

KATY MCKEOUGH

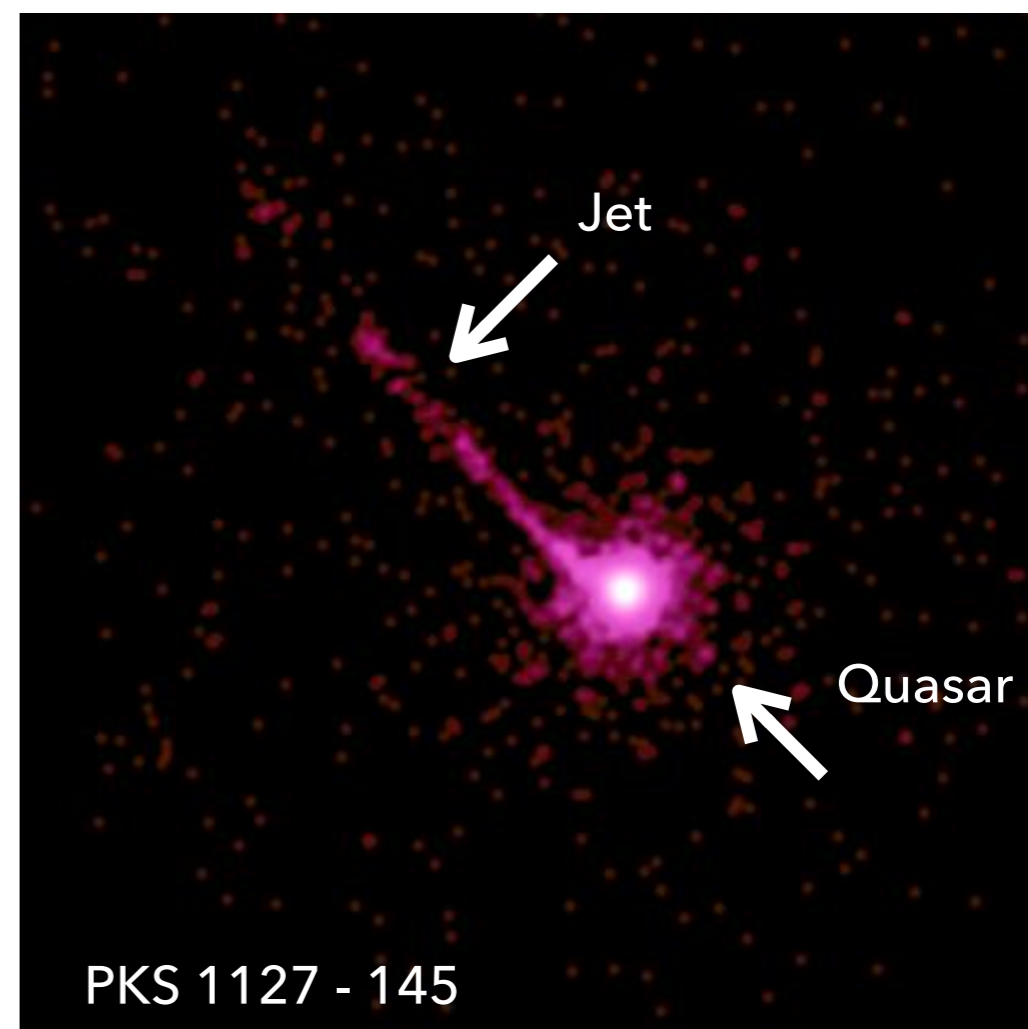
CHASC ASTRO-STATISTICS

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**DEFINING REGIONS THAT CONTAIN COMPLEX
ASTRONOMICAL STRUCTURES**

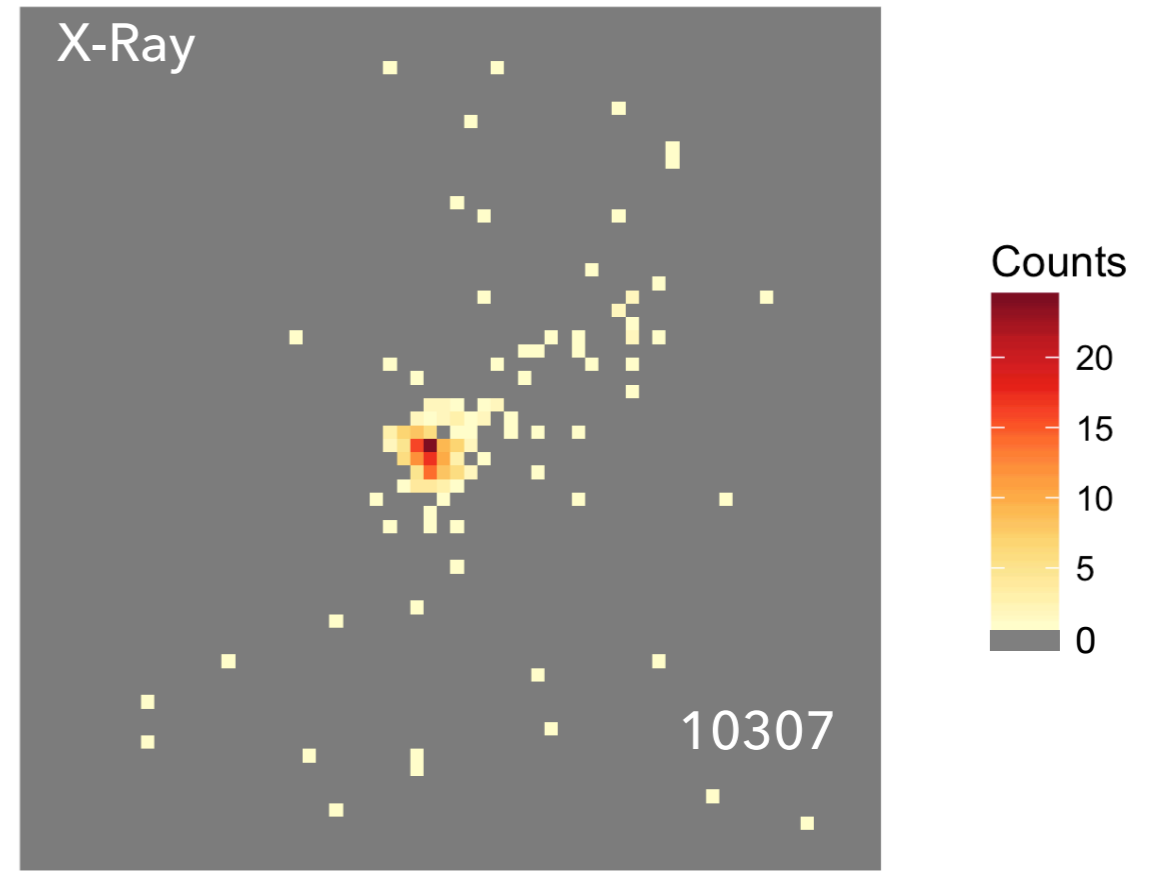
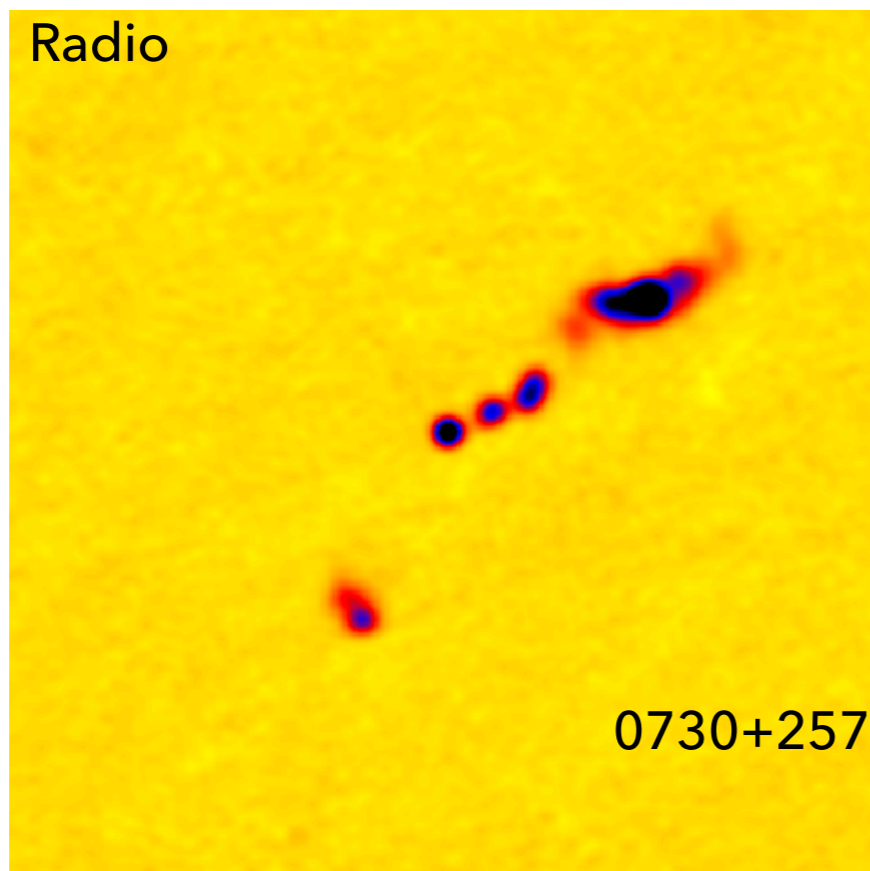
SCIENTIFIC MOTIVATION

- ▶ We are interested in defining an outline around extragalactic jets coming from quasars at high redshift ($z > 2.1$) in X-ray images
- ▶ Defining this boundary is important for accurate luminosity and flux calculations.
- ▶ Detecting jets is difficult because they are diffuse sources (no edges, or center) and dim compared to the quasar.
- ▶ Images of high redshift jets are of low resolution and few X-ray photons



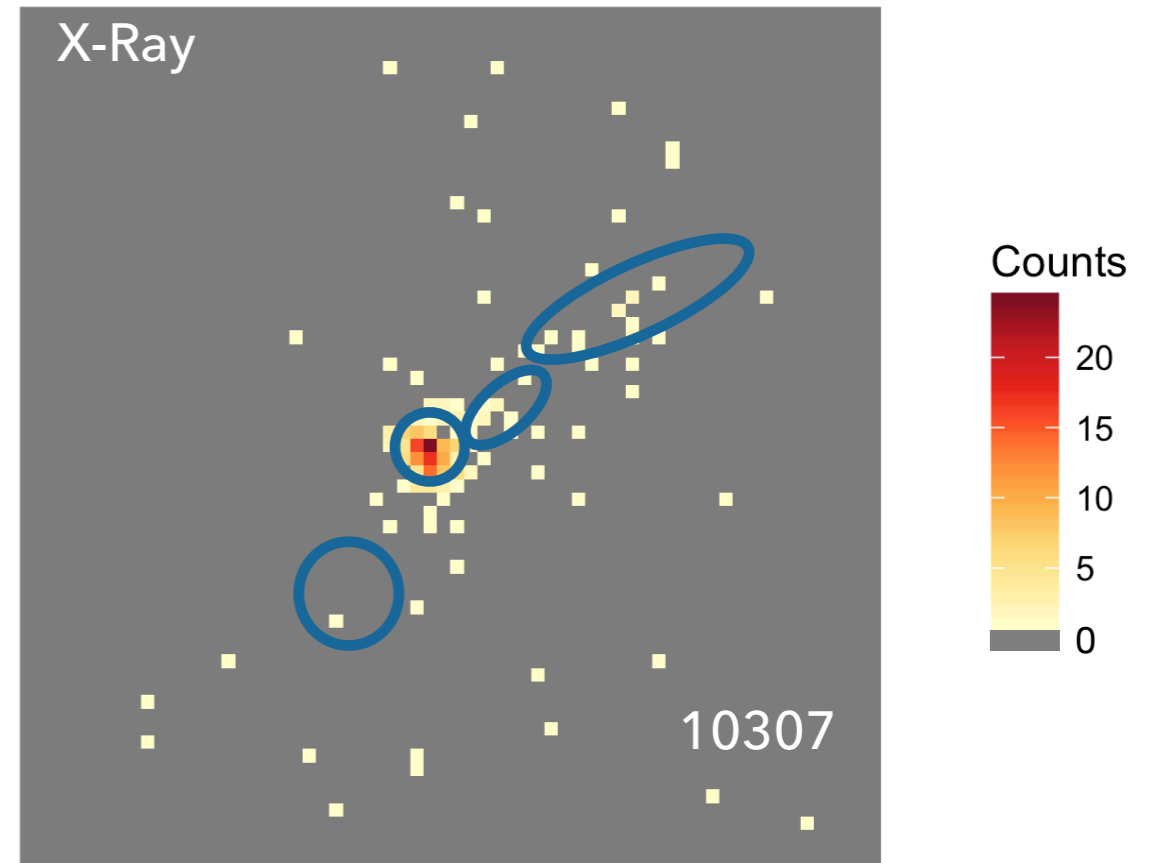
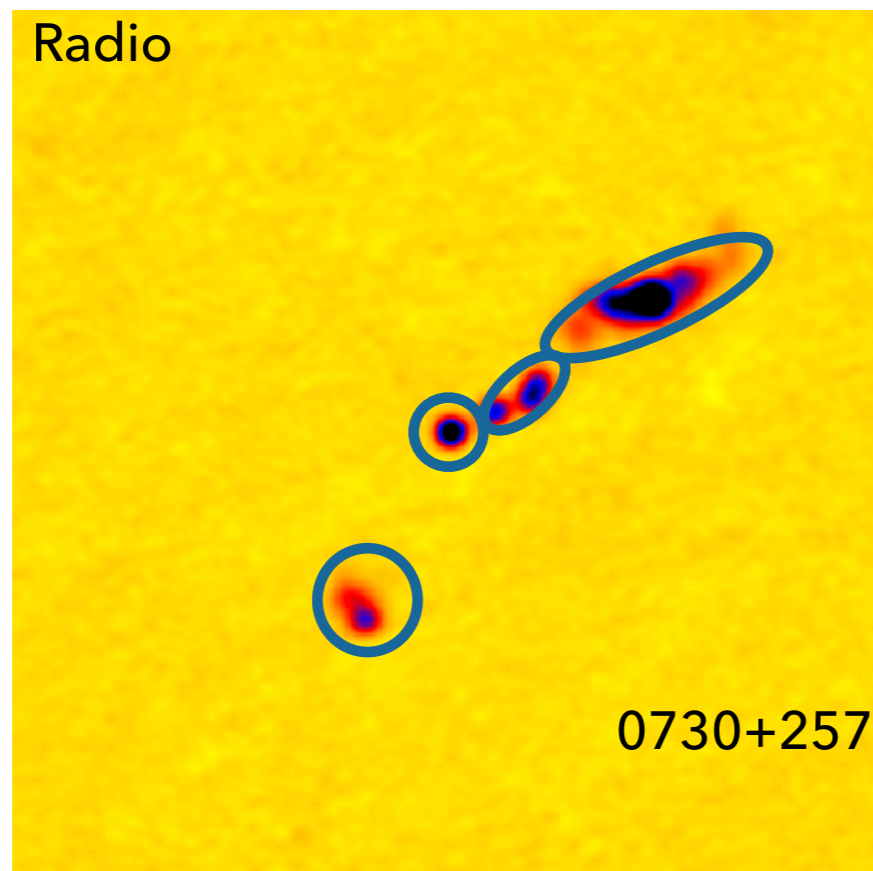
OBSERVATIONAL DATA

- ▶ Chandra X-ray Observatory - ACIS
- ▶ 64 x 64 or 128 x 128 pixel image centered on quasar
- ▶ High to intermediate redshift ($2.10 < z < 4.72$)



REGION OF INTEREST

- ▶ **Region of Interest (ROI)** - region containing the jet or a partition of the jet (e.g. node or lobe)
- ▶ Previous work tests whether or not a jet exists in a predefined ROI (McKeough et al. 2016, Stein et al. 2015)



REGION OF INTEREST


- ▶ Ability to detect jet is sensitive to fit of ROI
- ▶ Issues with previous methods:
 - ▶ Region is defined using radio imaging
 - ▶ Not always available
 - ▶ Not always aligned with X-ray imaging
 - ▶ Region definition relies on human interaction
 - ▶ Inefficient and source of potential error

GOAL

GOAL

Define a boundary around the ROI of an irregularly shaped, diffuse source.

Give a measure of uncertainty.




**Pre-Process
Image**



**Pixel
Assignments**



**Boundary of
ROI**



**Pre-Process
Image**



**Pixel
Assignments**

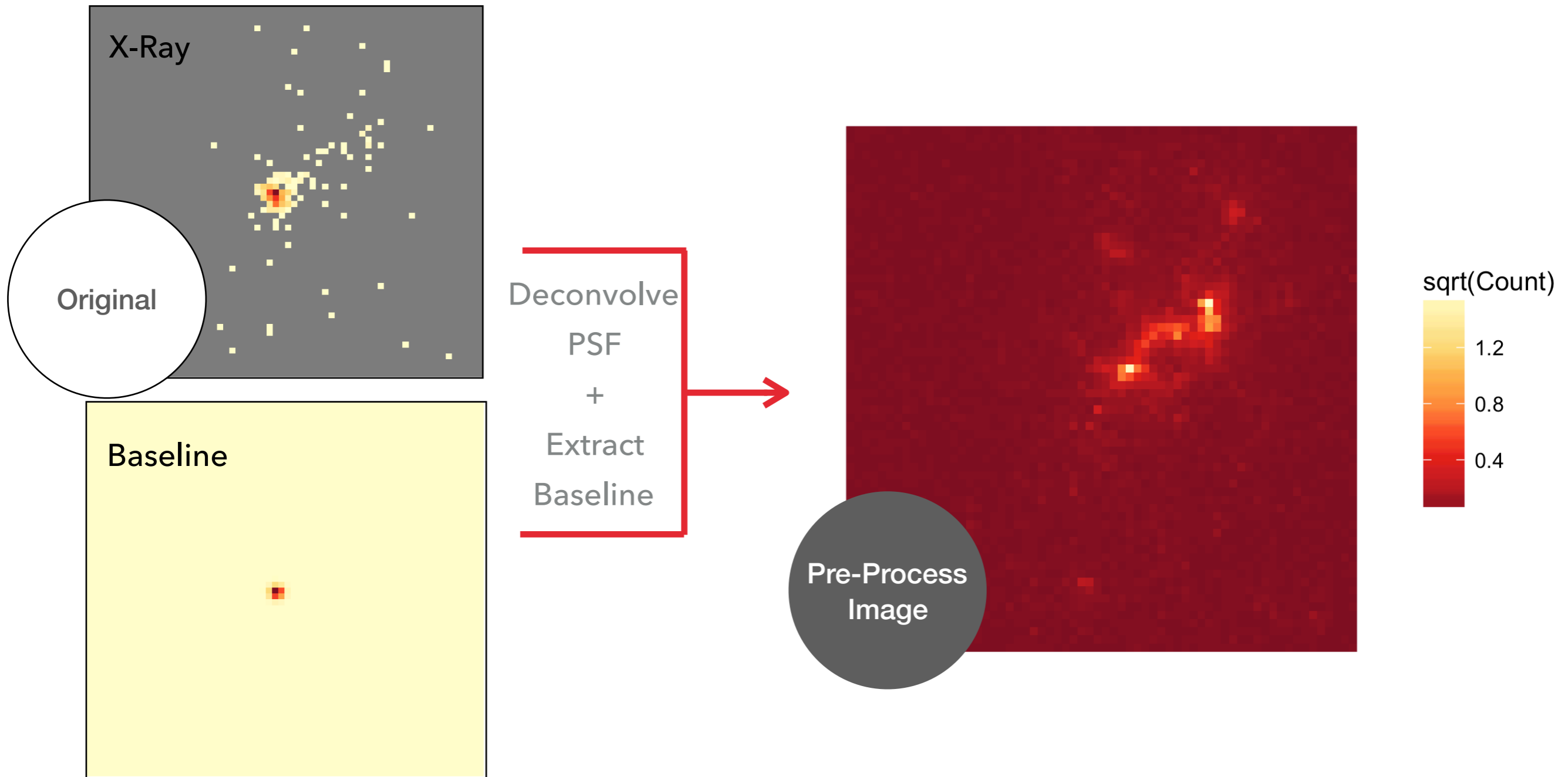


**Boundary of
ROI**

LOW COUNT IMAGE RECONSTRUCTION AND ANALYSIS (LIRA)

- ▶ Esch et al (2004), Connors & van Dyk (2007)
- ▶ Multi-scale Bayesian method
 - ▶ Intensity in “splits” of the image rather than individual pixels
- ▶ Removes quasar & deconvolve Point Spread Function (PSF)
- ▶ Creates posterior draws for residual pixels as a series of images that capture the emission that is present in excess of the quasar (i.e. the jet)

LOW COUNT IMAGE RECONSTRUCTION AND ANALYSIS (LIRA)



ROADMAP



Pre-Process
Image



Pixel
Assignments



Boundary of
ROI

LIKELIHOOD

$$\sqrt{\tilde{\lambda}_{ij}} | Z, \tau_{\pm}, \sigma_{\pm}^2 \sim \text{Normal}(\tau_{-}, \sigma_{-}^2) \mathbb{I}_{z_{ij}=-1} + \text{Normal}(\tau_{+}, \sigma_{+}^2) \mathbb{I}_{z_{ij}=+1}$$

- ▶ We are given observation Y from which we draw the LIRA output:

$$\tilde{\lambda} | Y$$

- ▶ We want to assign each pixel to either the background (-1) or the ROI (+1):

$$z_{ij} = \{-1, +1\}$$

- ▶ Each pixel assignment will have its own average intensity:

$$\tau_{-}, \tau_{+}$$

- ▶ We suspect the variance of the source will be greater than the background:

$$\sigma_{-}^2, \sigma_{+}^2$$

2D ISING PRIOR

$$p(z|\beta) = \frac{\exp(\beta \sum_{ij, i'j' \in |ij-i'j'|=1} z_{ij} z_{i'j'})}{\tilde{Z}(\beta)}$$

▶ Inverse temperature:

 β

▶ Higher β induces more correlation between pixels

▶ Partition function:

 $\tilde{Z}(\beta)$

▶ Estimated via Beale (1996) assuming periodic structure

▶ Commonly used in modeling ferromagnetism.

▶ Induces spatial correlation; adjacent pixels will tend to have the same assignment.

REMINDER: MODEL SETUP

► Likelihood:

$$\sqrt{\tilde{\lambda}_{ij}} | Z, \tau_{\pm}, \sigma_{\pm}^2 \sim \text{Normal}(\tau_{-}, \sigma_{-}^2) \mathbb{I}_{z_{ij}=-1} + \text{Normal}(\tau_{+}, \sigma_{+}^2) \mathbb{I}_{z_{ij}=+1}$$

► Prior:

$$p(z|\beta) = \frac{\exp(\beta \sum_{ij, i'j' \in |ij-i'j'|=1} z_{ij} z_{i'j'})}{\tilde{Z}(\beta)}$$

STEP 1 – LIKELIHOOD PARAMETERS

▶ Draw from posterior directly:

▶ Priors:

$$\tau_{\pm} \sim \text{Normal}(\mu_0, \sigma_{\pm}^2)$$

$$\sigma_{\pm}^2 \sim \text{Inv-}\chi^2(\nu_0, \omega_0^2)$$

STEP 2 – TEMPERATURE PARAMETER

▶ Drawn through Metropolis Hastings

▶ Prior:

$$\beta \sim \text{Gamma}(a_{\beta}, b_{\beta})$$

STEP 3- ASSIGNMENTS

- ▶ A well established way to draw the spin state given a specific temperature is **Swendsen & Wang (1987)**.
- ▶ The S-W method takes a spin system $z|\beta$ and induces a bigger system that contains the original N spin variables and M additional bond variables, denoted by d .

- ▶ Define joint distribution that couples spins to bonds:

$$p(z, d|\tilde{\lambda}, \tau_{\pm}, \sigma_{\pm}^2, \beta) \propto \prod_{m=1}^M g_m(z_m, d_m|\beta) \prod_{ij} f(\tilde{\lambda}_{ij}|z, \tau_{\pm}, \sigma_{\pm}^2)$$

- ▶ Marginal distribution of z is equal to our posterior.

$$\sum_d p(z, d|\tilde{\lambda}, \tau_{\pm}, \sigma_{\pm}^2, \beta) = p(z|\tilde{\lambda}, \tau_{\pm}, \sigma_{\pm}^2, \beta)$$

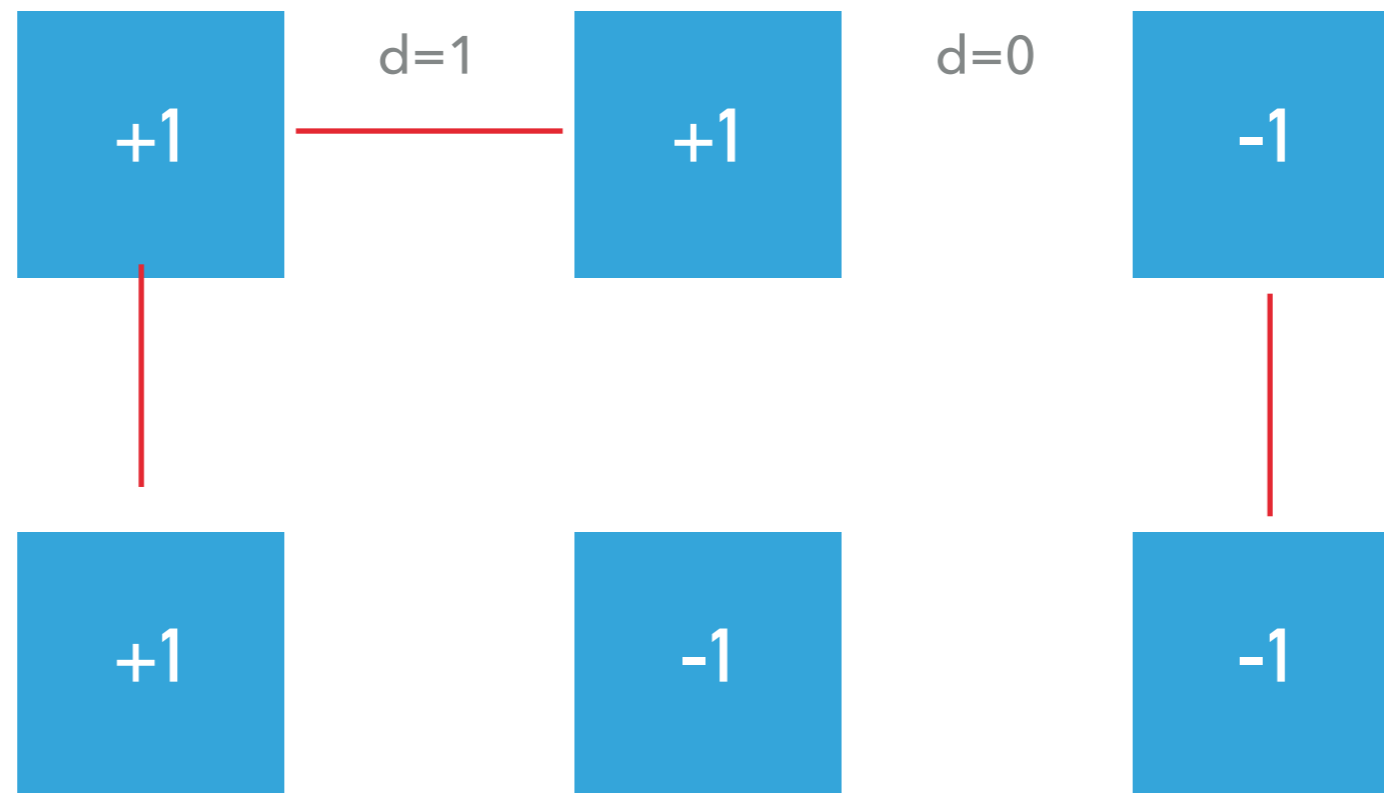
- ▶ Conditional distributions are easy to sample from.

$$p(z|d, \beta-) \quad p(d|z, \beta-)$$

COUPLING SPINS TO BONDS

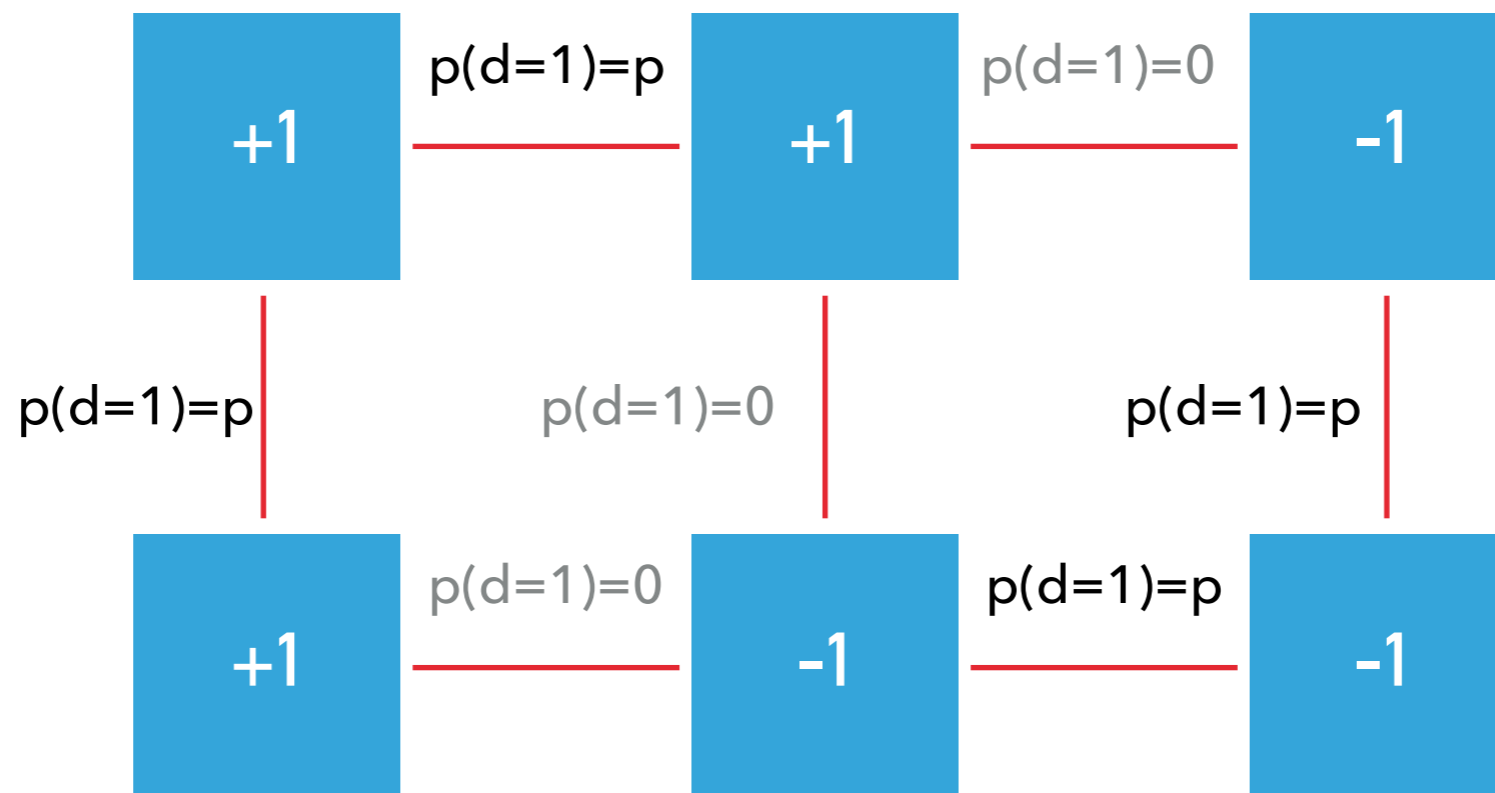
- ▶ Bonds can be disconnected (0) or connected (1).

$$d = \{0, 1\}$$



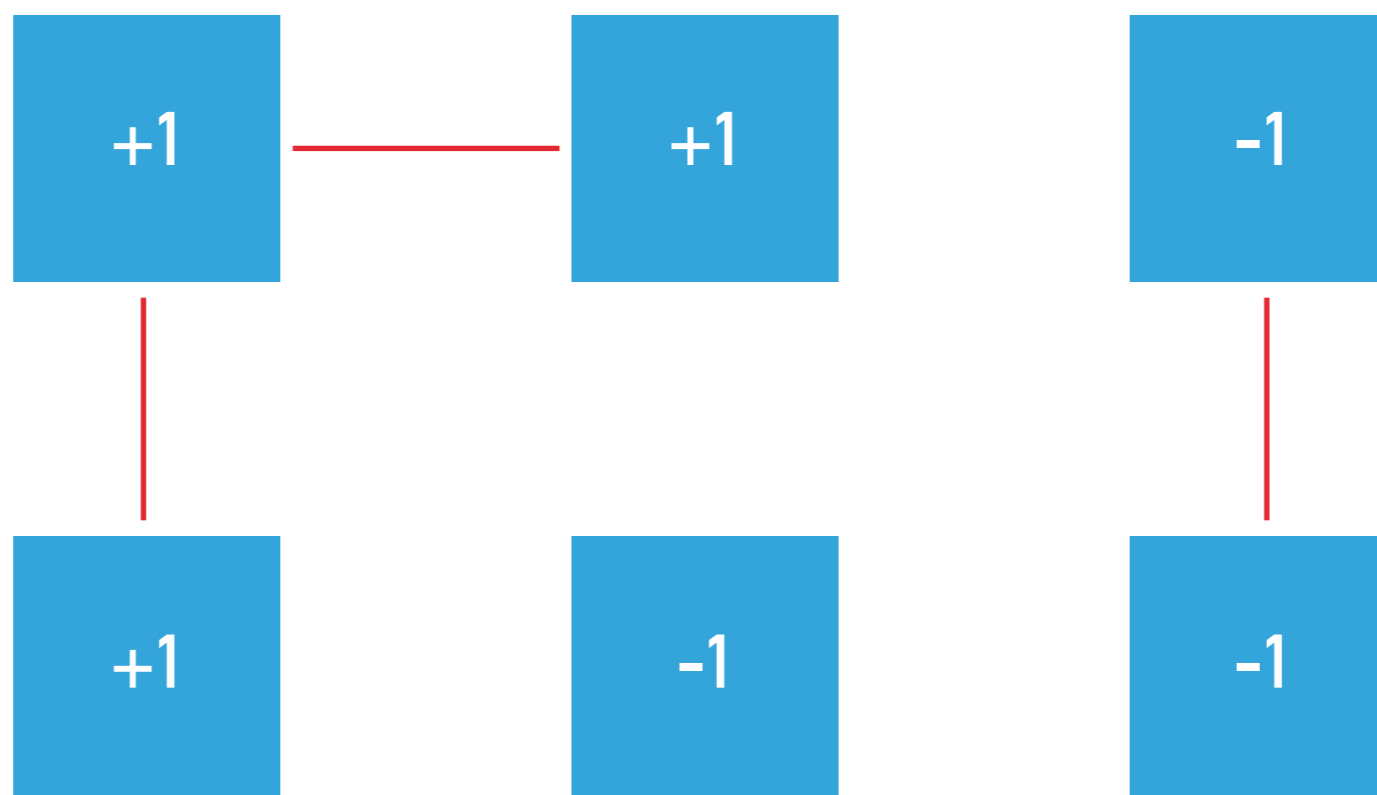
SAMPLING

- ▶ Sample from $p(d|z, \beta)$
 - ▶ If two spins connected to bond are equal, set the bond d_m equal to 1 with probability $p=1-\exp(-2\beta)$, and 0 otherwise.



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SAMPLING

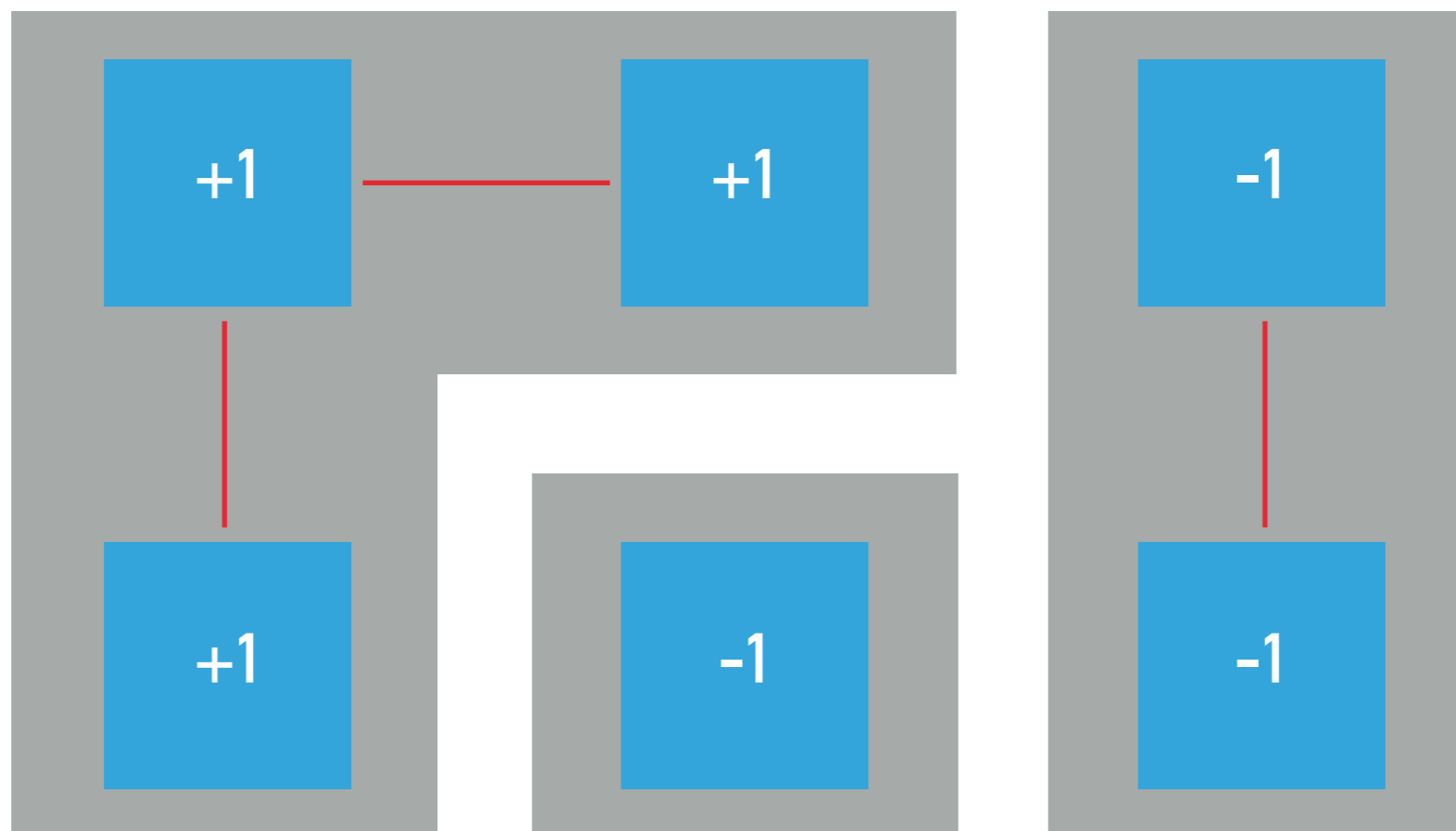
- ▶ Sample from $p(z|d, \beta)$
 - ▶ Bonds connect spins into C cluster.
 - ▶ **Cluster** - all pixels that are connected by a bond $d_m=1$
 - ▶ Each cluster will take spin $+1$ with probability p_+
 -1 with probability $p_- = 1 - p_+$

$$p_{\pm} \propto \prod_{ij \in C} f(\tilde{\lambda}_{ij} | z_{ij} = \pm 1, \tau_{\pm}, \sigma_{\pm}^2)$$

SAMPLING

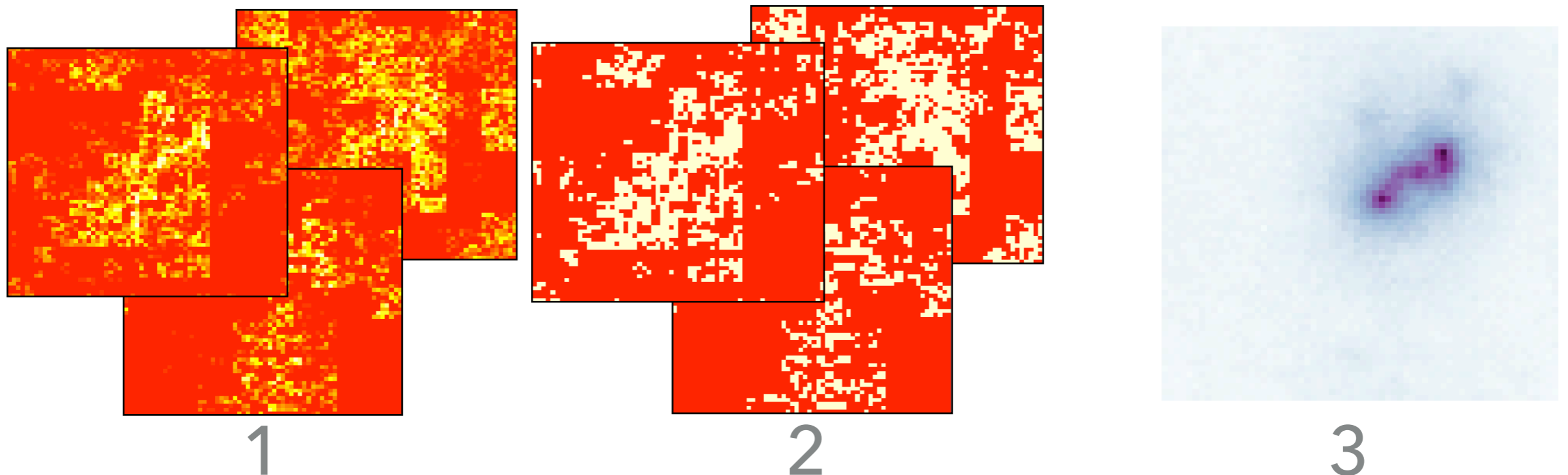
- ▶ Sample from $p(z|d, \beta)$

$$p(z=+1) = p_+$$



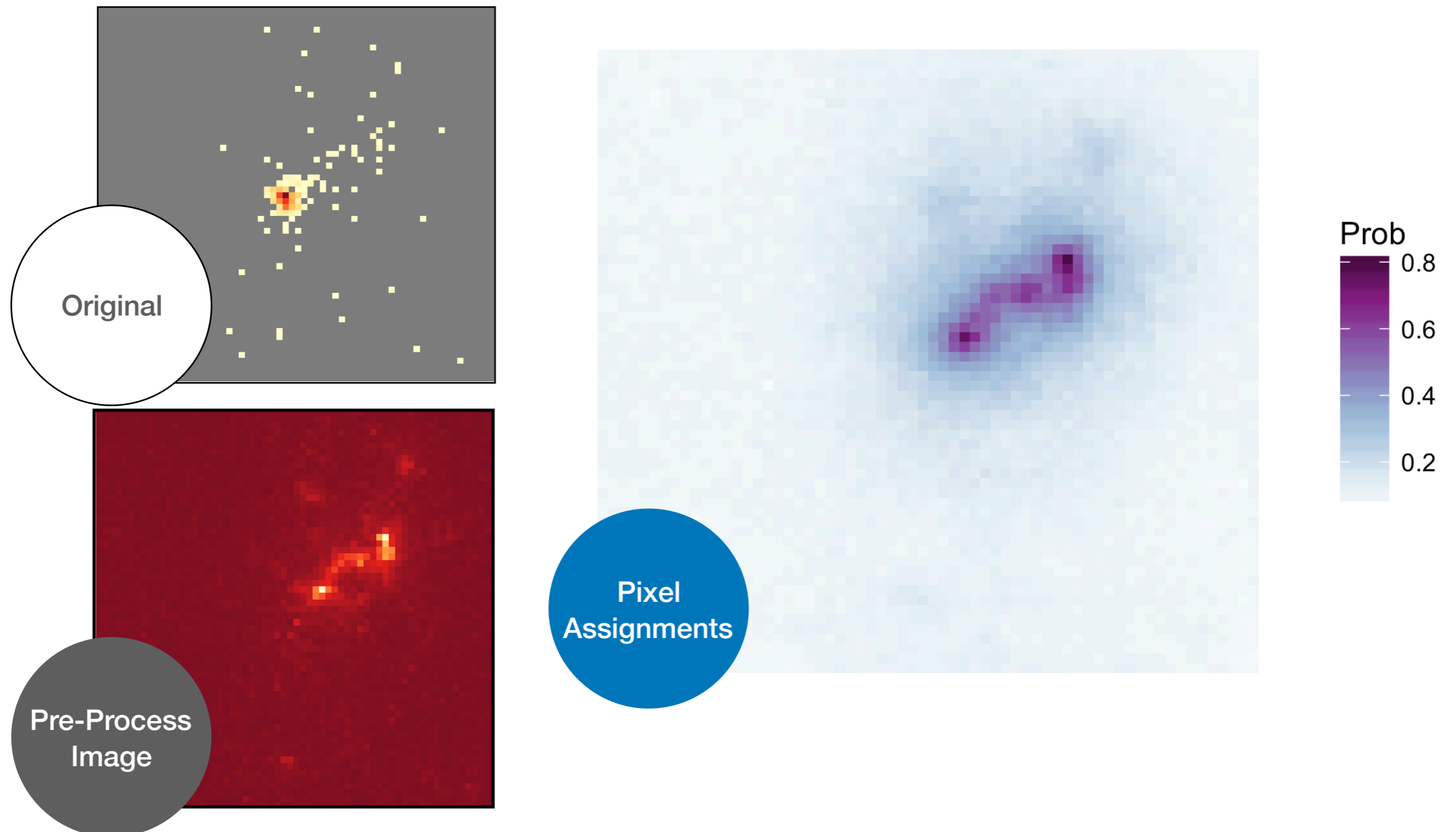
ISING-LIRA ITERATIONS

1. Get many posterior draws from LIRA
2. Apply Ising step to each LIRA draw
3. Average across LIRA-Ising iterations to get probability map.



PROBABILITY MAP

- ▶ Probability each pixel is a member of the ROI:



ROADMAP



Pre-Process
Image



Pixel
Assignments



Boundary of
ROI

OPTIMAL ROI

- ▶ Maximize posterior predictive:

$$P(Z|Y) = \int P(Z, \theta, \lambda|Y) d\theta d\lambda$$

OPTIMAL ROI

- ▶ Maximize posterior predictive:

$$P(Z|Y) = \int P(Z, \theta, \lambda|Y) d\theta d\lambda$$

- ▶ Ideally we could approximate this as:

$$\hat{P}(Z|Y) = \frac{1}{N} \sum_{k=1}^N P(Z|\theta^{(k)}, \lambda^{(k)})$$

OPTIMAL ROI

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$$P(Z|Y) = \int P(Z, \theta, \lambda|Y) d\theta d\lambda$$

- ▶ Ideally we could approximate this as:

$$\hat{P}(Z|Y) = \frac{1}{N} \sum_{k=1}^N P(Z|\theta^{(k)}, \lambda^{(k)})$$

... but this is very difficult.

MAXIMIZE POSTERIOR RATIO

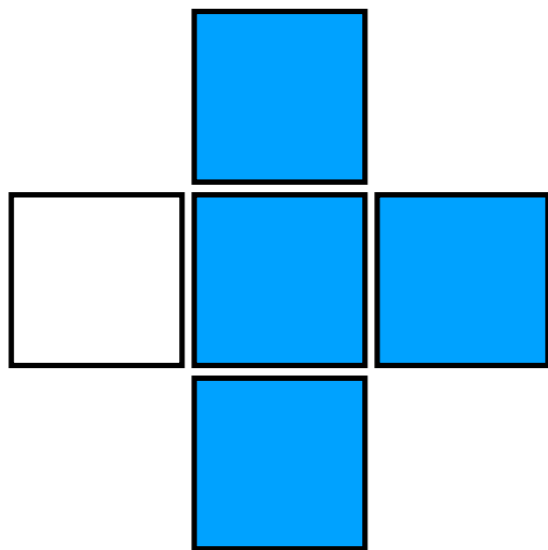
- ▶ Compare two different Z states:

$$\begin{aligned}\frac{\hat{P}(Z_1|Y)}{\hat{P}(Z_2|Y)} &= \frac{\sum_{k=1}^N \exp(\log P_k(Z_1))}{\sum_{k=1}^N \exp(\log P_k(Z_2))} \\ &= \sum_{k=1}^N w_k \exp\left(\log \frac{P_k(Z_1)}{P_k(Z_2)}\right)\end{aligned}$$

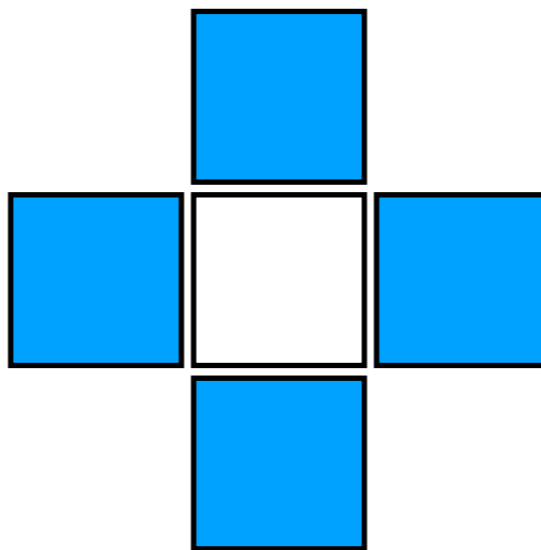
OPTIMIZATION SPACE

- ▶ Neighborhood statistic:

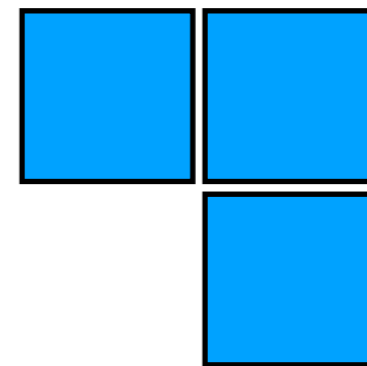
$$N_{ij} = \frac{\sum_{i'j' \in |ij - i'j'|=1} z_{ij} z_{i'j'}}{\sum_{i'j' \in |ij - i'j'|=1} |ij - i'j'|}$$



$$N_{ij} = 0.75$$



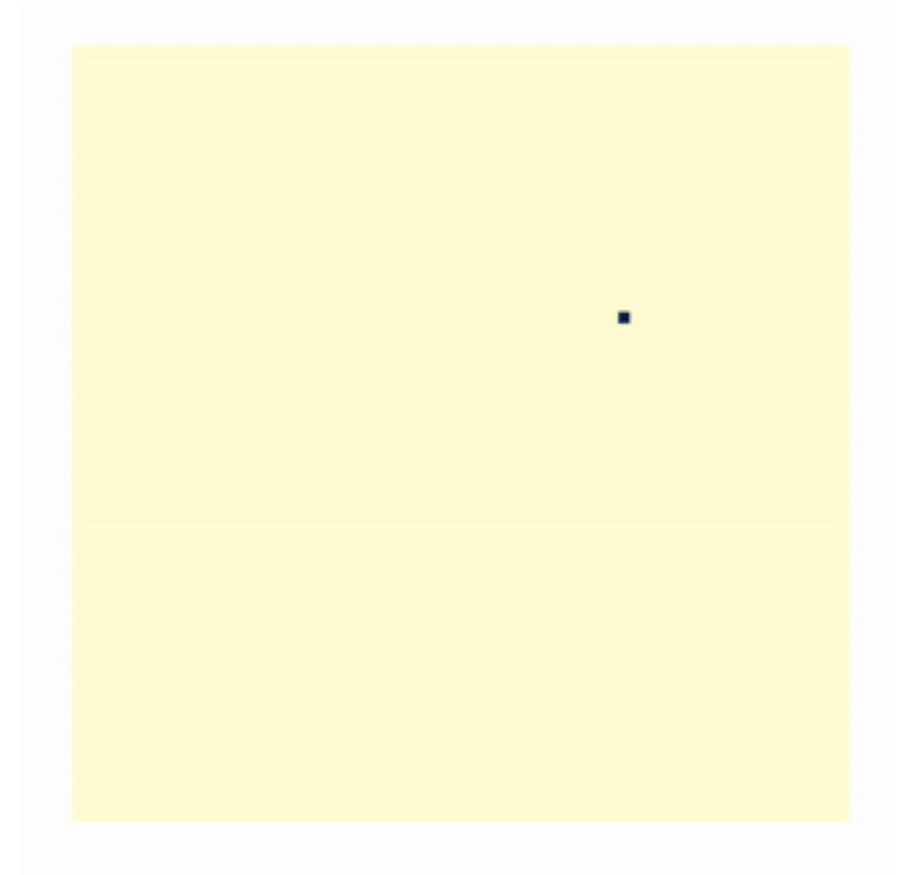
$$N_{ij} = 0$$



$$N_{ij} = 1$$

OPTIMIZATION SPACE

- ▶ Average N_{ij} across all posterior draws
- ▶ Rank N_{ij} from highest to lowest
- ▶ Build space to optimize over:
 - ▶ For the zip with the highest corresponding N_{ij} , set to 1 and the remainder to -1
 - ▶ Repeat including the next highest N_{ij} until all pixels are 1



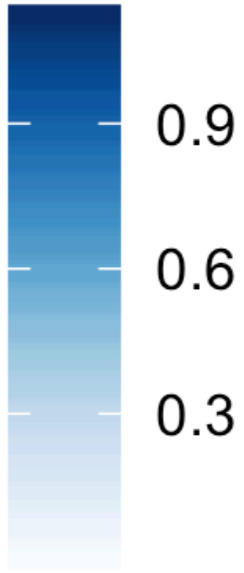
NOTES

- ▶ Maximize across all Z created using the neighborhood statistic and all Z drawn from the posterior
- ▶ We will always compare the new Z with the Z at the current maximum
- ▶ To build a confidence interval take more posterior iterations and repeat the process (TBD)

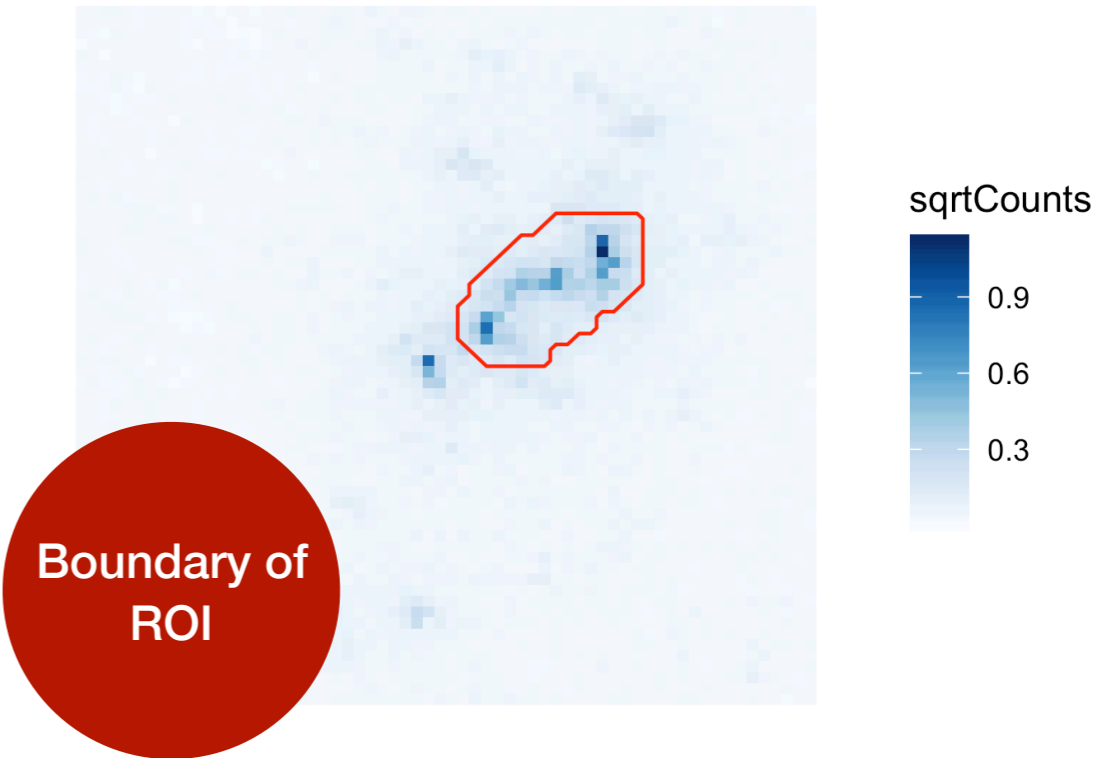
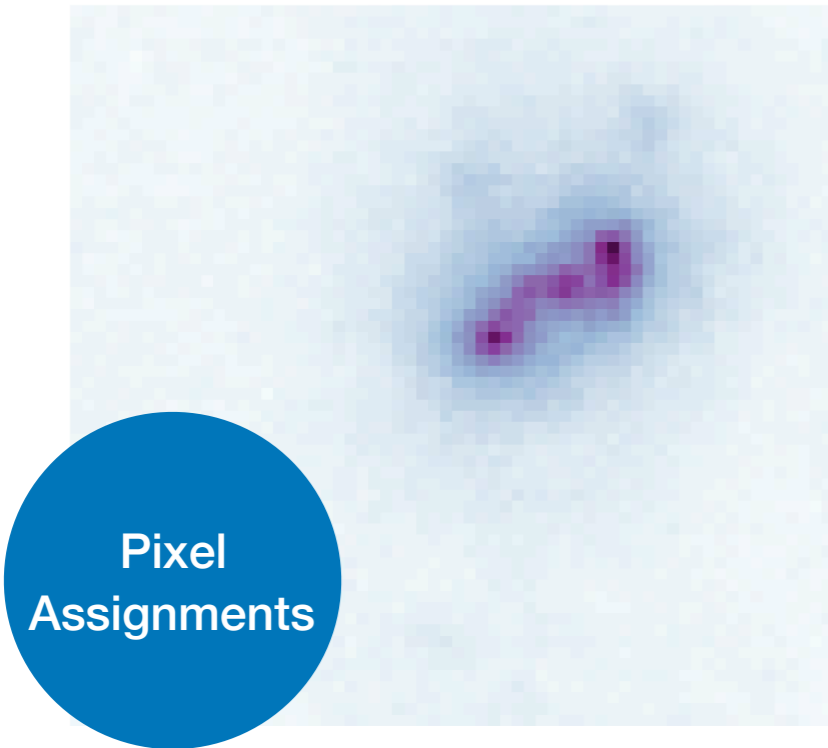
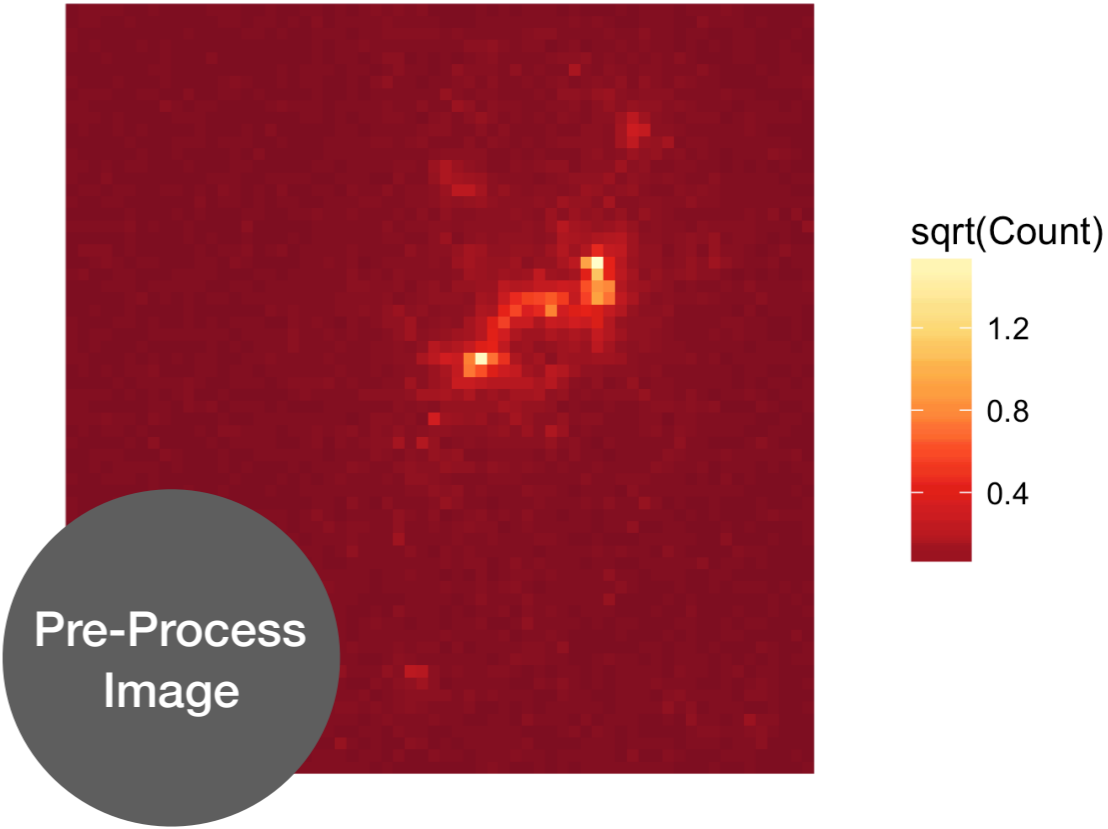
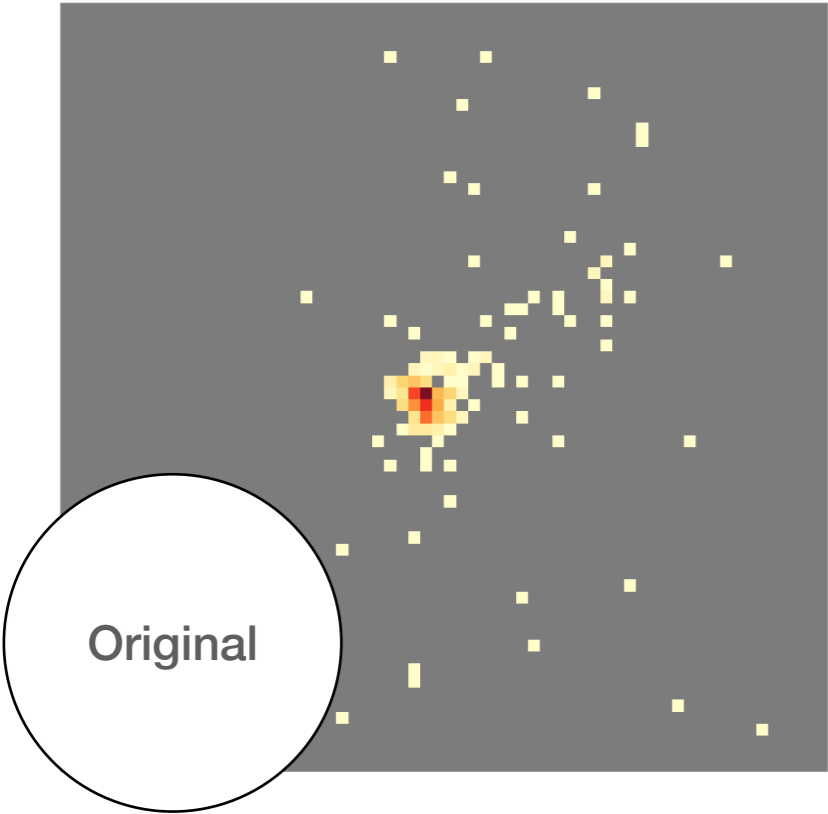
BOUNDARY OF ROI




sqrtCounts



RESULTS



Future Work



Pre-Process
Image

Pixel
Assignments

Boundary of
ROI

ADJACENT PIXEL DEFINITION

- ▶ Could be modified to the 8 nearest pixels instead of 4.
- ▶ Modified to include pixels beyond just the adjacent pixels
- ▶ Correlation as a function of distance

POTTS MODEL

- ▶ Want to identify multiple partitions of the jet (e.g. nodes)
- ▶ Potts is a more generalized version of the Ising model allows for more than two spin assignments:

$$z_{ij} = \{0, 1, 2, 3, \dots\}$$


DIFFERENT LIKELIHOODS

- ▶ **Hurdle model** - Account for many of the background pixels in the LIRA output being zero.

CONCLUSION

- ▶ LIRA has been successful in analyzing low count images and extracting noisy structure.
 - ▶ No way to define a ROI
 - ▶ No correlation structure between pixels
- ▶ Utilized an Ising distribution and corresponding techniques to create a probabilistic ROI.

Model Compatibility



Pre-Process
Image

Pixel
Assignments

Boundary of
ROI

“IDEAL” MODIFICATION TO LIRA

- ▶ Current LIRA output:

$$P(\tilde{\lambda}|Y)$$

- ▶ The missing piece of LIRA is the pixel membership indicator:

$$z_{ij} = \{-1, +1\}$$

- ▶ An ideal joint model (denote using subscript \mathcal{J}) would infer λ_{ij} and z_{ij} simultaneously

$$P_{\mathcal{J}}(\tilde{\lambda}, z|Y) \propto f(Y|\tilde{\lambda}, z)\pi_{\mathcal{J}}(\tilde{\lambda}, z)$$

OUR APPROACH

- ▶ Two-step approach:

- ▶ LIRA "as is" (model S_1)

$$P_{S_1}(\tilde{\lambda}|Y) \propto f(Y|\tilde{\lambda})\pi_{S_1}(\tilde{\lambda})$$

- ▶ Ising (model S_2) conditional on ONE draw of from S_1

$$P_{S_2}(z|\tilde{\lambda}) \propto P_{S_2}(\tilde{\lambda}|z)\pi_{S_2}(z)$$

- ▶ Combine to get desired model:

$$\begin{aligned} P_S(\tilde{\lambda}, z|Y) &= P_{S_1}(\tilde{\lambda}|Y)P_{S_2}(z|\tilde{\lambda}) \\ &\propto f(Y|\tilde{\lambda})\pi_{S_1}(\tilde{\lambda})\frac{P_{S_2}(\tilde{\lambda}|z)\pi_{S_2}(z)}{P_{S_2}(\tilde{\lambda})} \end{aligned}$$

SUFFICIENT CONDITIONS

$$\begin{aligned} P_{\mathcal{J}}(\tilde{\lambda}, z|Y) \propto f(Y|\tilde{\lambda}, z)\pi_{\mathcal{J}}(\tilde{\lambda}, z) &\iff P_{\mathcal{S}}(\tilde{\lambda}, z|Y) = P_{\mathcal{S}_1}(\tilde{\lambda}|Y)P_{\mathcal{S}_2}(z|\tilde{\lambda}) \\ &\propto f(Y|\tilde{\lambda})\pi_{\mathcal{S}_1}(\tilde{\lambda})\frac{P_{\mathcal{S}_2}(\tilde{\lambda}|z)\pi_{\mathcal{S}_2}(z)}{P_{\mathcal{S}_2}(\tilde{\lambda})} \end{aligned}$$

- ▶ Assignment information does not effect distribution of photon counts:

$$f(Y|\tilde{\lambda}) = f(Y|\tilde{\lambda}, z)$$

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 &\propto f(Y|\tilde{\lambda})\pi_{\mathcal{S}_1}(\tilde{\lambda})\frac{P_{\mathcal{S}_2}(\tilde{\lambda}|z)\pi_{\mathcal{S}_2}(z)}{P_{\mathcal{S}_2}(\tilde{\lambda})}
 \end{aligned}$$

- ▶ Assignment information does not effect distribution of photon counts:

$$f(Y|\tilde{\lambda}) = f(Y|\tilde{\lambda}, z)$$

- ▶ LIRA prior on photon counts is compatible with Ising model prior on assignments:

$$\pi_{\mathcal{S}_1}(\tilde{\lambda}) = \int \pi_{\mathcal{J}}(\tilde{\lambda}, z)dz = \int P_{\mathcal{S}_2}(\tilde{\lambda}|z)\pi_{\mathcal{S}_2}(z)dz$$

HOW FAR OFF ARE WE?

$$P_{\mathcal{J}}(\tilde{\lambda}, z|Y) \propto f(Y|\tilde{\lambda}, z)\pi_{\mathcal{J}}(\tilde{\lambda}, z) \quad P_{\mathcal{S}}(\tilde{\lambda}, z|Y) = P_{\mathcal{S}_1}(\tilde{\lambda}|Y)P_{\mathcal{S}_2}(z|\tilde{\lambda})$$
$$\propto f(Y|\tilde{\lambda})\pi_{\mathcal{S}_1}(\tilde{\lambda})\frac{P_{\mathcal{S}_2}(\tilde{\lambda}|z)\pi_{\mathcal{S}_2}(z)}{P_{\mathcal{S}_2}(\tilde{\lambda})}$$

► Inference for λ is equivalent:

$$P_{\mathcal{J}}(\lambda|Y) \propto f(Y|\lambda) \int \pi_{\mathcal{J}}(\lambda, z) dz = f(Y|\lambda)\pi_{\mathcal{S}_1}(\lambda) \propto P_{\mathcal{S}}(\lambda|Y) dz$$

HOW FAR OFF ARE WE?

$$\begin{aligned}
 P_{\mathcal{J}}(\tilde{\lambda}, z|Y) &\propto f(Y|\tilde{\lambda}, z)\pi_{\mathcal{J}}(\tilde{\lambda}, z) & P_{\mathcal{S}}(\tilde{\lambda}, z|Y) &= P_{\mathcal{S}_1}(\tilde{\lambda}|Y)P_{\mathcal{S}_2}(z|\tilde{\lambda}) \\
 & & &\propto f(Y|\tilde{\lambda})\pi_{\mathcal{S}_1}(\tilde{\lambda})\frac{P_{\mathcal{S}_2}(\tilde{\lambda}|z)\pi_{\mathcal{S}_2}(z)}{P_{\mathcal{S}_2}(\tilde{\lambda})}
 \end{aligned}$$

- ▶ Inference for λ is equivalent:

$$P_{\mathcal{J}}(\lambda|Y) \propto f(Y|\lambda) \int \pi_{\mathcal{J}}(\lambda, z) dz = f(Y|\lambda)\pi_{\mathcal{S}_1}(\lambda) \propto P_{\mathcal{S}}(\lambda|Y)$$

- ▶ Posterior inference is bounded by the prior divergence (which can be calculated)

$$D_{KL}(P_{\mathcal{J}}(\lambda, z|Y), P_{\mathcal{S}}(\lambda, z|Y)) = \int P_{\mathcal{J}}(\lambda|Y) D_{KL}(P_{\mathcal{J}}(z|\lambda), P_{\mathcal{S}}(z|\lambda)) d\lambda$$

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LIRA

MULTI-SCALE IMAGE REPRESENTATION

- ▶ Stores total intensities and series of four way split proportions such that the product recovers original pixel intensities

- ▶ Pixel Intensity

$$\Lambda = \{\Lambda_i, I = 1 \dots N\}$$

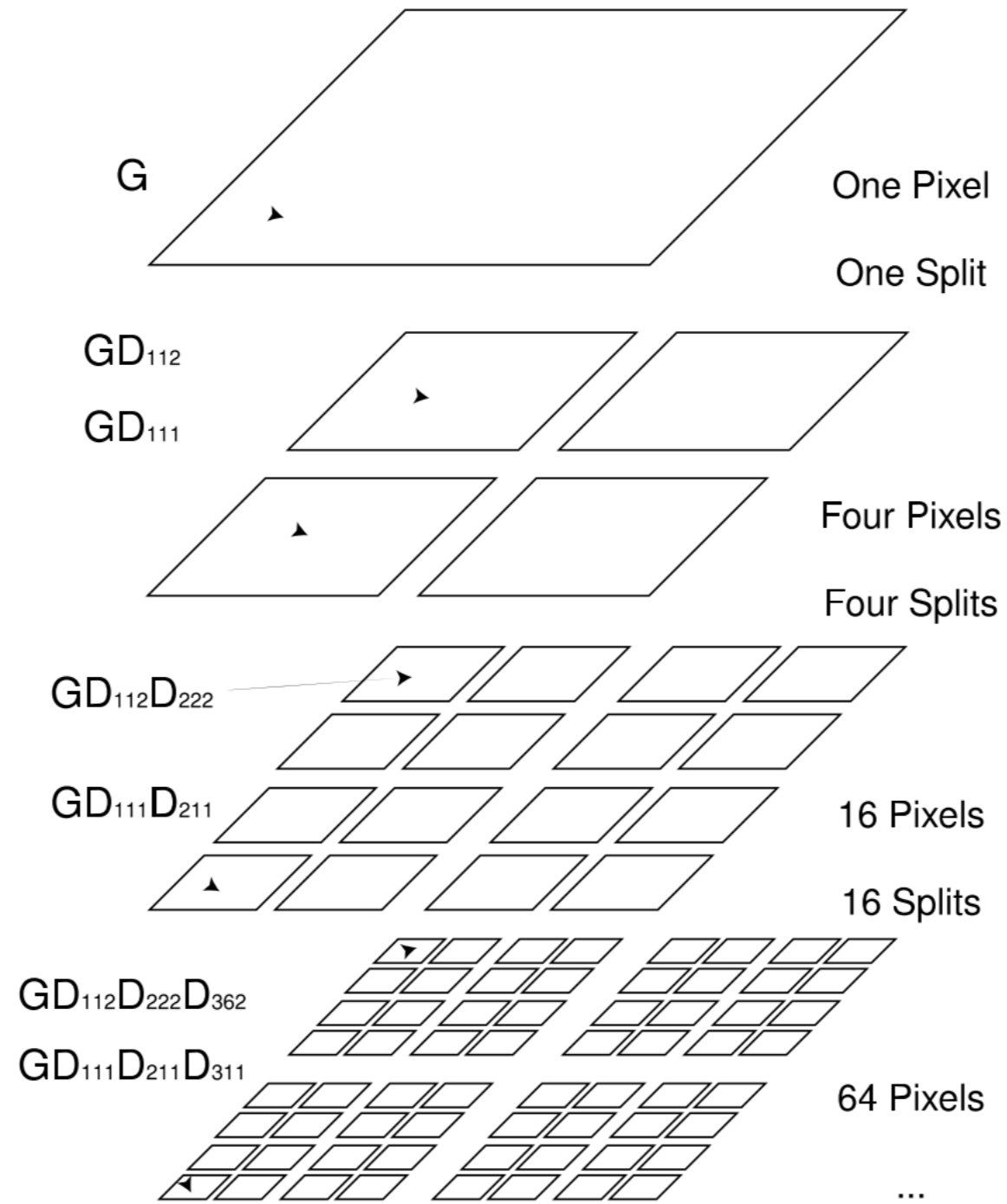
- ▶ Splits

$$D_{k, l_{k(i)}, m_{k(i)}}$$

- ▶ Split proportion at scale k corresponding to group i

$$\Lambda_i = G \prod_{k=1}^K D_{k, l_{k(i)}, m_{k(i)}}$$

MULTI-SCALE IMAGE REPRESENTATION



LIKELIHOOD

- ▶ Probability photon originating in pixel i , is observed in pixel j (*PSF*):

$$P_i = \{P_{ij}, j = 1, \dots, N\}$$

- ▶ Observed pixel counts:

$$Y = \{Y_i, i = 1, \dots, N\}$$

- ▶ Distribution of Y :

$$Y_j | \Lambda, \Lambda^B \underset{\sim}{\sim} \text{Poisson} \left[\left(\sum_{i \in \mathcal{I}} P_{ij} \Lambda_i \right) + \Lambda_j^B \right]$$

- ▶ Suppress background to obtain likelihood:

$$L(\Lambda, \Lambda^B | \mathbf{Y}) \equiv L(\Lambda | \mathbf{Y}) \propto \prod_{j \in \mathcal{I}} p(Y_j | \Lambda).$$

PRIOR

- ▶ Prior on total intensity:

$$G \sim \text{Gamma}(\gamma_0, \gamma_1)$$

- ▶ Prior on splits:

$$\mathbf{D}_{kl} \equiv \{D_{klm}, m = 1, \dots, 4\} \stackrel{d}{\sim} \text{Dirichlet}(\alpha_k, \alpha_k, \alpha_k, \alpha_k)$$
$$k = 1, \dots, K, \quad l = 1, \dots, 4^{k-1}$$

- ▶ Hyperprior favors smoother image:

$$p(\alpha_k) \propto \exp(-\delta \alpha^3 / 3)$$

CYCLE SPINNING

- ▶ Multiscale format produces checkerboard-like patterns
- ▶ Solution:
 - ▶ Shift center of image randomly before making splits
 - ▶ Splits wrap around edges of image to induce translation invariance

SWENDSEN-

WANG

COUPLING SPINS TO BONDS

- ▶ Factor coupling bonds and spins is:

$$g_m(z_m, d_m) = \begin{cases} & d_m = 0 & & d_m = 1 \\ z_{ij} = -1 & z_{i'j'} = -1 & z_{i'j'} = +1 & z_{i'j'} = -1 & z_{i'j'} = +1 \\ & e^{-\beta} & e^{-\beta} & e^{\beta} - e^{-\beta} & 0 \\ z_{ij} = +1 & e^{-\beta} & e^{-\beta} & 0 & e^{\beta} - e^{-\beta} \end{cases}$$

- ▶ Rescale by constant factor: $p = 1 - e^{-2\beta}$

$$\tilde{g}_m(z_m, d_m) = \begin{cases} & d_m = 0 & & d_m = 1 \\ z_{ij} = -1 & z_{i'j'} = -1 & z_{i'j'} = +1 & z_{i'j'} = -1 & z_{i'j'} = +1 \\ & 1 - p & 1 - p & p & 0 \\ z_{ij} = +1 & 1 - p & 1 - p & 0 & p \end{cases}$$