_i)$$

$$y_i \sim \text{Pois}(t_i b_i)$$

$$\mathbf{z}_l^i \leq u_i \epsilon_i \leq \mathbf{z}_u^i$$

$b$  and  $\epsilon$  are nuisance parameters.

$i$  is the channel, in 1..n.

## THE THREE POISSON MODEL DSM

The parameter of interest is  $s$ .

$$n_i \sim \text{Pois}(\epsilon_i s + b_i)$$

$$\mathbf{Y}_l^i \leq t_i b_i \leq \mathbf{Y}_u^i$$

$$\mathbf{Z}_l^i \leq u_i \epsilon_i \leq \mathbf{Z}_u^i$$

$b$  and  $\epsilon$  are nuisance parameters.

$i$  is the channel, in 1..n.

## THE THREE POISSON MODEL DSM

The parameter of interest is  $s$ .

$$\mathbf{N}_l^i \leq (\epsilon_i s + b_i) \leq \mathbf{N}_u^i$$

$$\mathbf{Y}_l^i \leq t_i b_i \leq \mathbf{Y}_u^i$$

$$\mathbf{Z}_l^i \leq u_i \epsilon_i \leq \mathbf{Z}_u^i$$

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The parameter of interest is  $s$ .

$$\mathbf{N}_l^i \leq (\epsilon_i s + b_i) \leq \mathbf{N}_u^i$$

$$\mathbf{Y}_l^i \leq t_i b_i \leq \mathbf{Y}_u^i$$

$$\frac{1}{u_i} \mathbf{Z}_l^i \leq \epsilon_i \leq \frac{1}{u_i} \mathbf{Z}_u^i$$

## THE THREE POISSON MODEL DSM

The parameter of interest is  $\textcolor{red}{S}$ .

$$\mathbf{N}_{\textcolor{brown}{l}}^i \leq (\textcolor{green}{\epsilon}_i \textcolor{red}{s} + \textcolor{blue}{b}_i) \leq \mathbf{N}_{\textcolor{green}{u}}^i$$

$$\frac{1}{t_i} \mathbf{Y}_{\textcolor{brown}{l}}^i \leq \textcolor{blue}{b}_i \leq \frac{1}{t_i} \mathbf{Y}_{\textcolor{green}{u}}^i$$

$$\frac{1}{u_i} \mathbf{Z}_{\textcolor{brown}{l}}^i \leq \textcolor{green}{\epsilon}_i \leq \frac{1}{u_i} \mathbf{Z}_{\textcolor{green}{u}}^i$$

## THE THREE POISSON MODEL DSM

The parameter of interest is  $s$ .

$$\mathbf{N}_l^i \leq (\epsilon_i s + b_i) \leq \mathbf{N}_u^i$$

$$\mathbf{N}_l^i - \frac{1}{t_i} \mathbf{Y}_u^i \leq \epsilon_i s \leq \mathbf{N}_u^i - \frac{1}{t_i} \mathbf{Y}_l^i$$

$$\frac{1}{u_i} \mathbf{Z}_l^i \leq \epsilon_i \leq \frac{1}{u_i} \mathbf{Z}_u^i$$

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$$\mathbf{N}_l^i - \frac{1}{t_i} \mathbf{Y}_u^i \leq \epsilon_i s \leq \mathbf{N}_u^i - \frac{1}{t_i} \mathbf{Y}_l^i$$

$$\frac{\mathbf{N}_l^i - \frac{1}{t_i} \mathbf{Y}_u^i}{\frac{1}{u_i} \mathbf{Z}_u^i} \leq s \leq \frac{\mathbf{N}_u^i - \frac{1}{t_i} \mathbf{Y}_l^i}{\frac{1}{u_i} \mathbf{Z}_l^i}$$

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$$\mathcal{S} \geq 0$$

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$$\mathcal{s} \geq 0$$

$$\mathcal{s}_l \leq \mathcal{s} \leq \frac{\mathbf{N}_u^i - \frac{1}{t_i} \mathbf{Y}_l^i}{\frac{1}{u_i} \mathbf{Z}_l^i}$$

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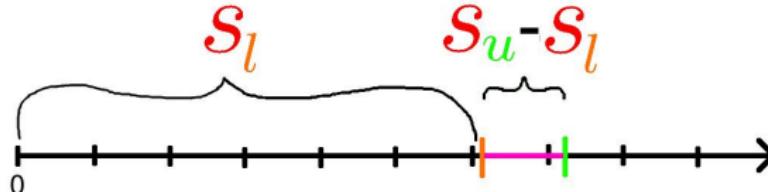
$$s \geq 0$$

$$s_l \leq s \leq s_u$$

# THE PLAUSIBILITY TRANSFORM

$$s_l \leq s \leq s_u$$

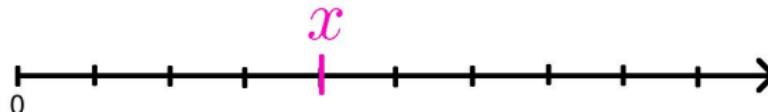
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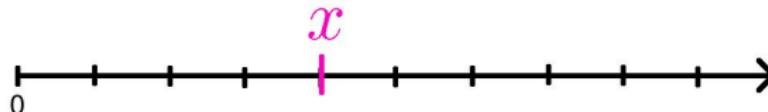
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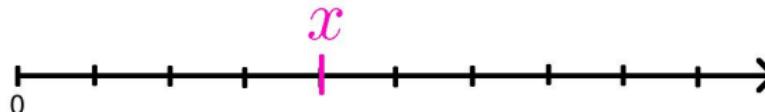
$$\text{Plaus}(\{\textcolor{magenta}{x}\}) = \mathbb{P}(\textcolor{magenta}{x} \in (\mathbf{S}_l, \mathbf{S}_u))$$



## THE PLAUSIBILITY TRANSFORM

$$\text{Plaus}(\{\textcolor{magenta}{x}\}) = \mathbb{P}(\textcolor{magenta}{x} \in (\mathbf{S}_l, \mathbf{S}_u))$$

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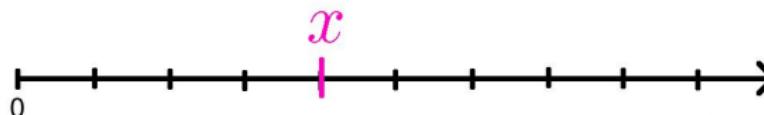


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$$= 1 - (F_{\mathbf{S}_u}(\textcolor{magenta}{x}) + (1 - F_{\mathbf{S}_l}(\textcolor{magenta}{x})))$$



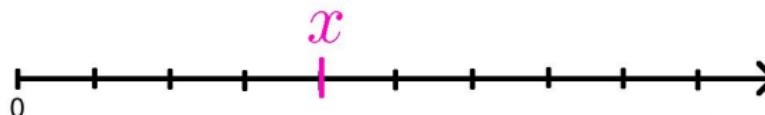
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$$= F_{\mathbf{S}_l}(\textcolor{magenta}{x}) - F_{\mathbf{S}_u}(\textcolor{magenta}{x})$$



## ANALYTICAL FORM

From these and from the additional constraint that  $s \geq 0$ , we see that

$$\mathbf{S}_l^i = \frac{\max(0, \mathbf{N}_l^i - \frac{1}{t} \mathbf{Y}_u^i)}{\frac{1}{u} \mathbf{Z}_u^i} \text{ and}$$

$$\mathbf{S}_u^i = \frac{\mathbf{N}_u^i - \frac{1}{t} \mathbf{Y}_l^i}{\frac{1}{u} \mathbf{Z}_l^i}$$

in the equation  $\mathbf{S}_l^i \leq s \leq \mathbf{S}_u^i$ .

## ANALYTICAL FORM

Thus, if we ignore (momentarily) the constraint that  $s \geq 0$ , we may characterize the CDFs of  $S_I^i$  and  $S_u^i$  as

$$F_{S_I^i}^*(x) = \mathbb{P}\left(\frac{\mathbf{N}_I^i - \frac{1}{t_i} \mathbf{Y}_u^i}{\frac{1}{u_i} \mathbf{Z}_u^i} \leq x\right) \text{ and}$$

$$F_{S_u^i}^*(x) = \mathbb{P}\left(\frac{\mathbf{N}_u^i - \frac{1}{t_i} \mathbf{Y}_I^i}{\frac{1}{u_i} \mathbf{Z}_I^i} \leq x\right).$$

# ANALYTICAL FORM

Rearranging, we may write this as

$$F_{S_i^i}^*(x) = \mathbb{P}(N_I^i \leq \frac{1}{t_i} Y_u^i + \frac{x}{u_i} Z_u^i) \text{ and}$$

$$F_{S_u^i}^*(x) = \mathbb{P}(N_u^i \leq \frac{1}{t_i} Y_I^i + \frac{x}{u_i} Z_I^i).$$

# UNNORMALIZED CDFs

We will see that these can be written in terms of the Beta distribution as

$$F_{S_u^i}^*(x) = 1 - pBeta\left(\frac{u_i}{u_i + x}, z_i, n_i + 1\right) +$$

$$\int_0^{\frac{u_i}{u_i+x}} pBeta\left(\frac{1}{1+t_i-\frac{\gamma}{u_i+x}}, z_i + n_i + 1, y_i\right) dBeta(\gamma, z_i, n_i + 1) d\gamma,$$

and

$$F_{S_l^i}^*(x) = 1 - pBeta\left(\frac{u_i}{u_i + x}, z_i + 1, n_i\right) +$$

$$\int_0^{\frac{u_i}{u_i+x}} pBeta\left(\frac{1}{1+t_i-\frac{\gamma}{u_i+x}}, z_i + 1 + n_i, y_i + 1\right) dBeta(\gamma, z_i + 1, n_i) d\gamma.$$

# ANALYTICAL FORM

We are ultimately interested in the normalized quantities

$$F_{S'_l}(x) = \frac{F^*_{S'_l} - \mathbb{P}(S'_l < 0)}{1 - \mathbb{P}(S'_l < 0)} \text{ and}$$
$$F_{S'_u}(x) = \frac{F^*_{S'_u} - \mathbb{P}(S'_u < 0)}{1 - \mathbb{P}(S'_u < 0)},$$

where we condition on the upper end of the interval,  $S'_u$ , being non-negative.

# ANALYTICAL FORM

Since this condition is met whenever  $\mathbf{N}_u^i \geq \frac{1}{t_i} \mathbf{Y}_l^i$ , we have

$$\begin{aligned} F_{S_l^i}(x) &= \frac{\mathbb{P}(\mathbf{N}_l^i \leq \frac{1}{t_i} \mathbf{Y}_u^i + \frac{x}{u_i} \mathbf{Z}_u^i) - \mathbb{P}(\mathbf{N}_u^i < \frac{1}{t_i} \mathbf{Y}_l^i)}{1 - \mathbb{P}(\mathbf{N}_u^i < \frac{1}{t_i} \mathbf{Y}_l^i)} \text{ and} \\ F_{S_u^i}(x) &= \frac{\mathbb{P}(\mathbf{N}_u^i \leq \frac{1}{t_i} \mathbf{Y}_l^i + \frac{x}{u_i} \mathbf{Z}_l^i) - \mathbb{P}(\mathbf{N}_u^i < \frac{1}{t_i} \mathbf{Y}_l^i)}{1 - \mathbb{P}(\mathbf{N}_u^i < \frac{1}{t_i} \mathbf{Y}_l^i)}. \end{aligned} \quad (1)$$

# CONFLICT

The constraint  $s \geq 0$  is violated whenever  $\mathbf{N}_u^i < \frac{1}{t_i} \mathbf{Y}_l^i$ , so the probability of conflict is  $\mathbb{P}(\mathbf{N}_u^i < \frac{1}{t_i} \mathbf{Y}_l^i)$ .

# CONFLICT

Since  $\mathbf{N}_u^i$  and  $\mathbf{Y}_I^i$  are gamma-distributed with unit scale, and with shape parameters  $(n_i + 1)$  and  $y_i$ , respectively,

$$\frac{\mathbf{Y}_I^i}{\mathbf{Y}_I^i + \mathbf{N}_u^i} \sim \text{Beta}(y_i, n_i + 1).$$

# CONFLICT

We can thus rearrange the probability of conflict to utilize the CDF of a beta:

$$\begin{aligned}\mathbb{P}(\mathbf{N}_u^i < \frac{1}{t_i} \mathbf{Y}_l^i) &= \mathbb{P}\left(\frac{\mathbf{N}_u^i}{\mathbf{N}_u^i + \mathbf{Y}_l^i} < \frac{\frac{1}{t_i} \mathbf{Y}_l^i}{\mathbf{N}_u^i + \mathbf{Y}_l^i}\right) \\ &= \mathbb{P}\left(1 - \frac{\mathbf{Y}_l^i}{\mathbf{N}_u^i + \mathbf{Y}_l^i} < \frac{\frac{1}{t_i} \mathbf{Y}_l^i}{\mathbf{N}_u^i + \mathbf{Y}_l^i}\right) \\ &= \mathbb{P}\left(\frac{\left(\frac{1}{t_i} + 1\right) \mathbf{Y}_l^i}{\mathbf{N}_u^i + \mathbf{Y}_l^i} > 1\right) \\ &= \mathbb{P}\left(\frac{\mathbf{Y}_l^i}{\mathbf{N}_u^i + \mathbf{Y}_l^i} > \frac{b}{b+1}\right).\end{aligned}$$

# CONFLICT

So the probability of conflict is

$$\mathbb{P}(\mathbf{N}_u^i < \frac{1}{t_i} \mathbf{Y}_l^i) = 1 - \text{pBeta}\left(\frac{t_i}{t_i + 1}, y_i, n_i + 1\right), \quad (2)$$

where  $\text{pBeta}(\cdot, \alpha, \beta)$  is the CDF of a beta with parameters  $\alpha$  and  $\beta$ .

# UNNORMALIZED CDFs

We now use similar techniques to characterize the unnormalized components  $F_{S_u^i}^*(\cdot)$  and  $F_{S_u^i}^*(\cdot)$ . Consider first

$$F_{S_u^i}^*(x) = \mathbb{P}(N_u^i \leq \frac{1}{t_i} \mathbf{Y}_I^i + \frac{x}{u_i} \mathbf{Z}_I^i).$$

## UNNORMALIZED CDFs

Noting that gamma random variables are never negative, we may apply the law of total probability to rewrite this as

$$\begin{aligned}
 F_{S_u^i}^*(x) &= \mathbb{P}(N_u^i \leq \frac{1}{t_i} Y_I^i + \frac{x}{u_i} Z_I^i \text{ and } N_u^i \leq \frac{x}{u_i} Z_I^i) + \mathbb{P}(N_u^i \leq \frac{1}{t_i} Y_I^i + \frac{x}{u_i} Z_I^i \\
 &= \mathbb{P}(N_u^i \leq \frac{x}{u_i} Z_I^i) + \mathbb{P}(N_u^i \leq \frac{1}{t_i} Y_I^i + \frac{x}{u_i} Z_I^i \text{ and } N_u^i > \frac{x}{u_i} Z_I^i) \\
 &= \mathbb{P}\left(\frac{Z_I^i}{Z_I^i + N_u^i} > \frac{u_i}{u_i + x}\right) + \mathbb{P}(N_u^i \leq \frac{1}{t_i} Y_I^i + \frac{x}{u_i} Z_I^i \text{ and } N_u^i > \frac{x}{u_i} Z_I^i) \\
 &= 1 - \text{pBeta}\left(\frac{u_i}{u_i + x}, z_i, n_i + 1\right) + \mathbb{P}(N_u^i \leq \frac{1}{t_i} Y_I^i + \frac{x}{u_i} Z_I^i \text{ and } N_u^i >
 \end{aligned}$$

by an argument similar to that used in deriving the Beta CDF representation for the probability of conflict.

## UNNORMALIZED CDFs

The latter part may be simplified also. We can rewrite  $\mathbf{N}_u^i - \frac{x}{u_i} \mathbf{Z}_I^i$

as  $(1 - \frac{\mathbf{Z}_I^i + \mathbf{N}_u^i}{\frac{u_i}{u_i+x}})(\mathbf{Z}_I^i + \mathbf{N}_u^i)$ , since

$$\begin{aligned}
 (1 - \frac{\mathbf{Z}_I^i + \mathbf{N}_u^i}{\frac{u_i}{u_i+x}})(\mathbf{Z}_I^i + \mathbf{N}_u^i) &= (\mathbf{Z}_I^i + \mathbf{N}_u^i) - \frac{\mathbf{Z}_I^i}{\frac{u_i}{u_i+x}} \\
 &= (\mathbf{Z}_I^i + \mathbf{N}_u^i) - \frac{\mathbf{Z}_I^i}{\frac{1}{1 + \frac{x}{u_i}}} \\
 &= (\mathbf{Z}_I^i + \mathbf{N}_u^i) - \mathbf{Z}_I^i(1 + \frac{x}{u_i}) \\
 &= \mathbf{N}_u^i - \frac{x}{u_i} \mathbf{Z}_I^i.
 \end{aligned}$$

# UNNORMALIZED CDFs

This leads to

$$\begin{aligned} & \mathbb{P}(\mathbf{N}_u^i \leq \frac{1}{t_i} \mathbf{Y}_I^i + \frac{x}{u_i} \mathbf{Z}_I^i \text{ and } \mathbf{N}_u^i > \frac{x}{u_i} \mathbf{Z}_I^i) \\ &= \mathbb{P}\left(\frac{1}{t_i} \mathbf{Y}_I^i \geq \left(1 - \frac{\mathbf{Z}_I^i + \mathbf{N}_u^i}{\frac{u_i}{u_i+x}}\right)(\mathbf{Z}_I^i + \mathbf{N}_u^i) \text{ and } \mathbf{N}_u^i > \frac{x}{u_i} \mathbf{Z}_I^i\right). \quad (3) \end{aligned}$$

## UNNORMALIZED CDFs

Recognizing again that the event that  $\mathbf{N}_u^i > \frac{x}{u_i} \mathbf{Z}_l^i$  is the same as the event that  $\frac{\mathbf{Z}_l^i}{\mathbf{Z}_l^i + \mathbf{N}_u^i} \leq \frac{u_i}{u_i + x}$ , the complicated probability in (3) may be simplified by conditioning on the value of  $\frac{\mathbf{Z}_l^i}{\mathbf{Z}_l^i + \mathbf{N}_u^i} = \gamma$ :

$$\mathbb{P}(\mathbf{N}_u^i \leq \frac{1}{t_i} \mathbf{Y}_l^i + \frac{x}{u_i} \mathbf{Z}_l^i \text{ and } \mathbf{N}_u^i > \frac{x}{u_i} \mathbf{Z}_l^i)$$

$$= \mathbb{P}\left(\frac{1}{t_i} \mathbf{Y}_l^i \geq \left(1 - \frac{\mathbf{Z}_l^i}{\frac{u_i}{u_i + x} (\mathbf{Z}_l^i + \mathbf{N}_u^i)}\right) (\mathbf{Z}_l^i + \mathbf{N}_u^i) \text{ and } \mathbf{N}_u^i > \frac{x}{u_i} \mathbf{Z}_l^i\right)$$

$$= \mathbb{P}\left(\frac{1}{t_i} \mathbf{Y}_l^i \geq \left(1 - \frac{\mathbf{Z}_l^i}{\frac{u_i}{u_i + x}}\right) (\mathbf{Z}_l^i + \mathbf{N}_u^i) \text{ and } \frac{\mathbf{Z}_l^i}{\mathbf{Z}_l^i + \mathbf{N}_u^i} \leq \frac{u_i}{u_i + x}\right)$$

$$= \int_0^{\frac{u_i}{u_i + x}} \mathbb{P}\left(\frac{1}{t_i} \mathbf{Y}_l^i \geq \left(1 - \frac{\gamma}{\frac{u_i}{u_i + x}}\right) (\mathbf{Z}_l^i + \mathbf{N}_u^i) \middle| \frac{\mathbf{Z}_l^i}{\mathbf{Z}_l^i + \mathbf{N}_u^i} = \gamma\right) d\mathbb{P}\left(\frac{\mathbf{Z}_l^i}{\mathbf{Z}_l^i + \mathbf{N}_u^i} < \gamma\right)$$

# UNNORMALIZED CDFs

and since  $(\mathbf{Z}_I^i + \mathbf{N}_u^i) \perp \frac{\mathbf{Z}_I^i}{\mathbf{Z}_I^i + \mathbf{N}_u^i}$ , we get

$$\mathbb{P}(\mathbf{N}_u^i \leq \frac{1}{t_i} \mathbf{Y}_I^i + \frac{x}{u_i} \mathbf{Z}_I^i \text{ and } \mathbf{N}_u^i > \frac{x}{u_i} \mathbf{Z}_I^i)$$

$$= \int_0^{\frac{u_i+x}{u_i+x}} \text{pBeta}\left(\frac{1}{1+t_i - \frac{\gamma}{\frac{u_i}{u_i+x}}}, z_i + n_i + 1, y_i\right) \text{dBeta}(\gamma, z_i, n_i + 1) d\gamma,$$

where  $\text{dBeta}(\cdot, \alpha, \beta)$  is the pdf of a beta with parameters  $\alpha$  and  $\beta$ . Note that this can be approximated to any desired precision by a straightforward numerical integration.

# UNNORMALIZED CDFs

Thus we have

$$F_{S_u^i}^*(x) = 1 - \text{pBeta}\left(\frac{u_i}{u_i + x}, z_i, n_i + 1\right) +$$

$$\int_0^{\frac{u_i}{u_i+x}} \text{pBeta}\left(\frac{1}{1+t_i-\frac{\gamma}{u_i+x}}, z_i + n_i + 1, y_i\right) d\text{Beta}(\gamma, z_i, n_i + 1) d\gamma, \quad (4)$$

and, by an analogous derivation,

$$F_{S_l^i}^*(x) = 1 - \text{pBeta}\left(\frac{u_i}{u_i + x}, z_i + 1, n_i\right) +$$

$$\int_0^{\frac{u_i}{u_i+x}} \text{pBeta}\left(\frac{1}{1+t_i-\frac{\gamma}{u_i+x}}, z_i + 1 + n_i, y_i + 1\right) d\text{Beta}(\gamma, z_i + 1, n_i) d\gamma. \quad (5)$$

## NORMALIZED CDFs

Plugging equations (4), (5), and (2) into equation (1) concludes the derivation, the CDFs of the upper and lower bounds on  $\mathbf{S}$  induced by the evidence from a single channel. Combining evidence across channels and normalizing yields the D-S Bayesian posterior

$$f_{\mathbf{S}}(x) = \frac{\prod_{i=1}^n (F_{\mathbf{S}_l^i}(x) - F_{\mathbf{S}_u^i}(x))}{\int_{x=0}^{\infty} \prod_{i=1}^n (F_{\mathbf{S}_l^i}(x) - F_{\mathbf{S}_u^i}(x))}. \quad (6)$$

## SPECIAL CASES

The above derivation for  $r_i(\cdot)$  assumed that  $n_i$ ,  $y_i$ , and  $z_i$  are all positive. In the event that  $n_i = 0$ ,  $\mathbf{S}_i^j = 0$  and  $F_{\mathbf{S}_i^j}(s) = 1 \forall x \geq 0$ .

When  $y_i = 0$ , there is no conflict, and

$F_{\mathbf{S}_u^i}^*(x) = 1 - \text{pBeta}\left(\frac{u_i}{u_i+x}, z_i, n_i + 1\right)$ , unless  $z_i = 0$ . Whenever

$z_i = 0$ ,  $\mathbf{S}_u^i = \infty$ , so  $F_{\mathbf{S}_u^i}(x) = 0 \forall x < \infty$ .

Note that when  $n_i = z_i = 0$ , we learn nothing new about  $s$ .